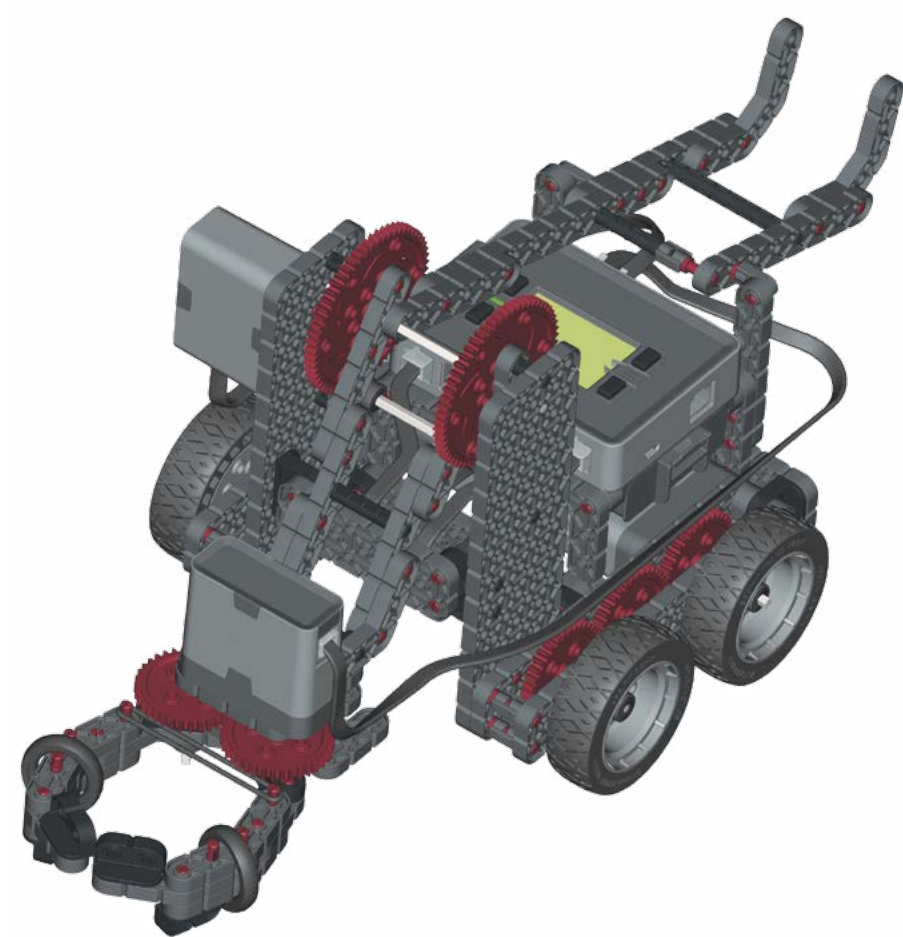
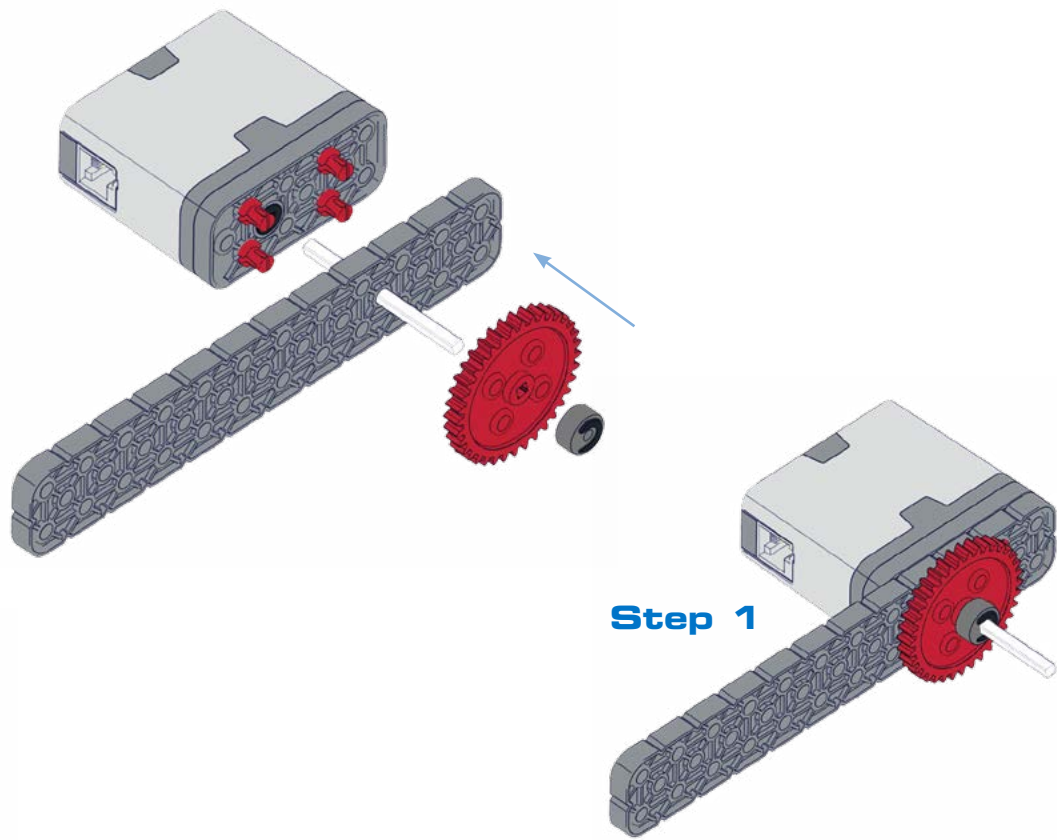
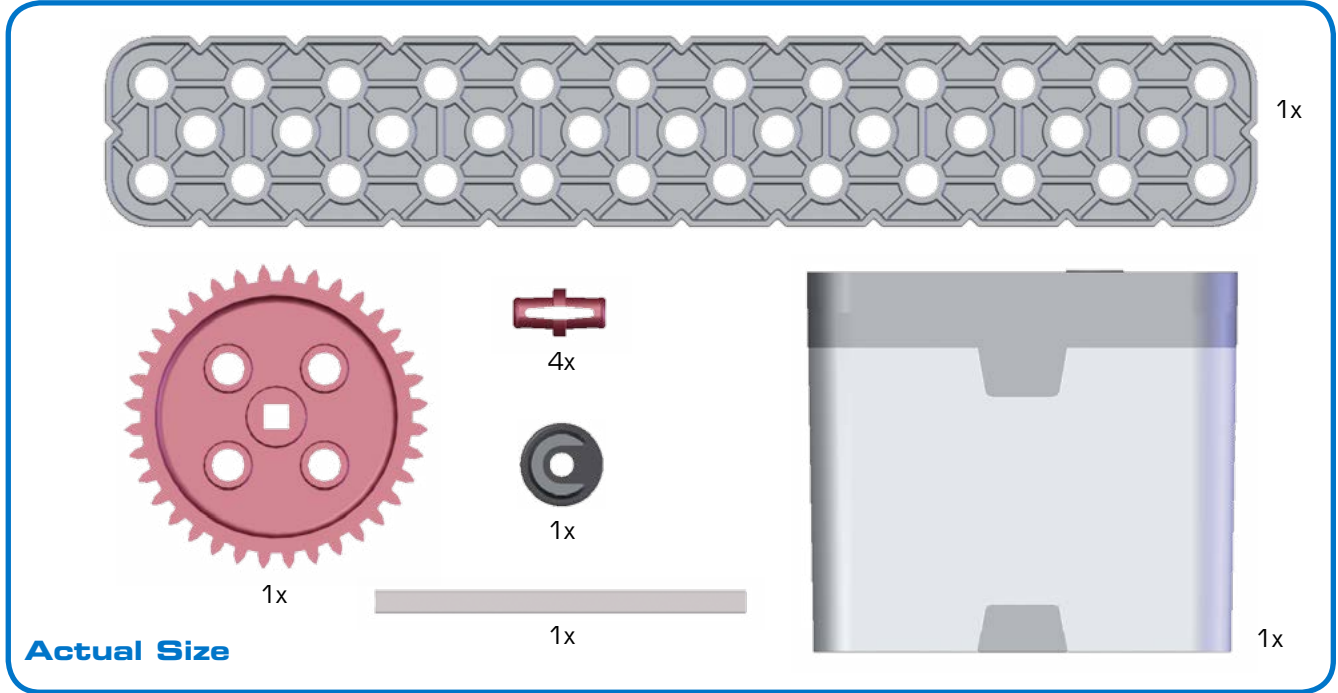


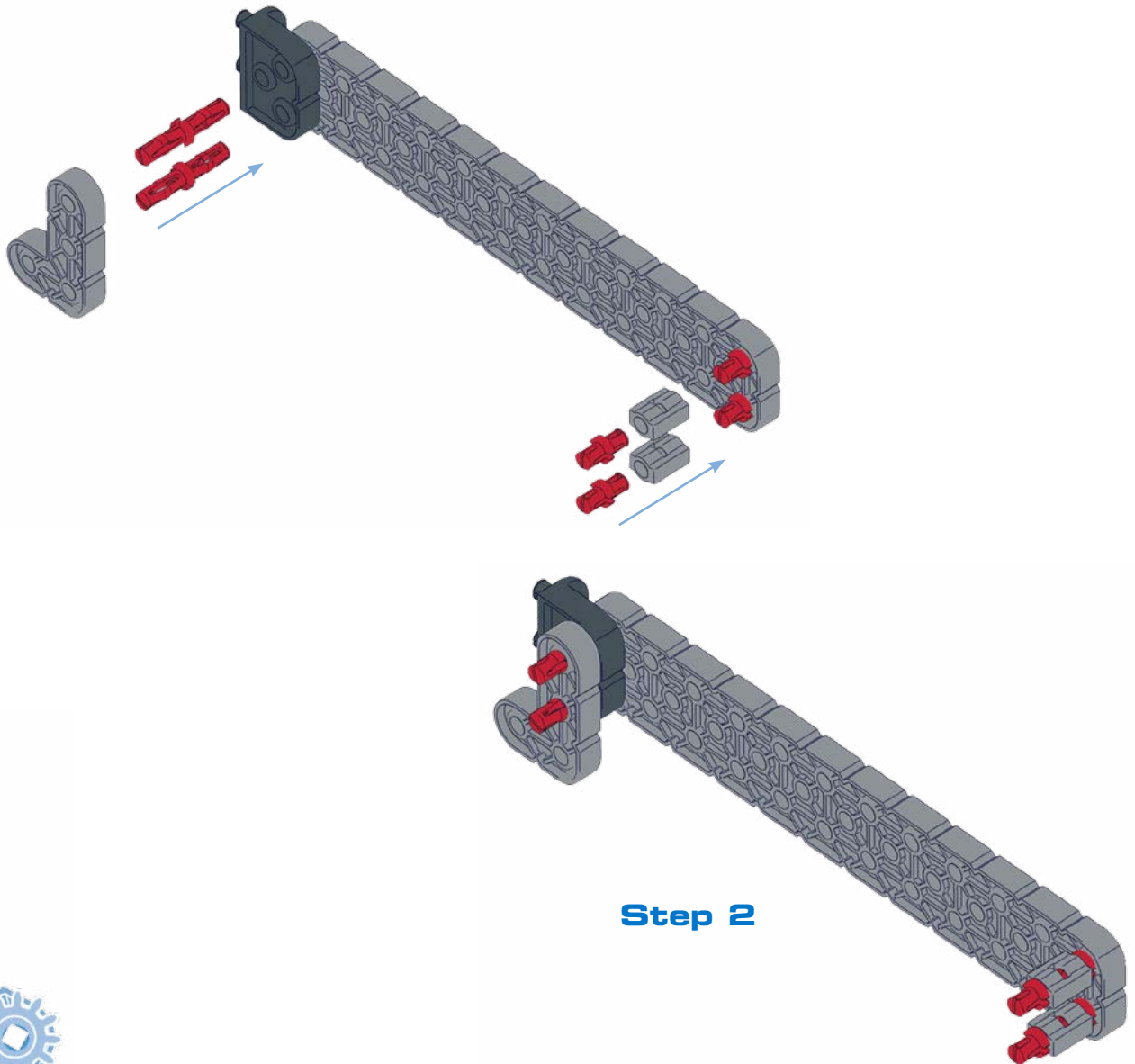
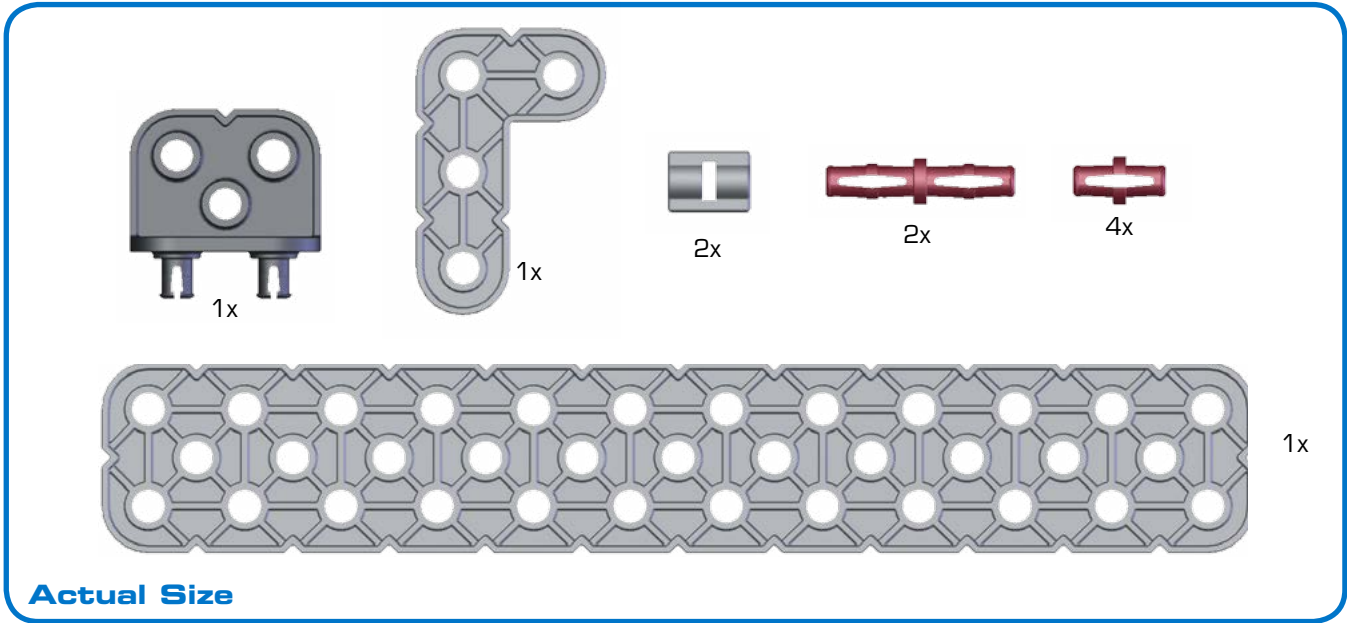


Clawbot Assembly Instructions

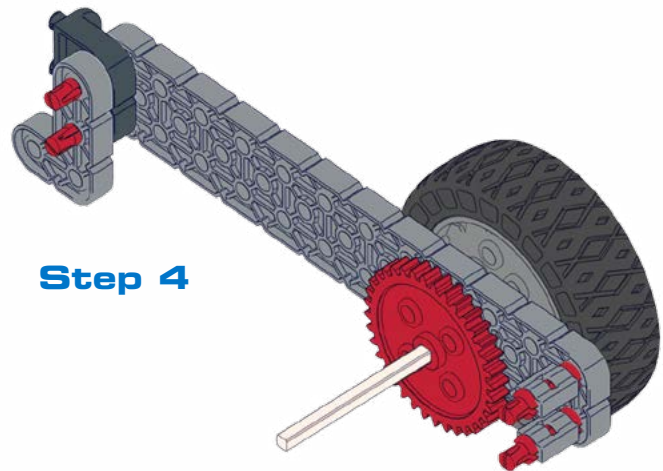
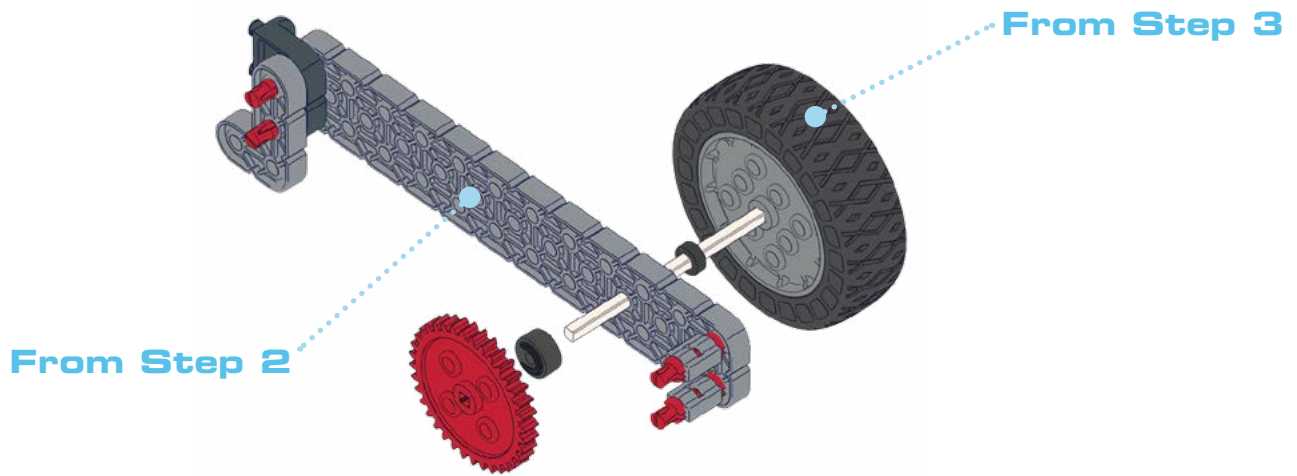
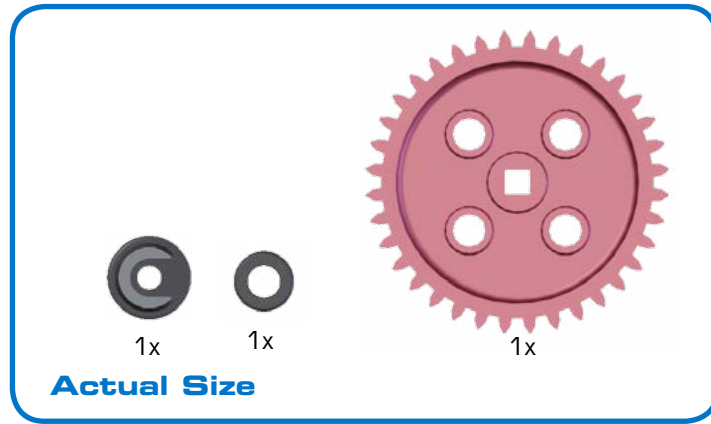


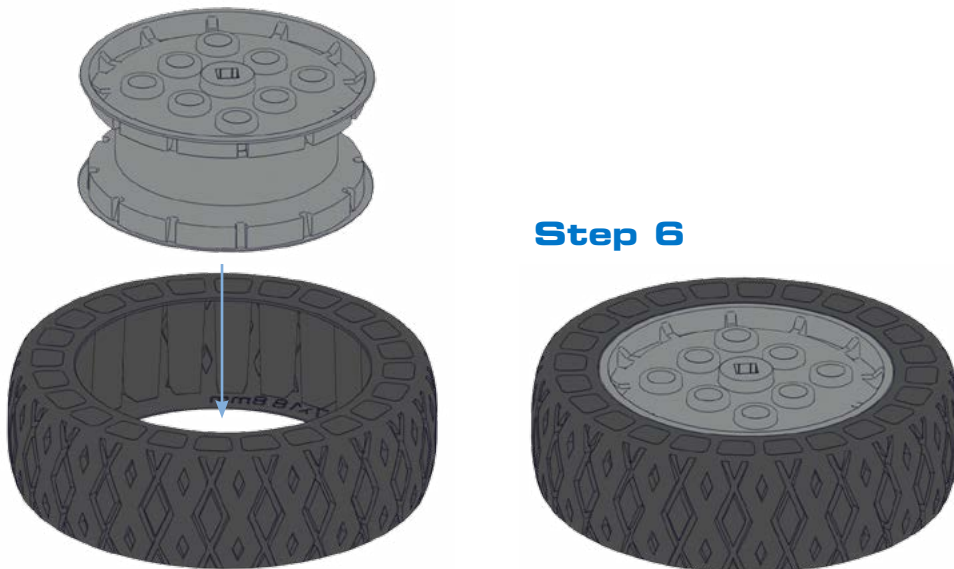
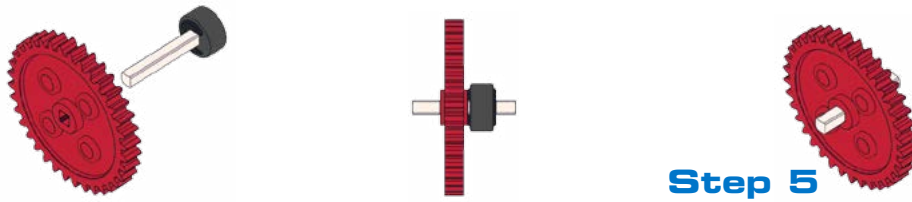
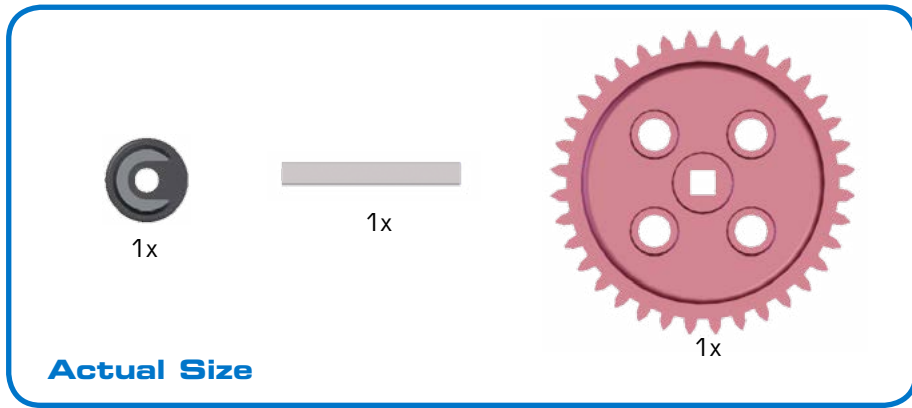
Part 1 Base

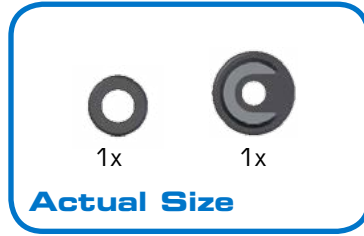




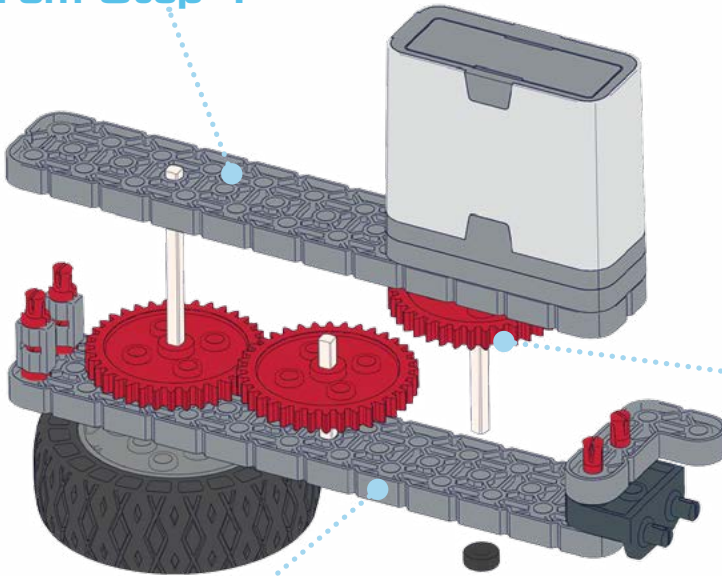




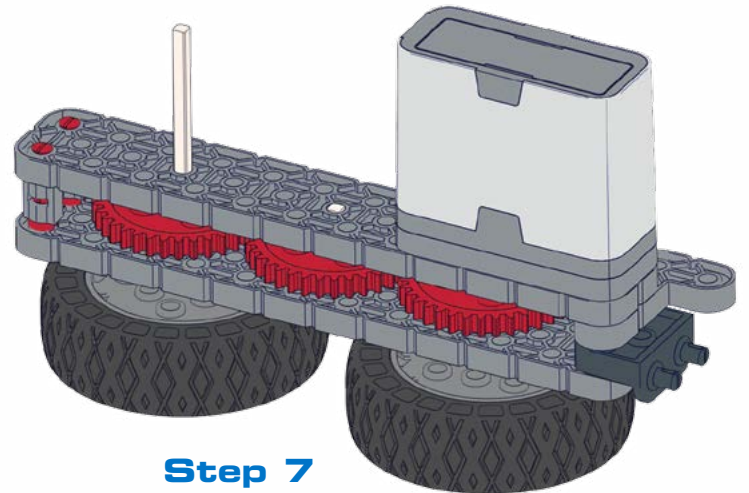


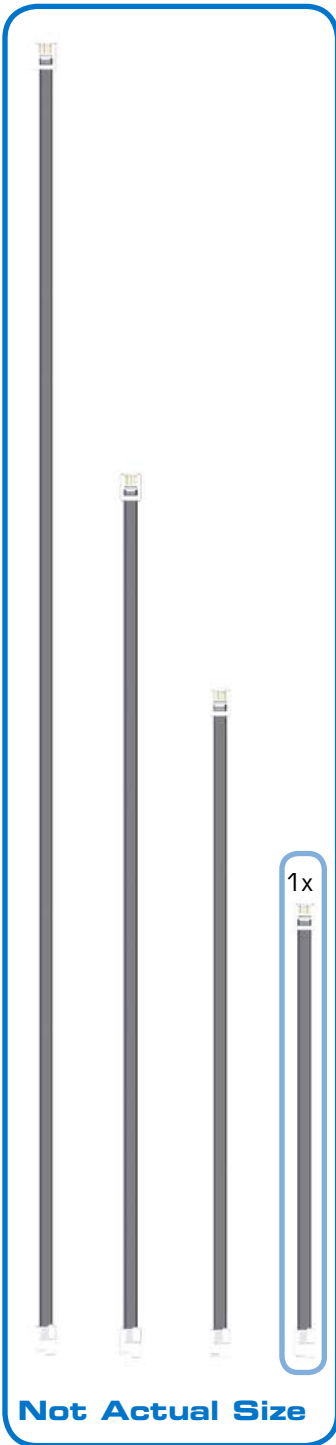


From Step 1

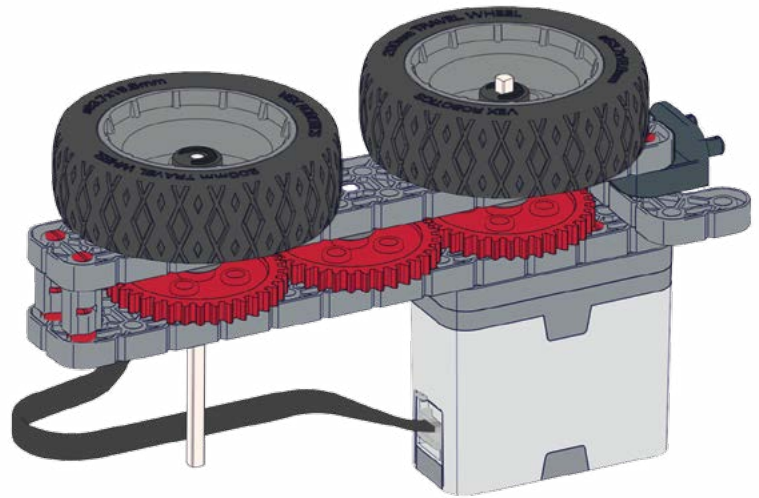
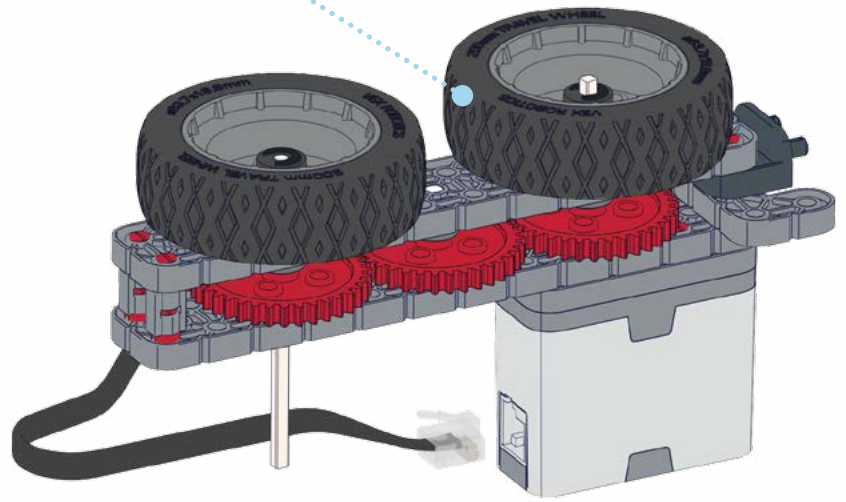


From Step 4



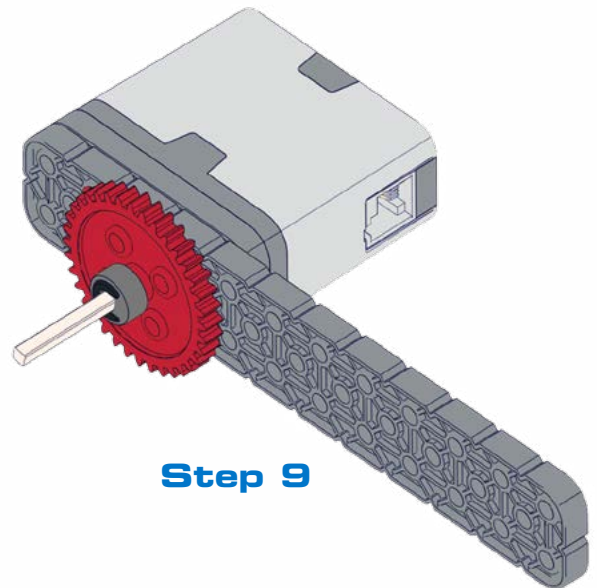
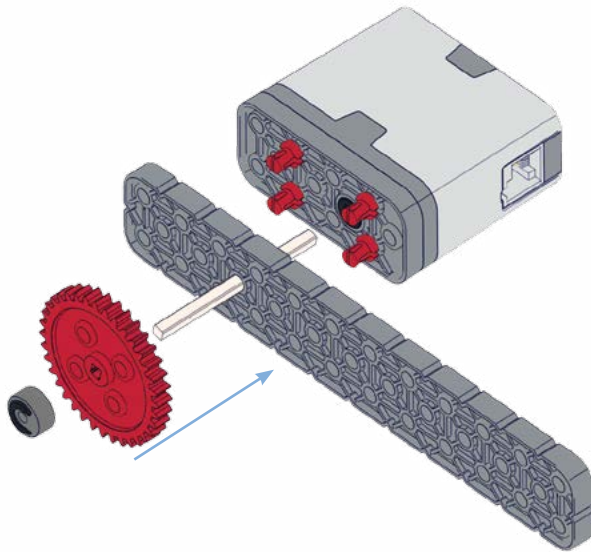
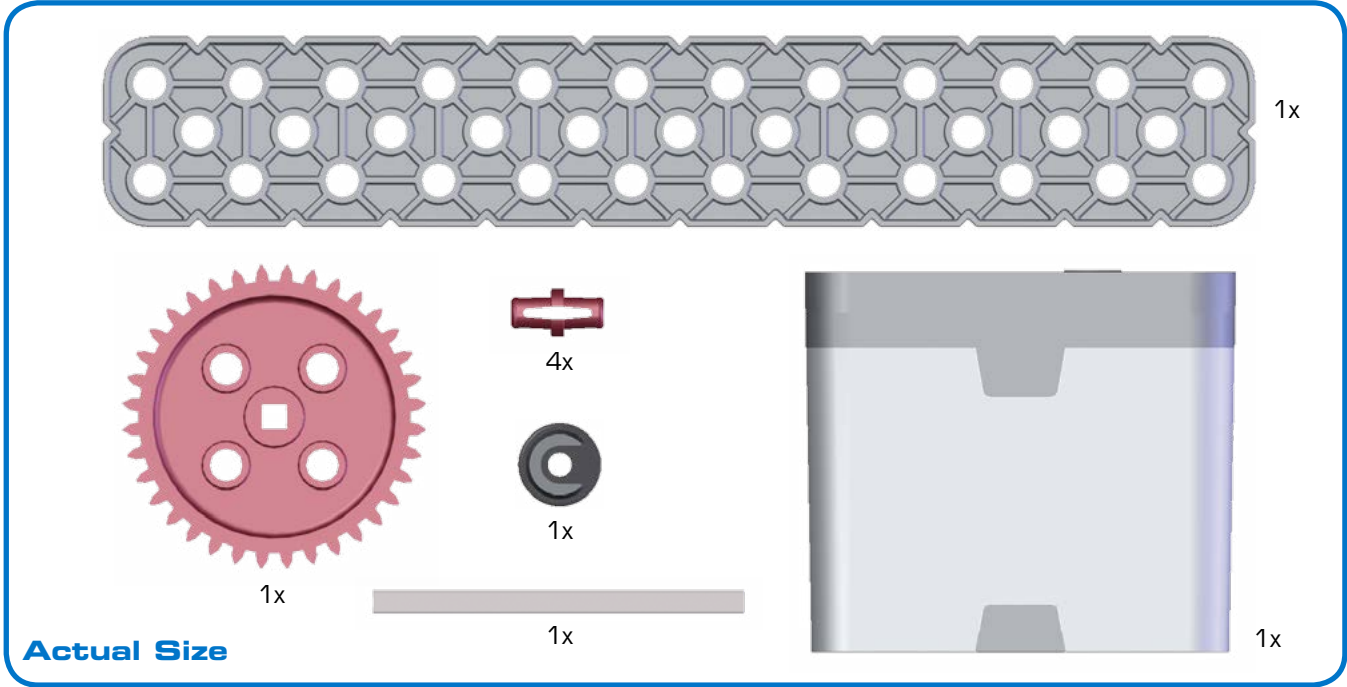


From Step 7

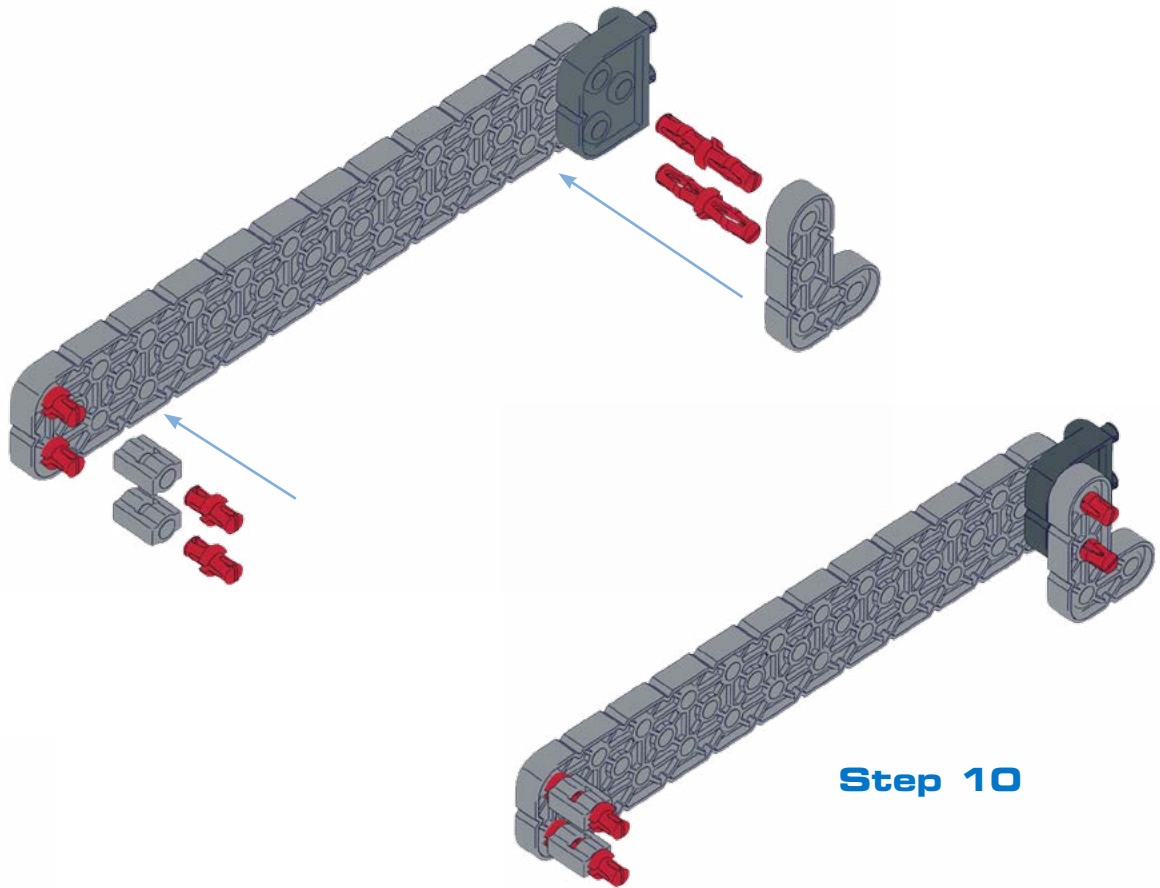
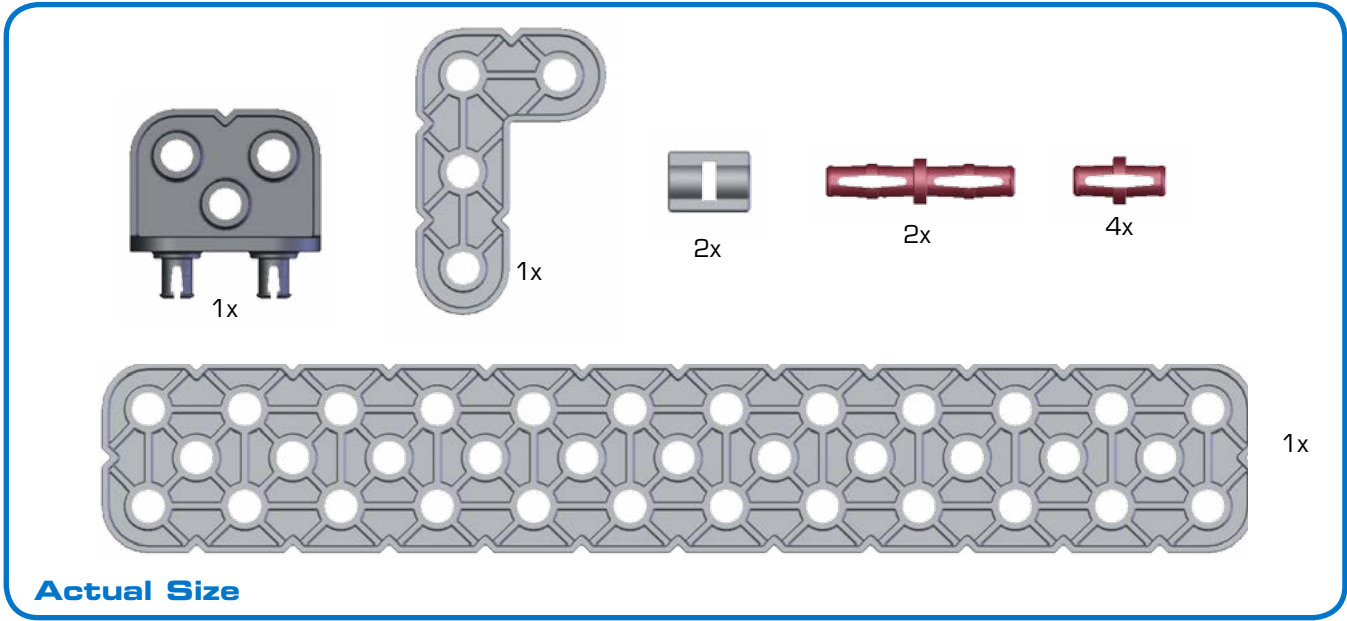


Step 8

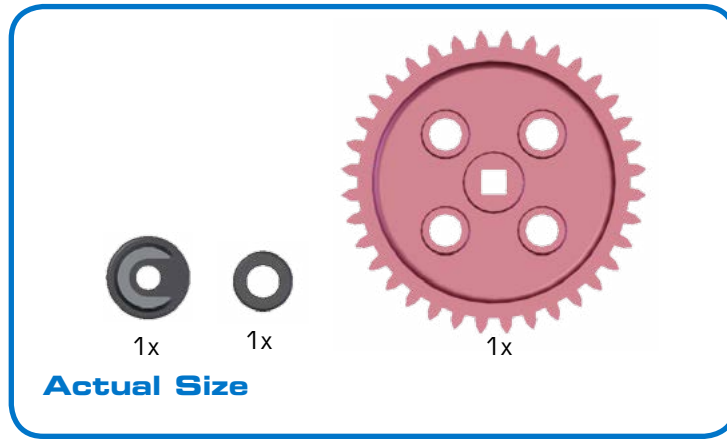




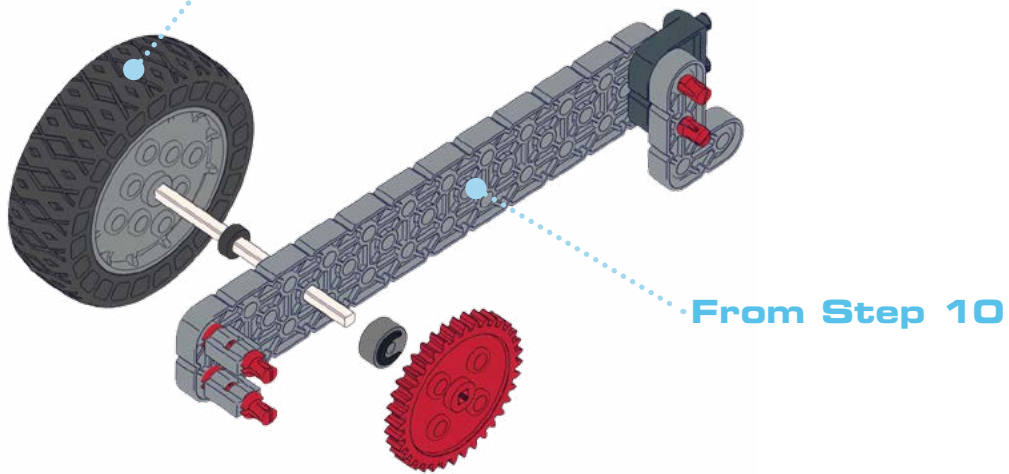
Step 9



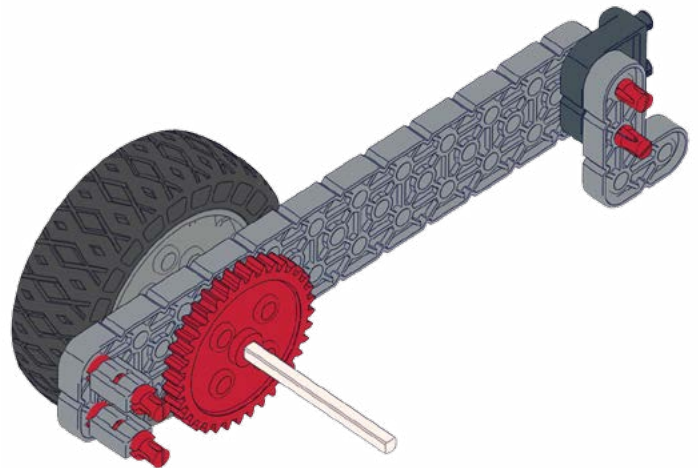


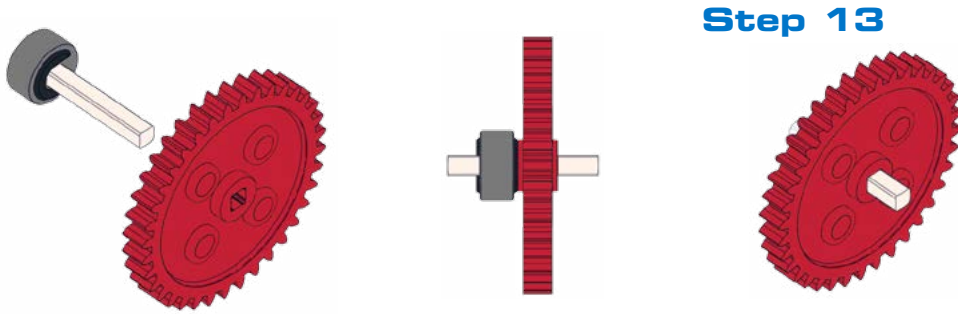
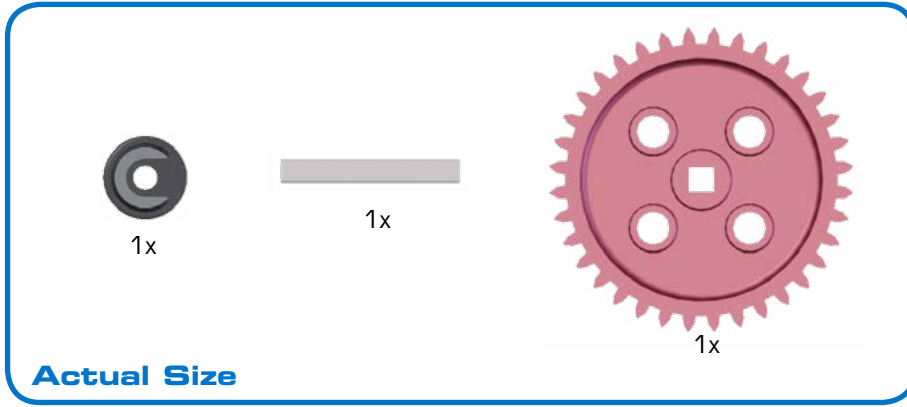


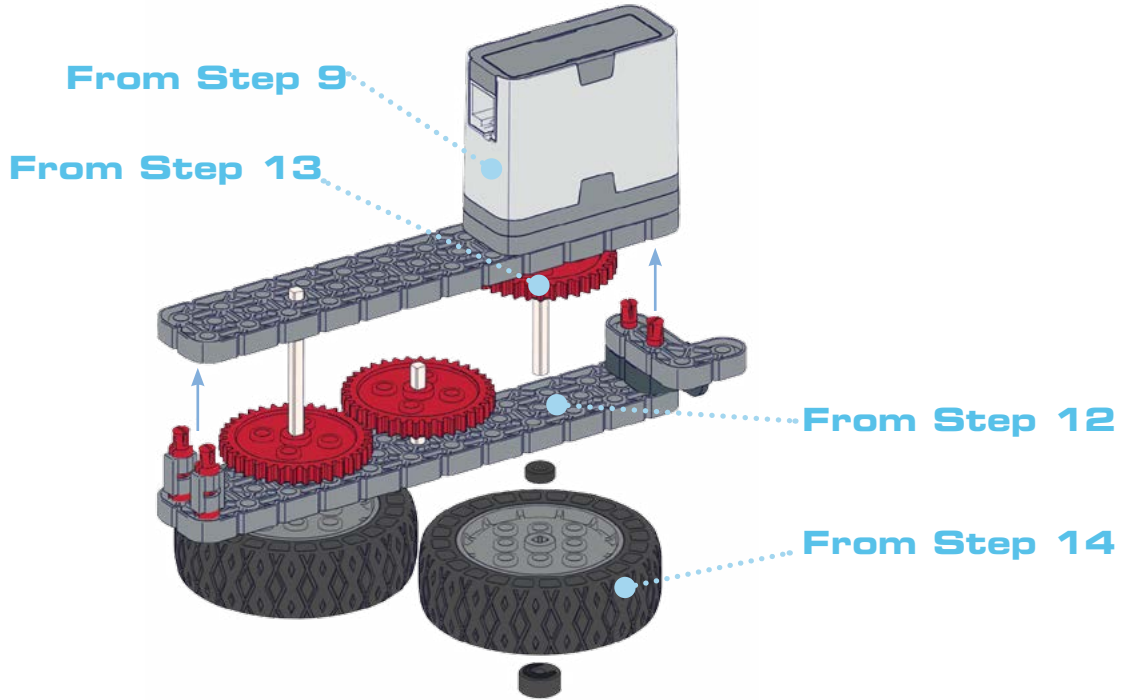
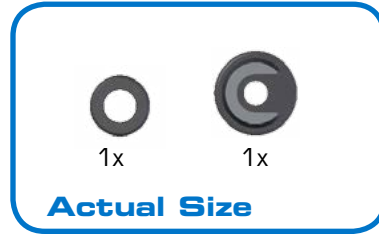
From Step 11



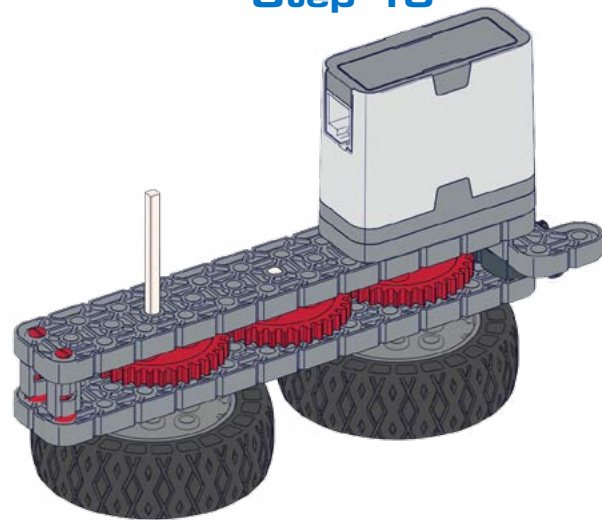
Step 12

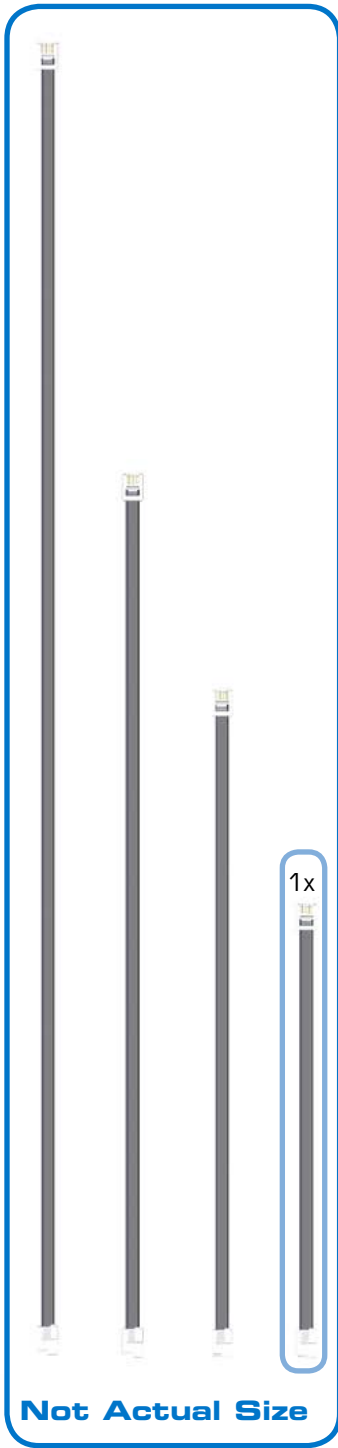




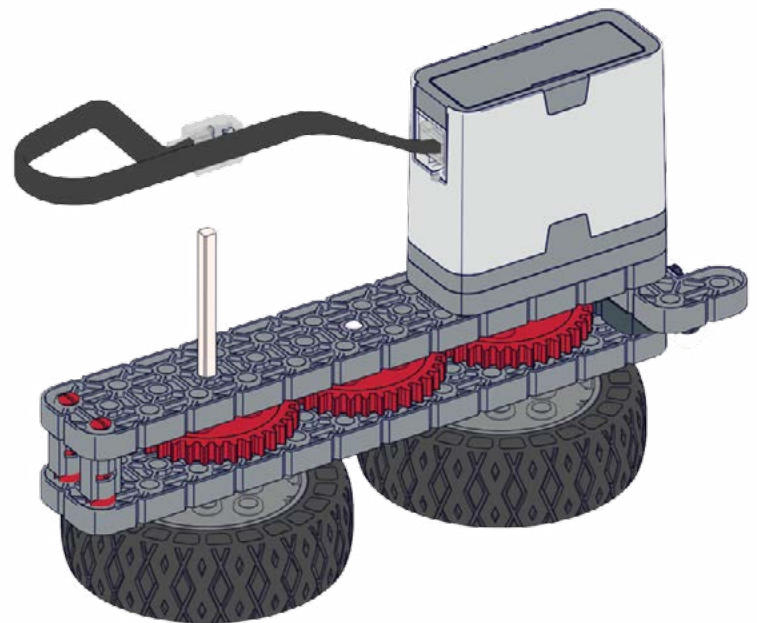
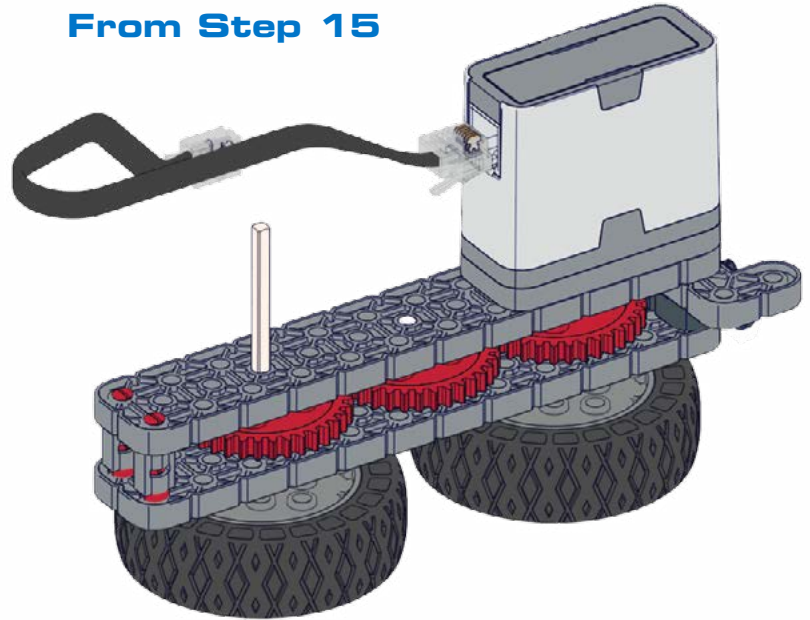


Step 15

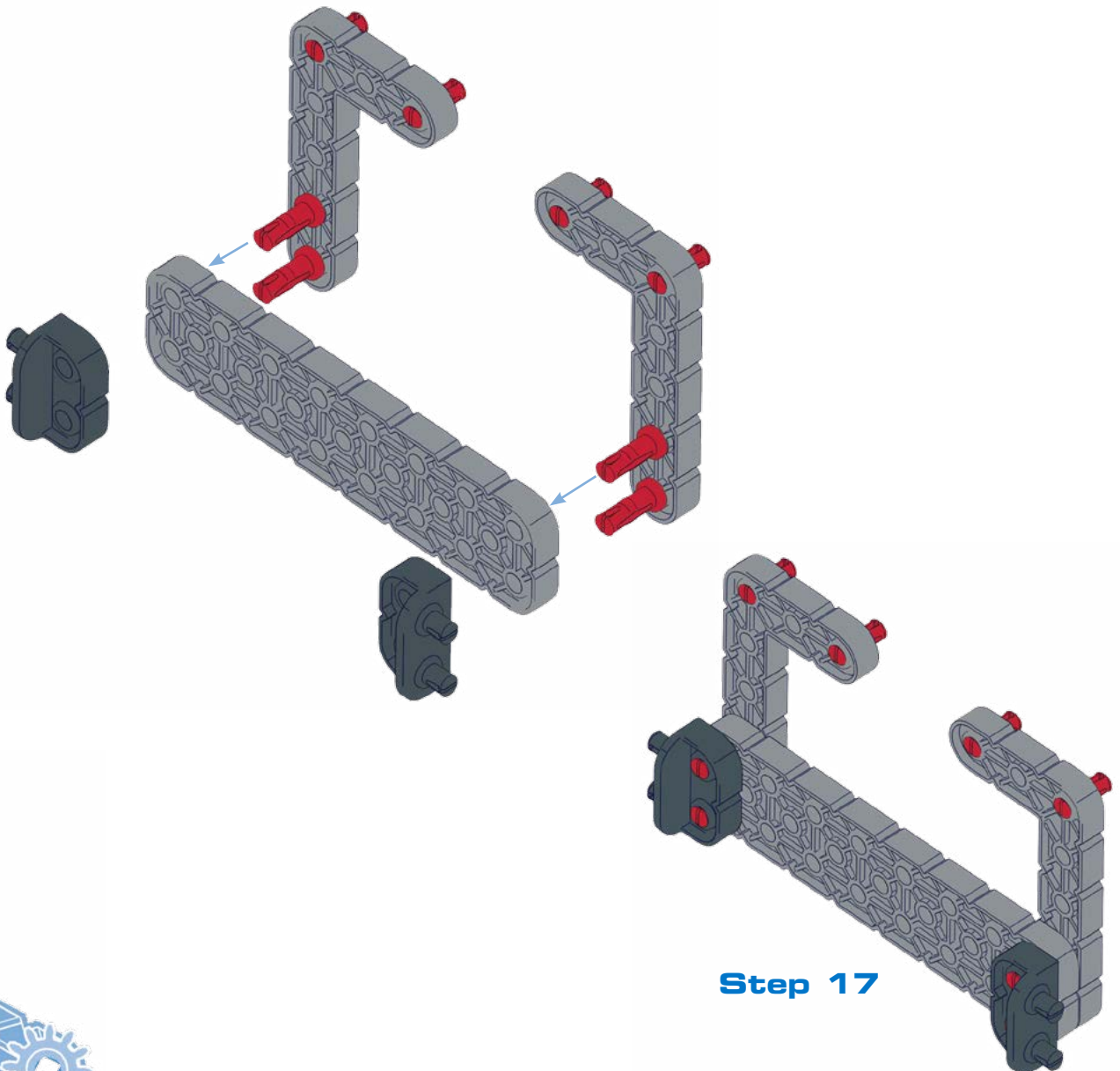
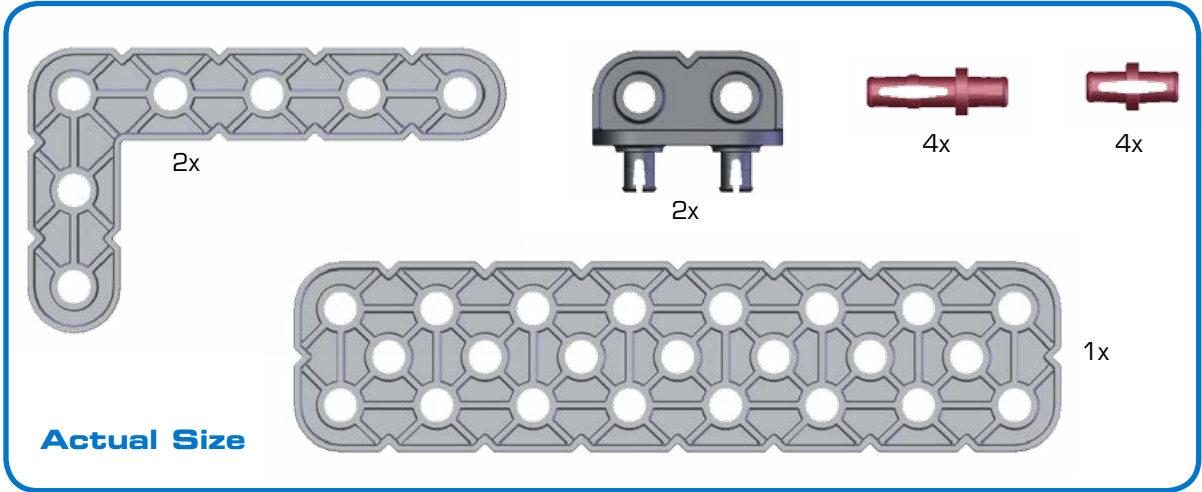


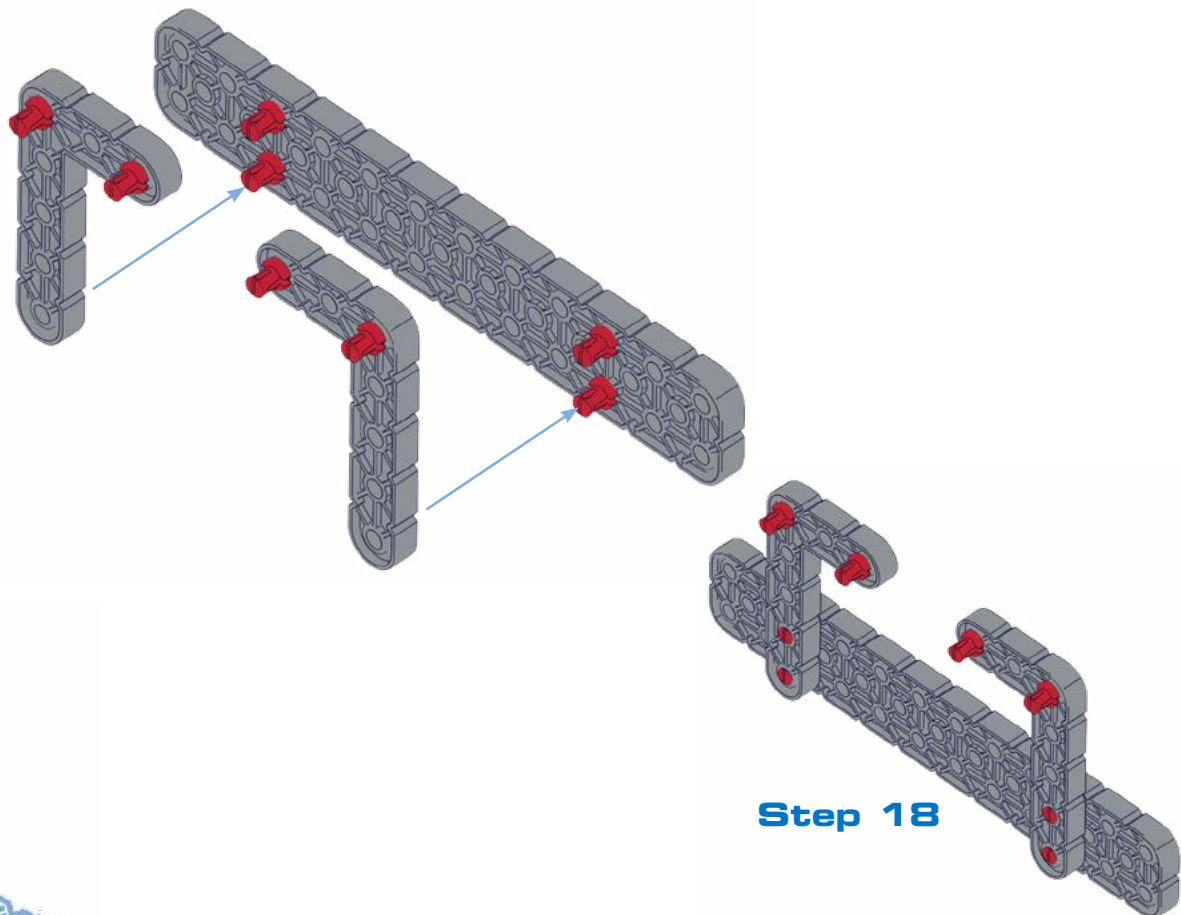
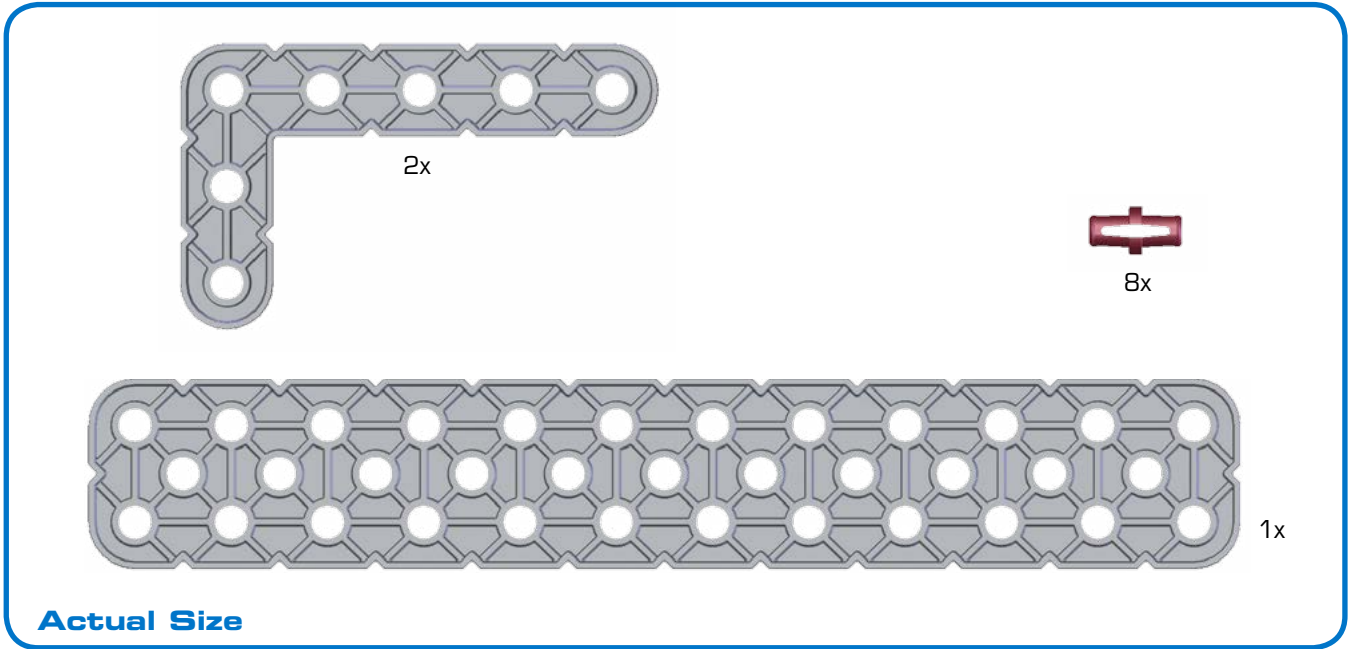


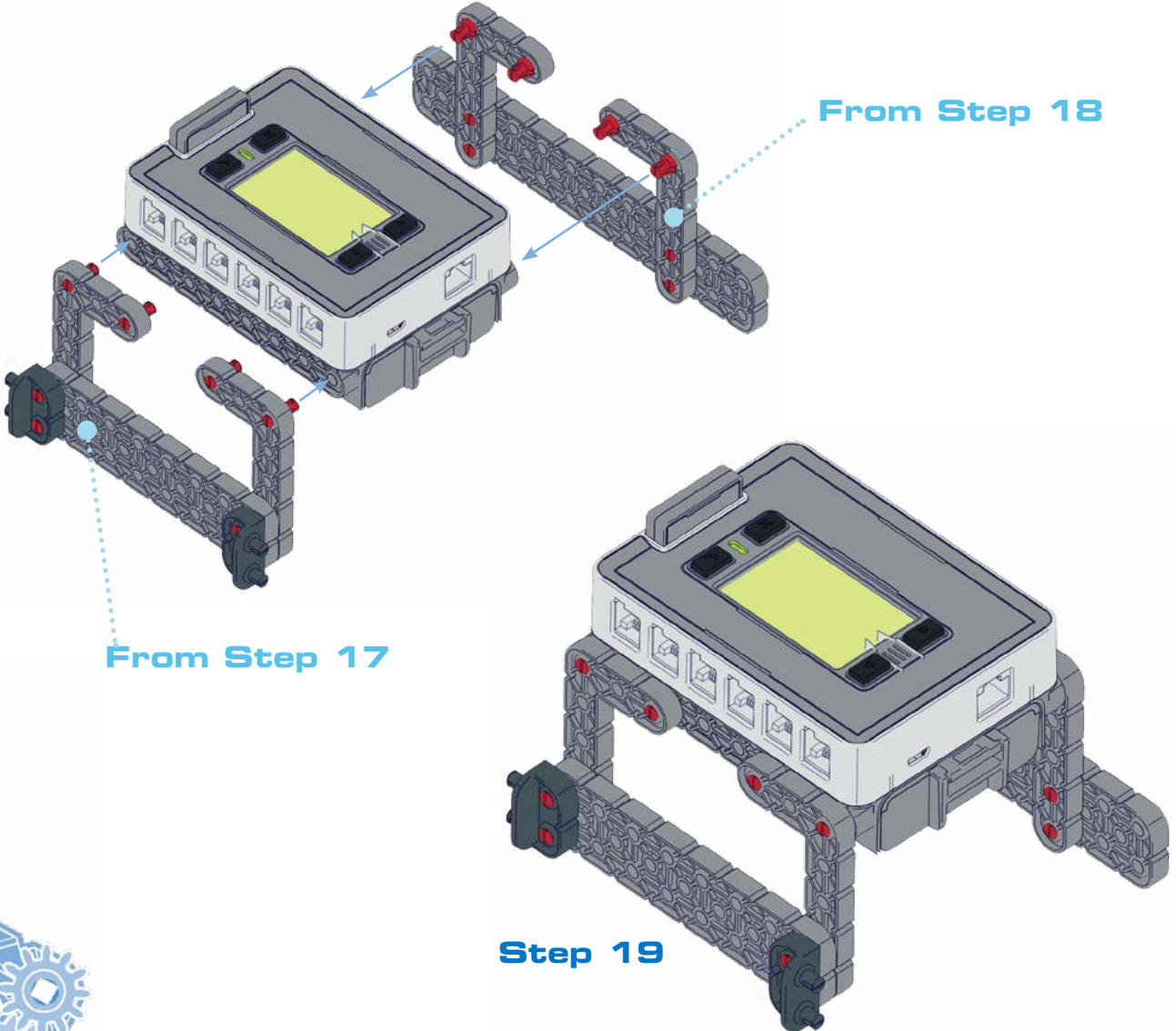
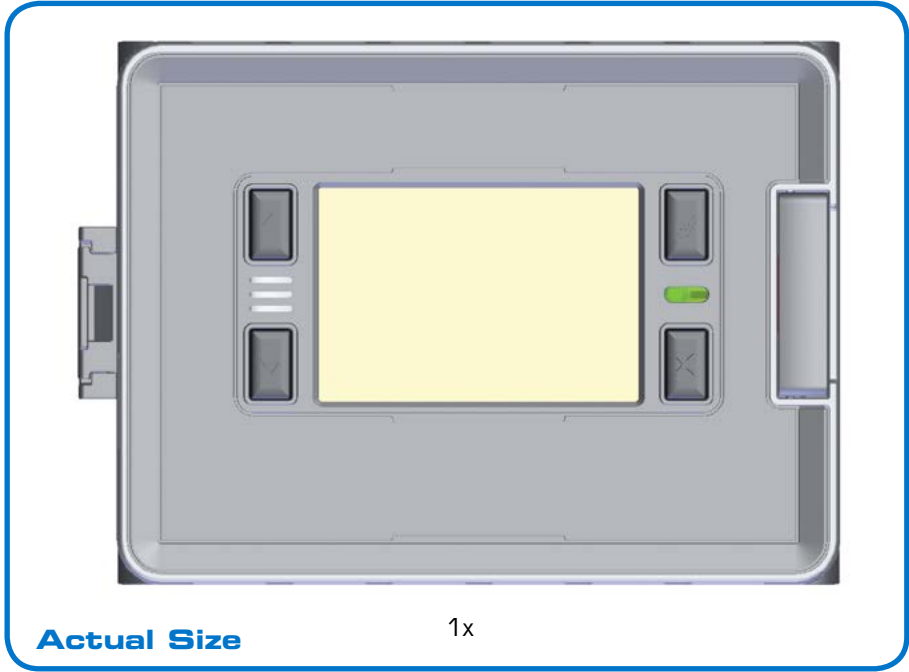
From Step 15

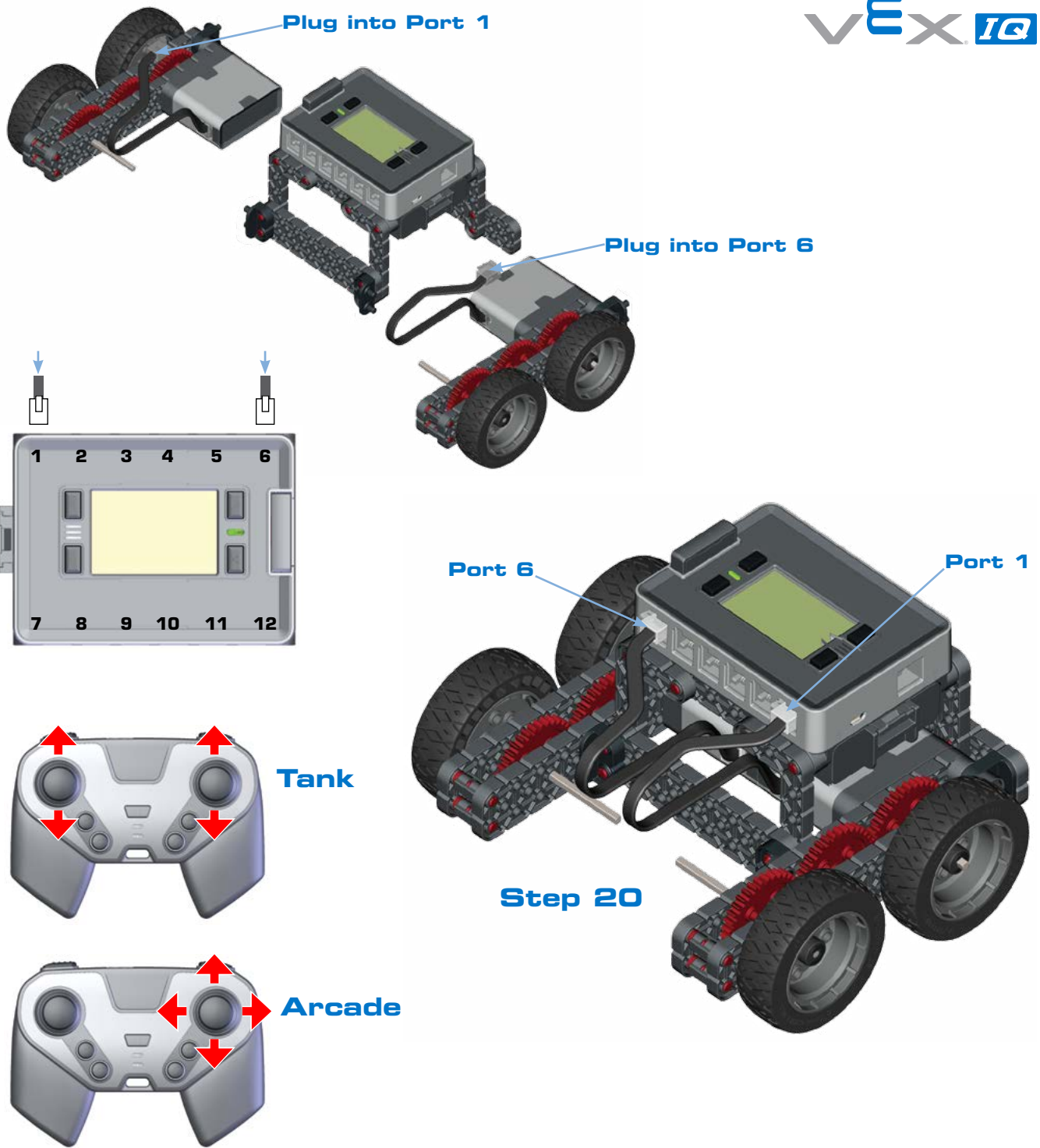


Step 16









**Robot Base is now Ready to Run!
Test it before continuing the Build.**

Part 2 Claw

1x [Grey L-shaped Technic part]

1x [Grey U-shaped Technic part]

2x [Red Technic Pin]

1x [Red Technic Pin]

1x [Red Technic Pin]

Actual Size



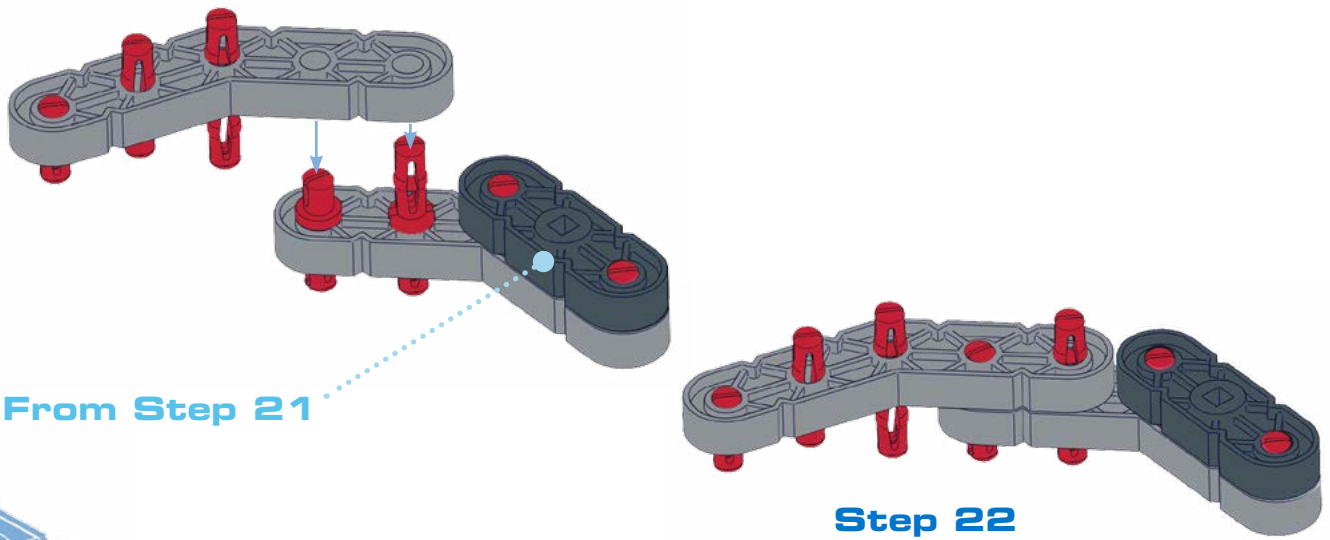
1x [Grey L-shaped Technic part]

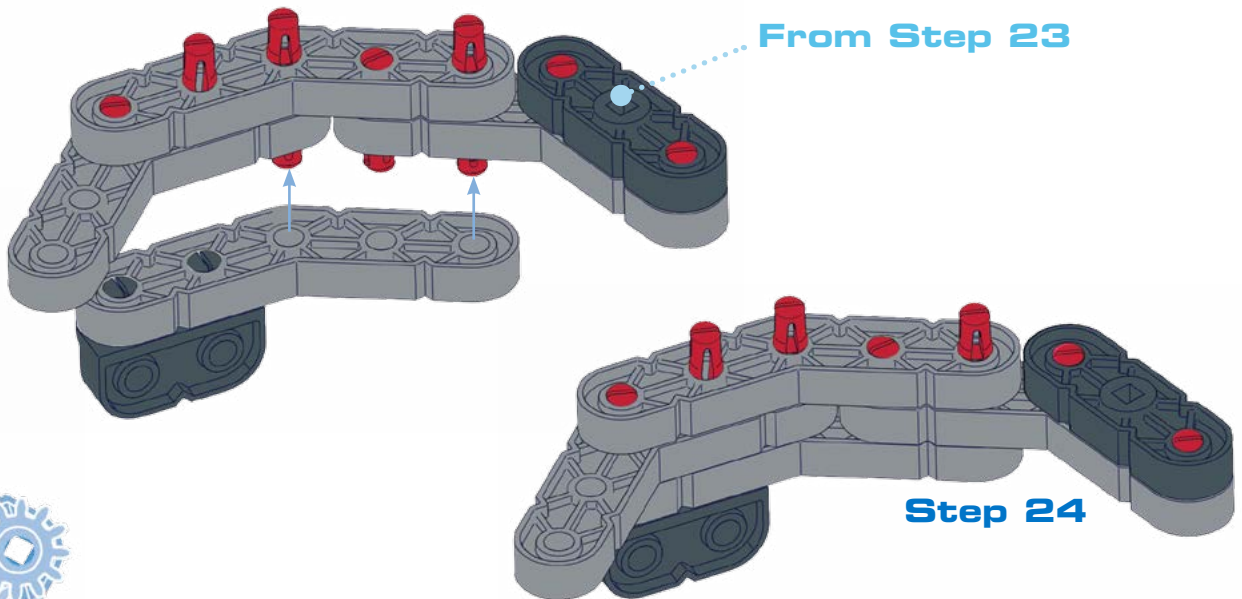
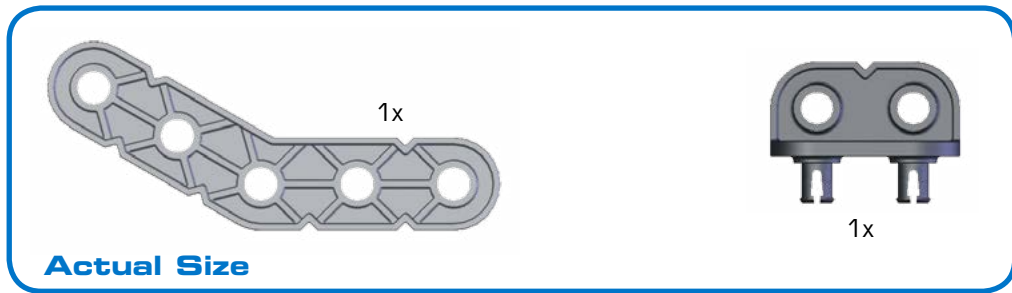
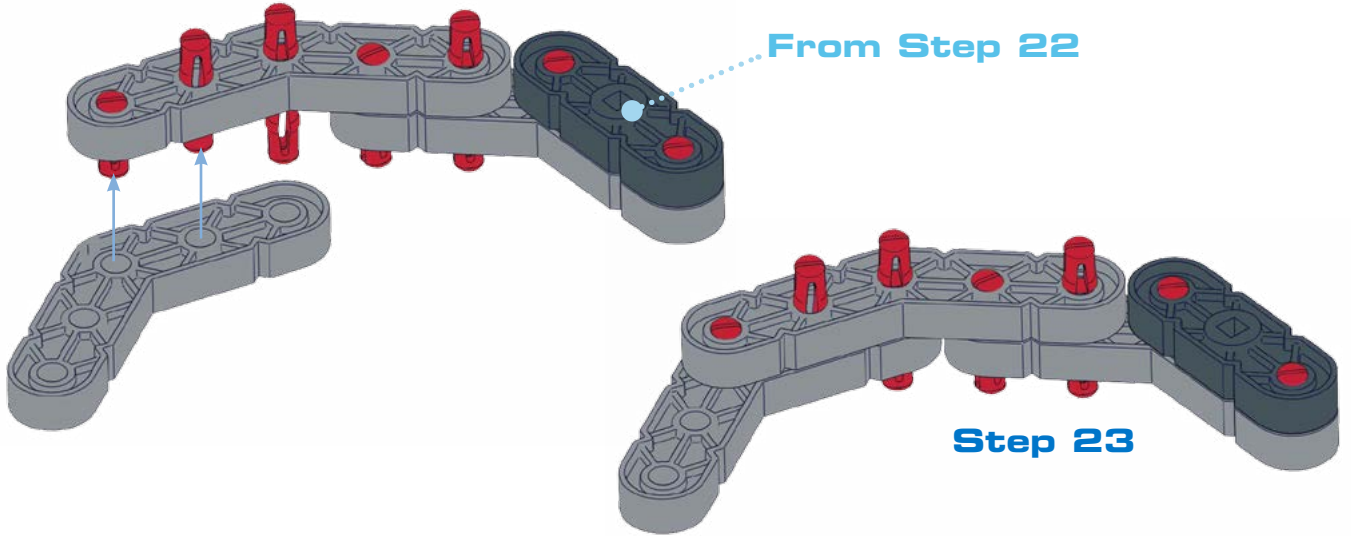
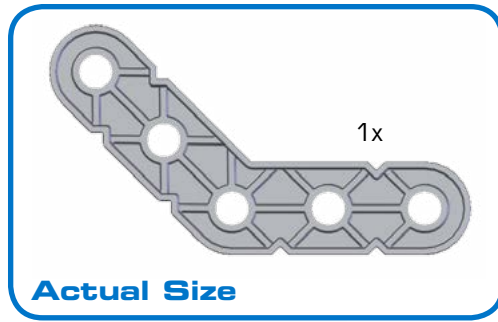
1x [Red Technic Pin]

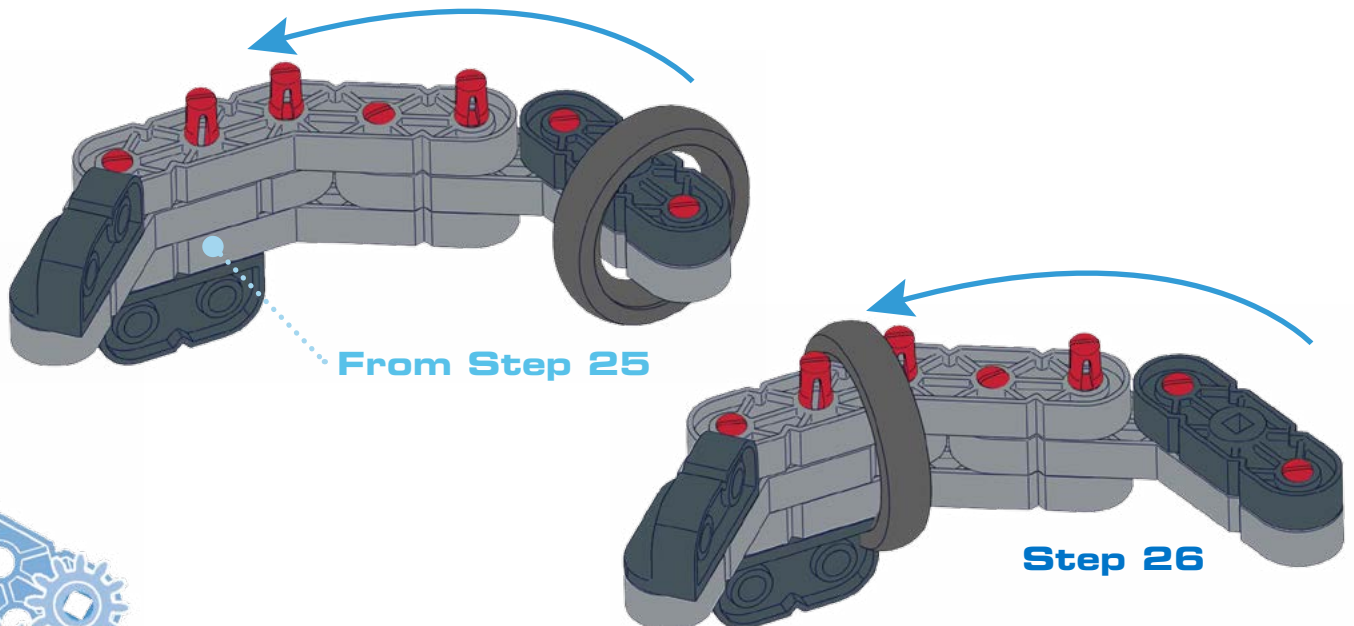
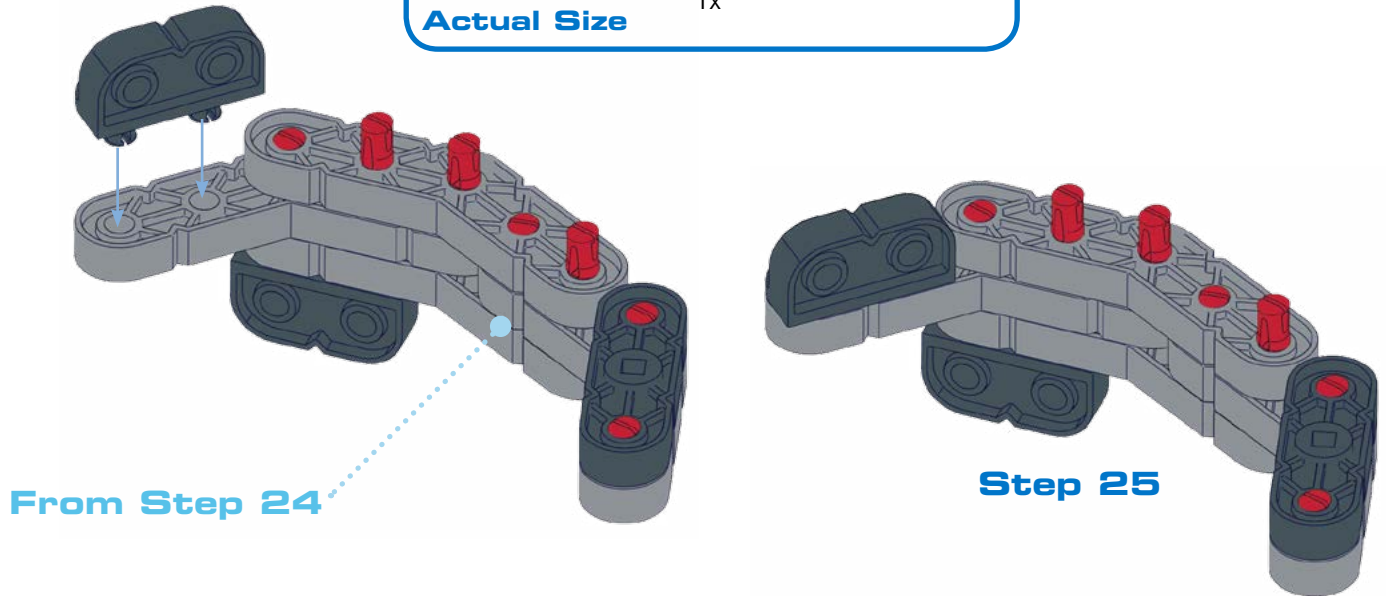
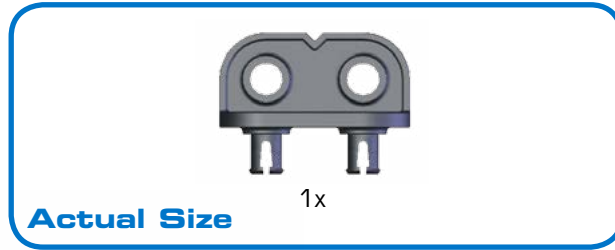
1x [Red Technic Pin]

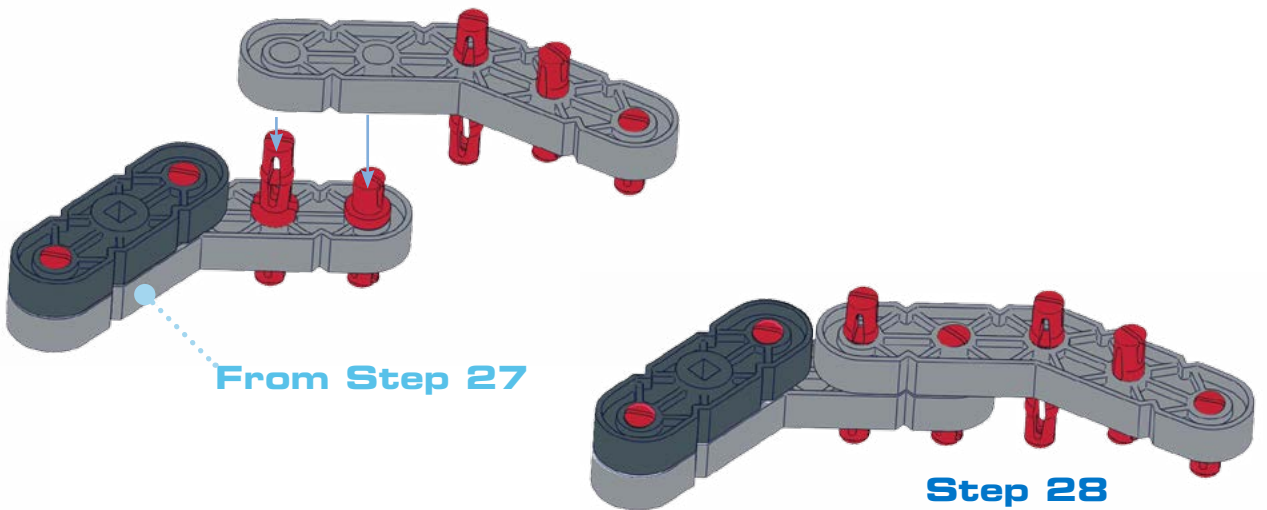
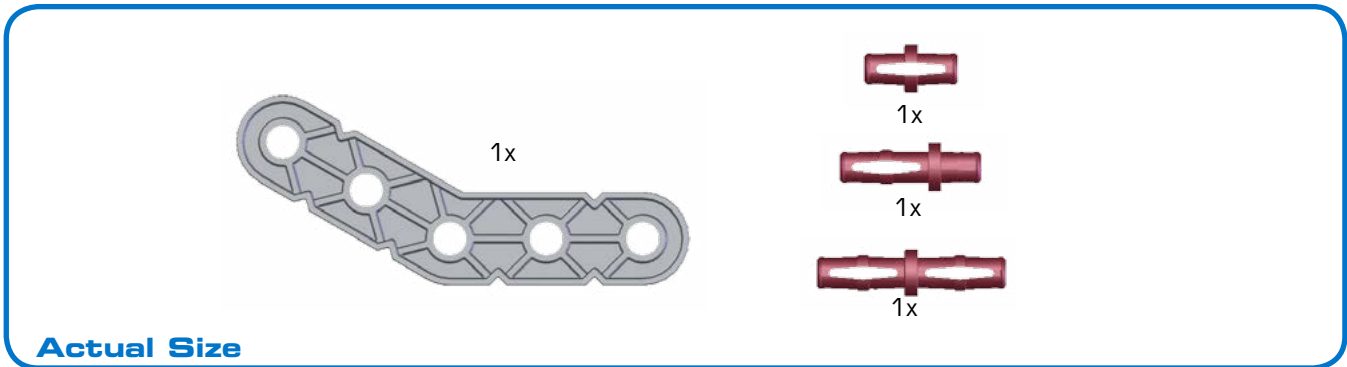
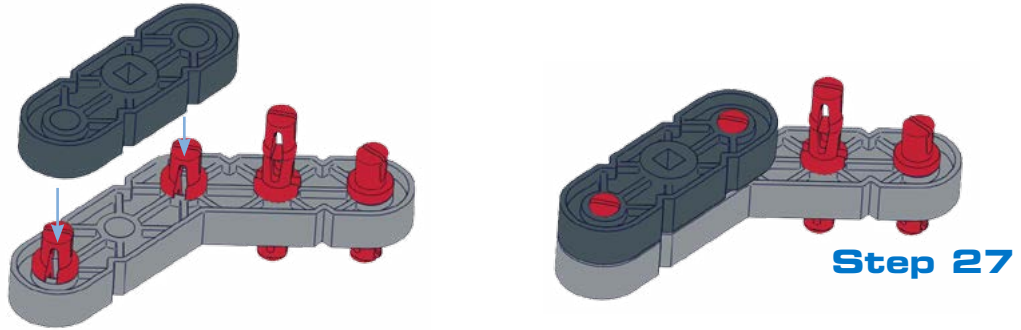
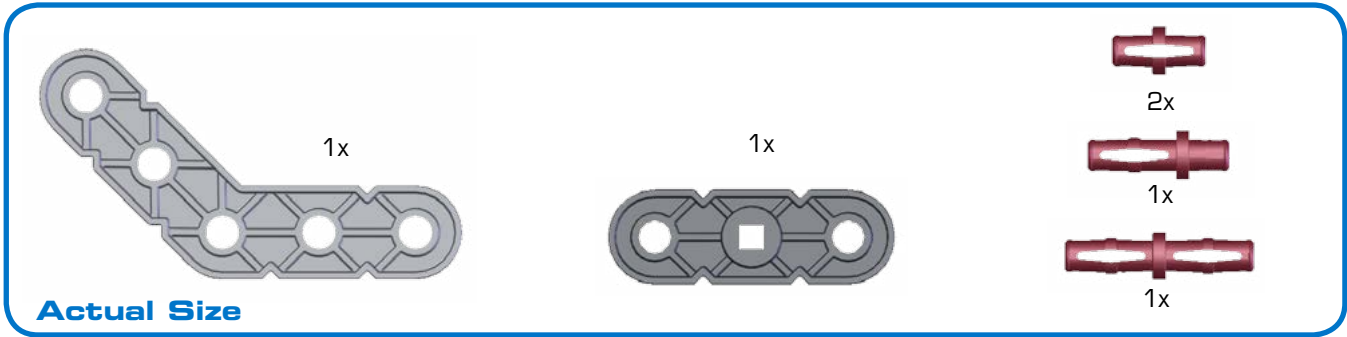
1x [Red Technic Pin]

Actual Size

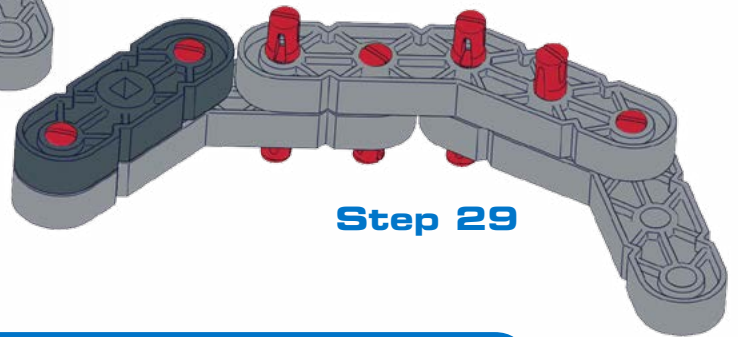
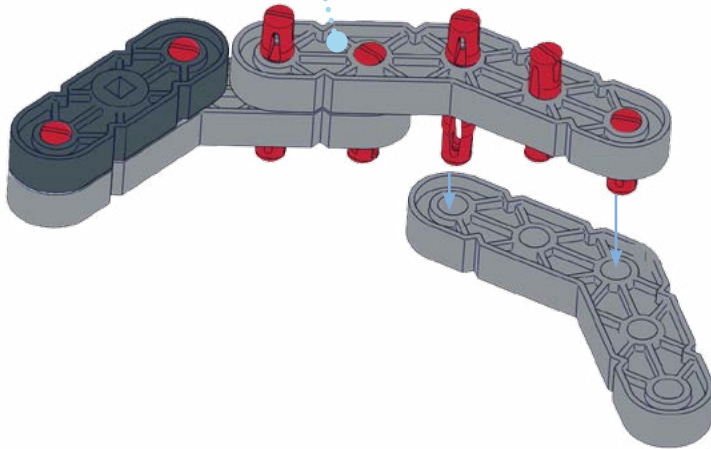
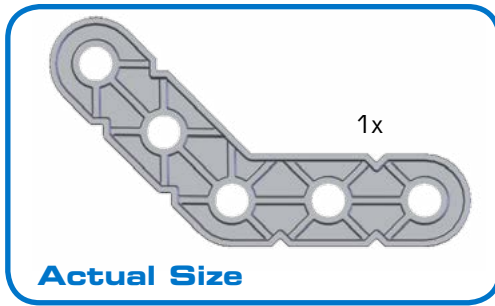




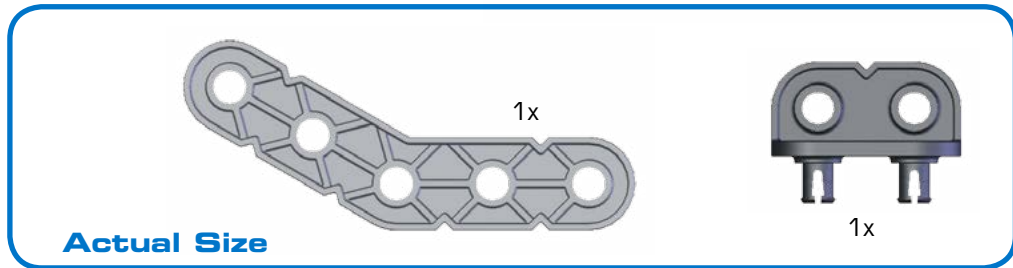




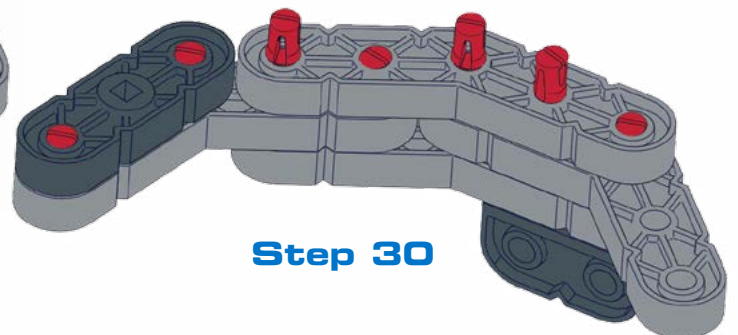
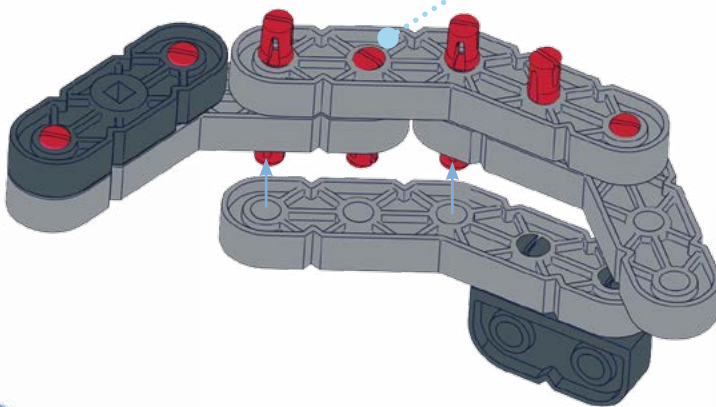
From Step 28



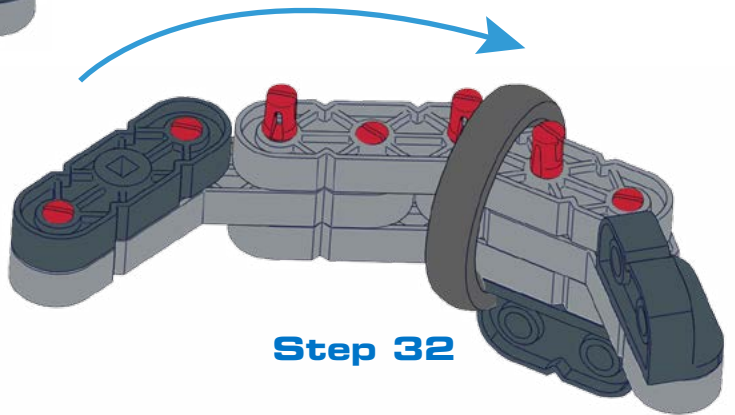
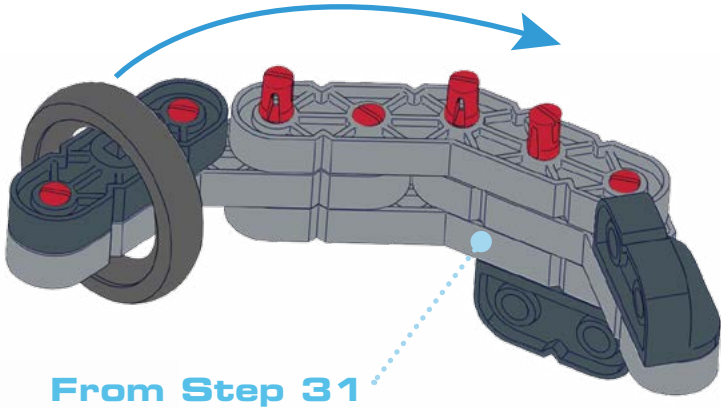
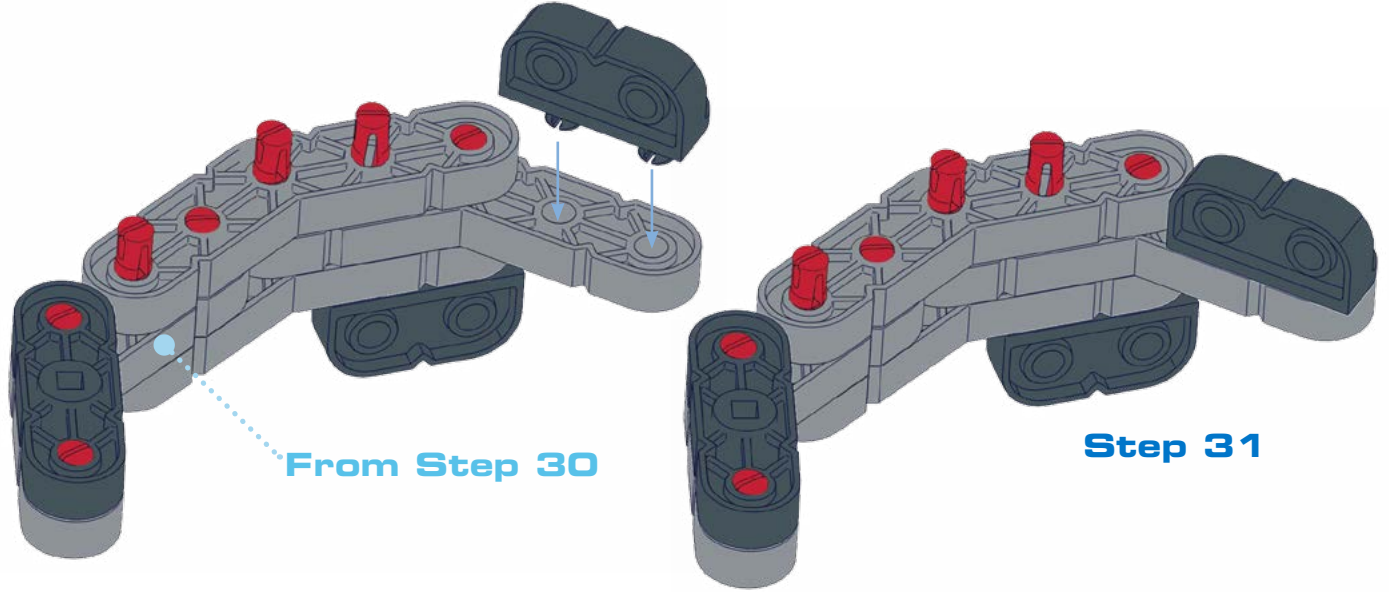
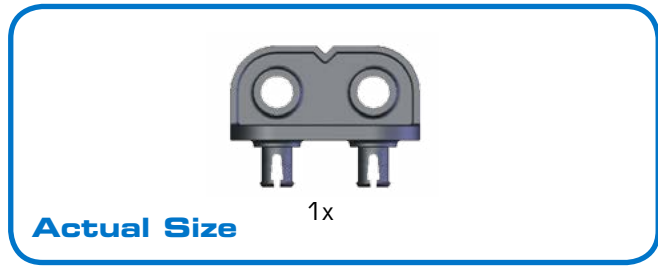
Step 29

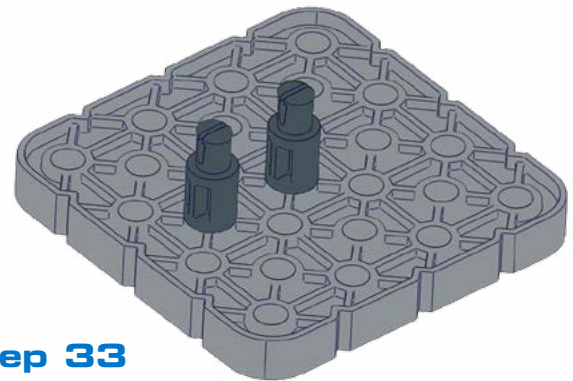
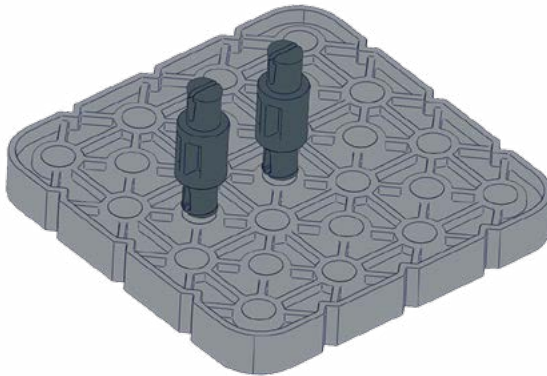
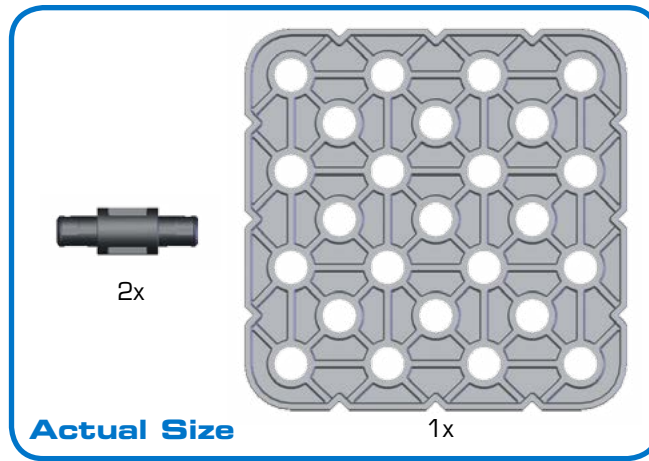


From Step 29

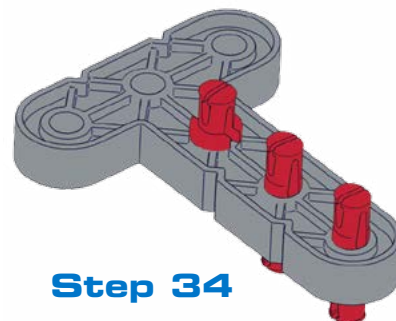
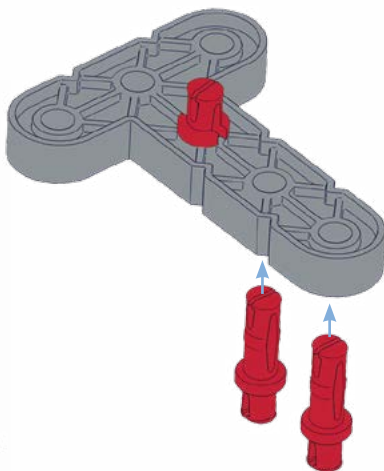
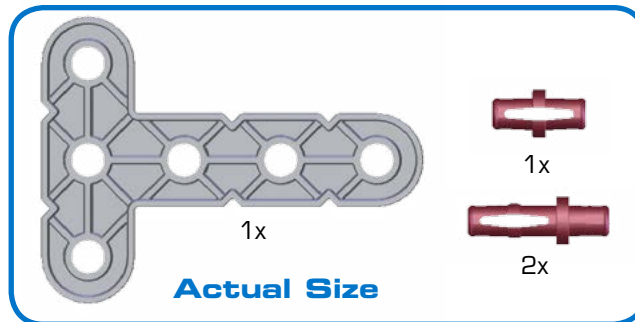


Step 30

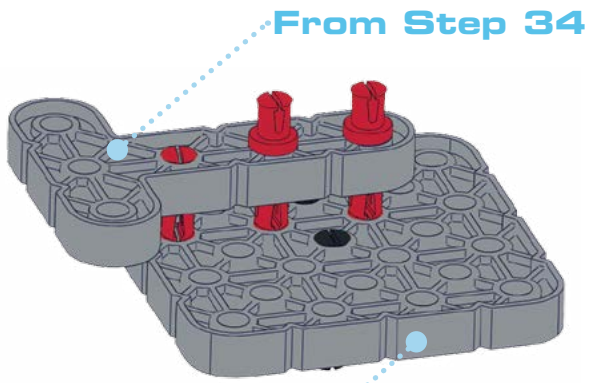




Step 33



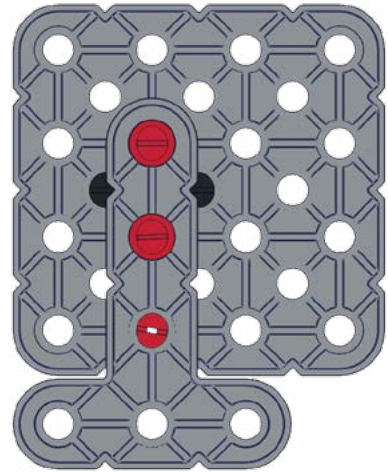
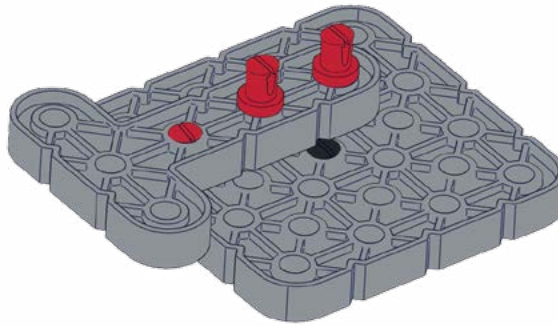
Step 34



From Step 34

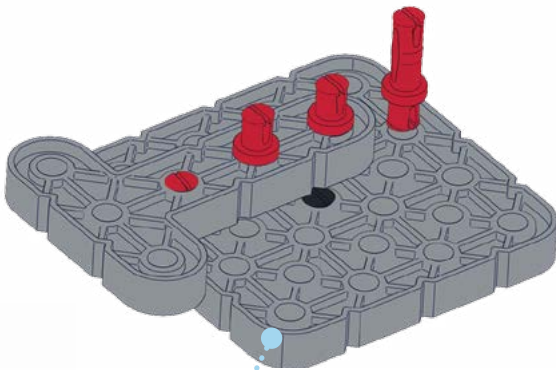
From Step 33

Step 35

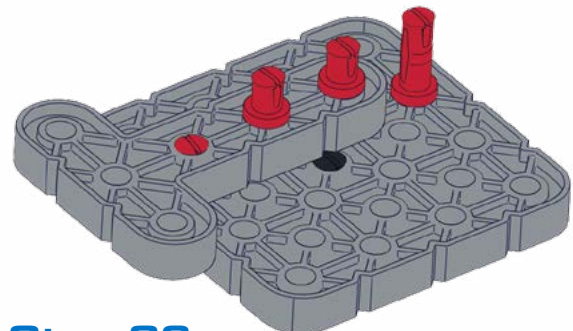


Actual Size

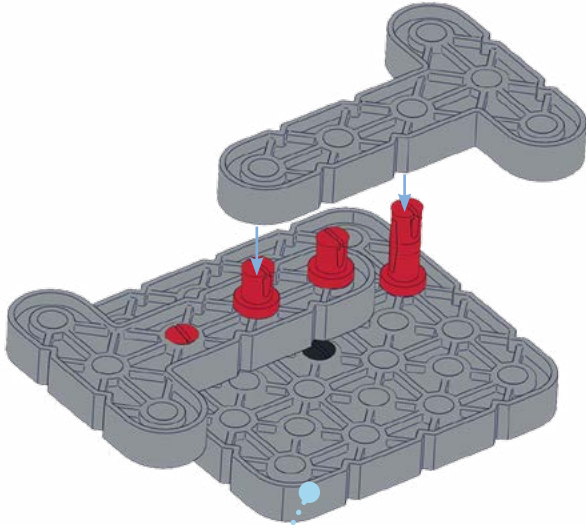
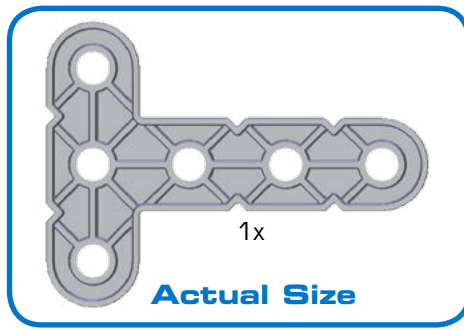
1x



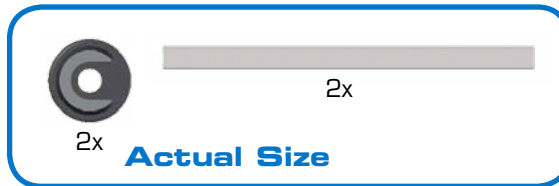
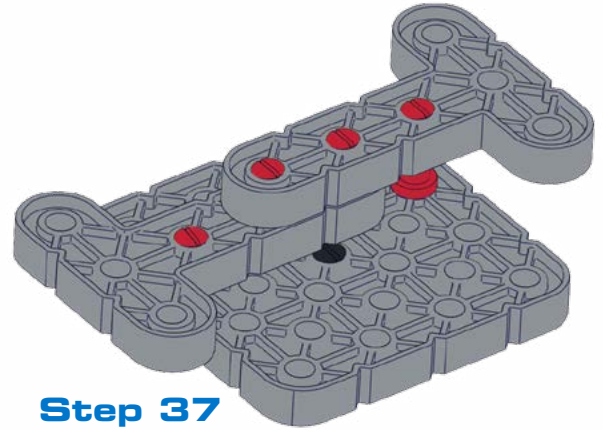
From Step 35



Step 36



From Step 36



Step 38



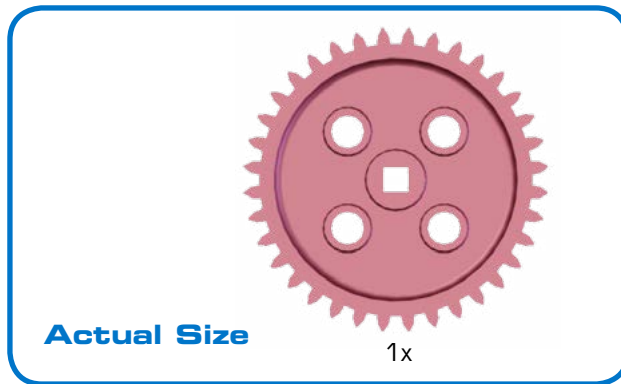
Make
(2x)

From Step 38

From Step 26

From Step 37

Step 39

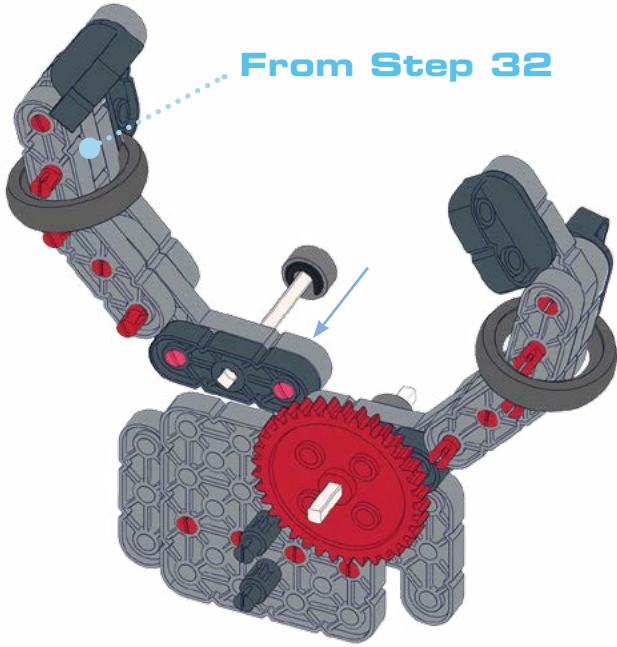


Actual Size

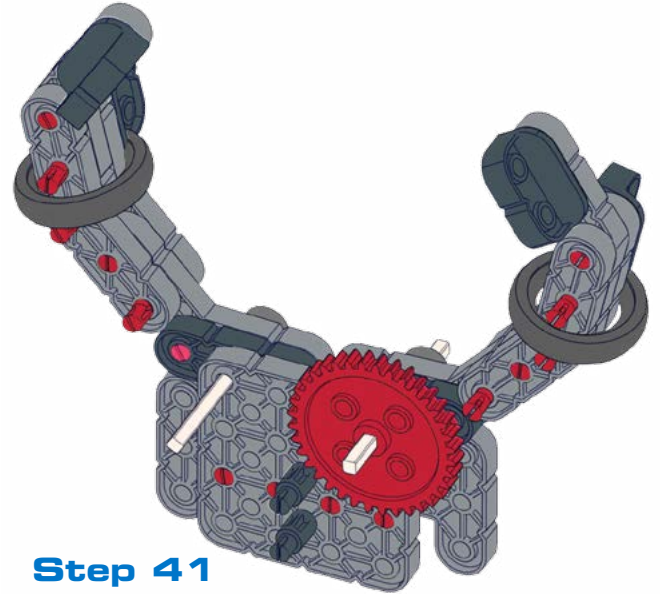
1x

From Step 39

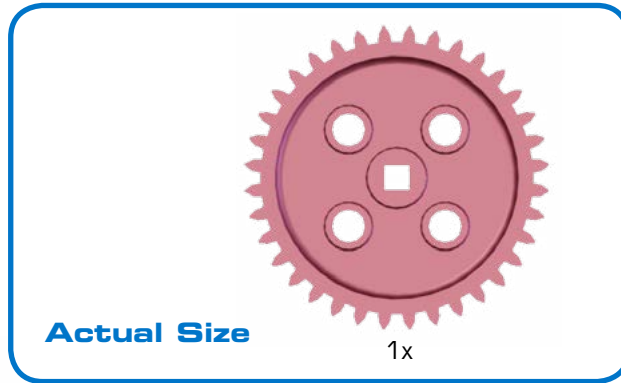
Step 40



From Step 32

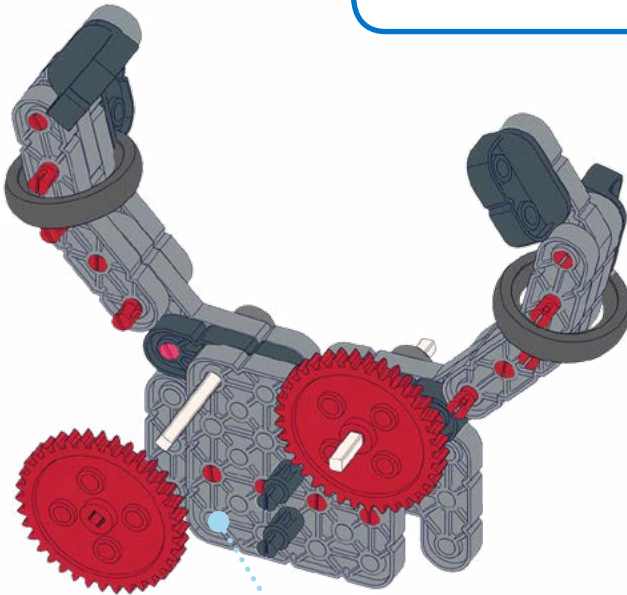


Step 41

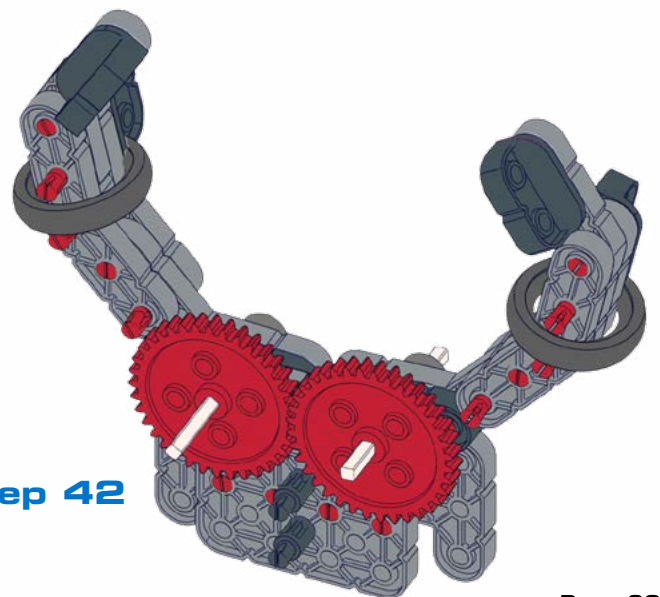


Actual Size

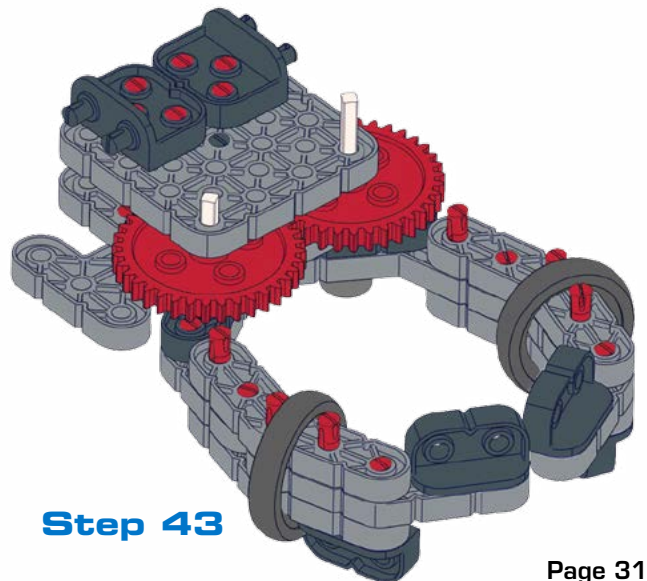
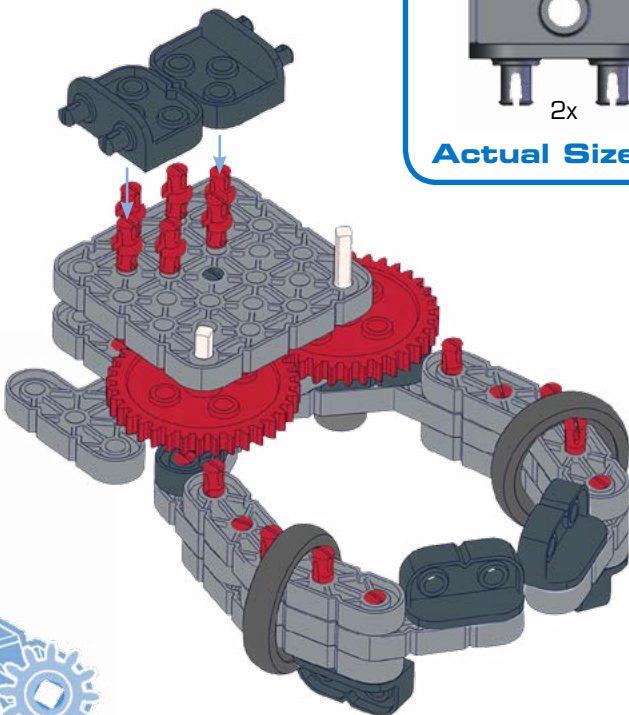
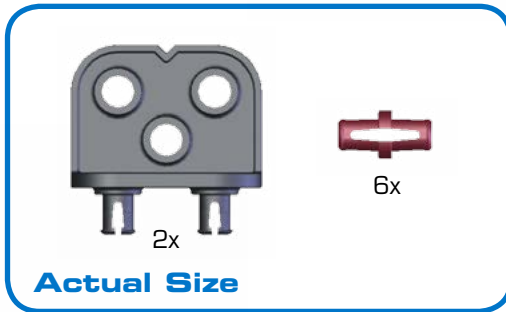
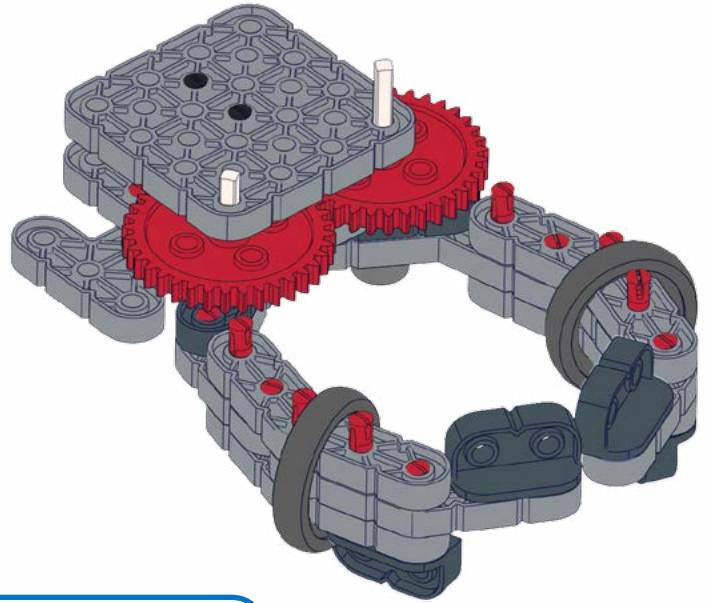
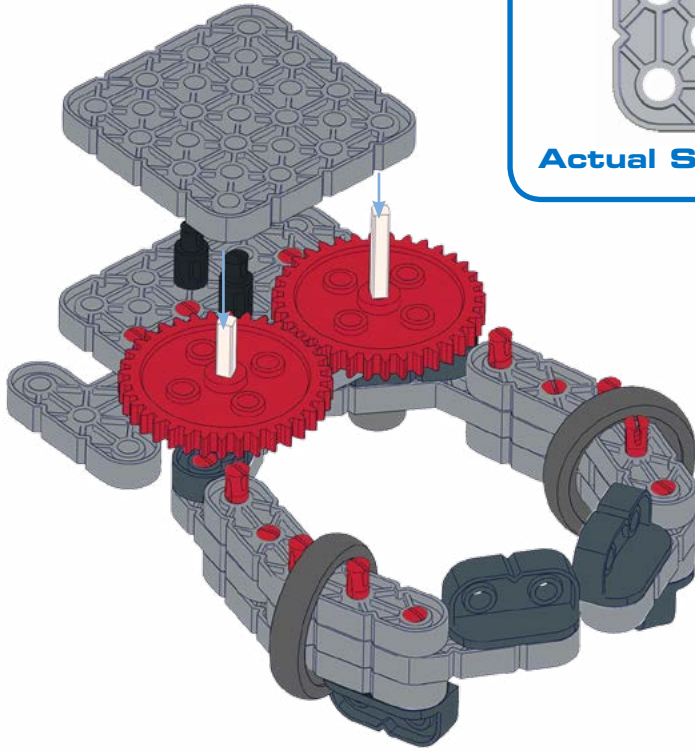
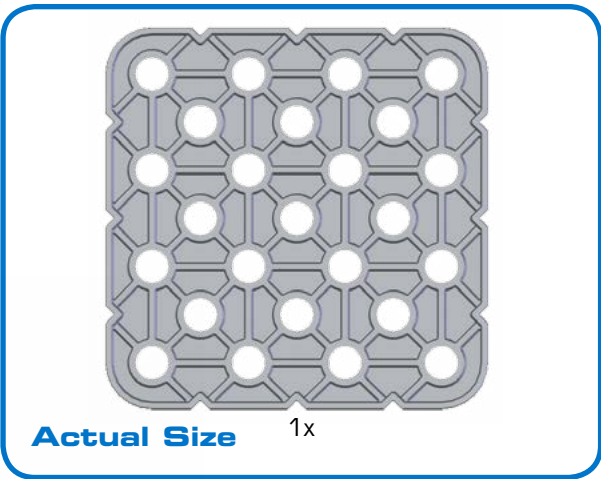
1x



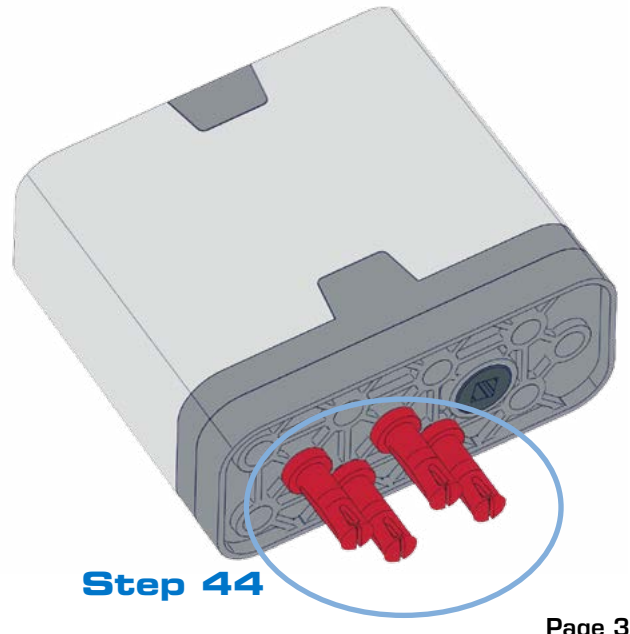
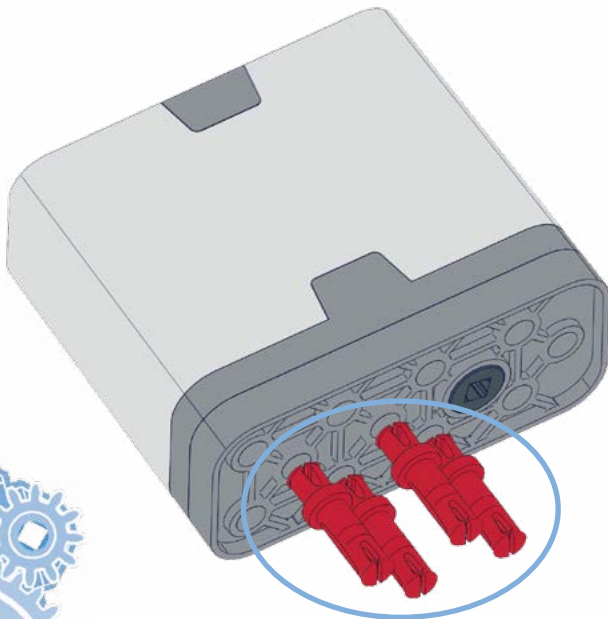
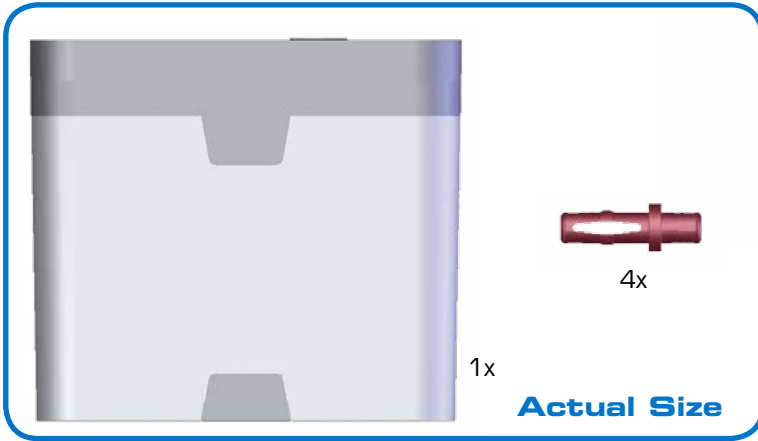
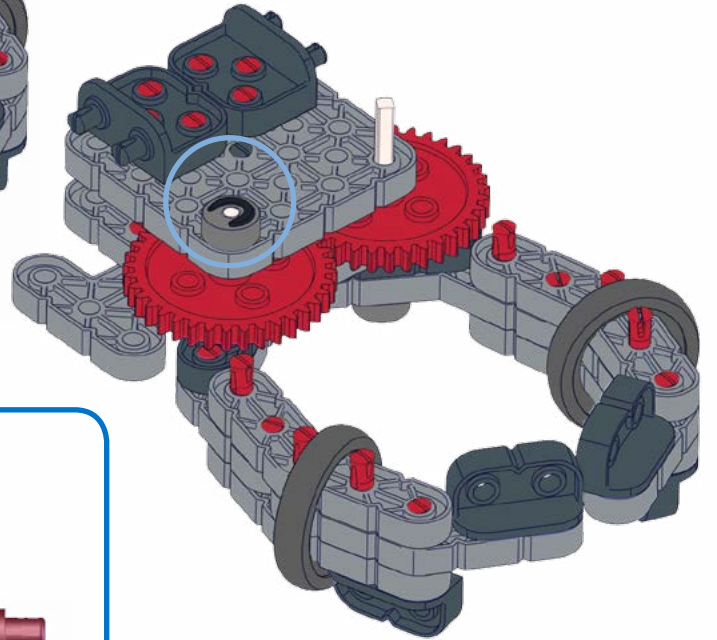
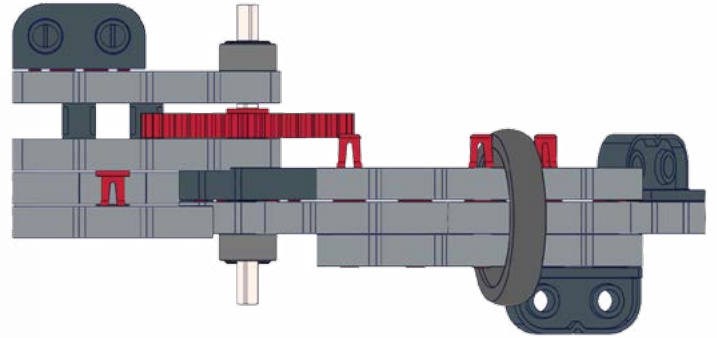
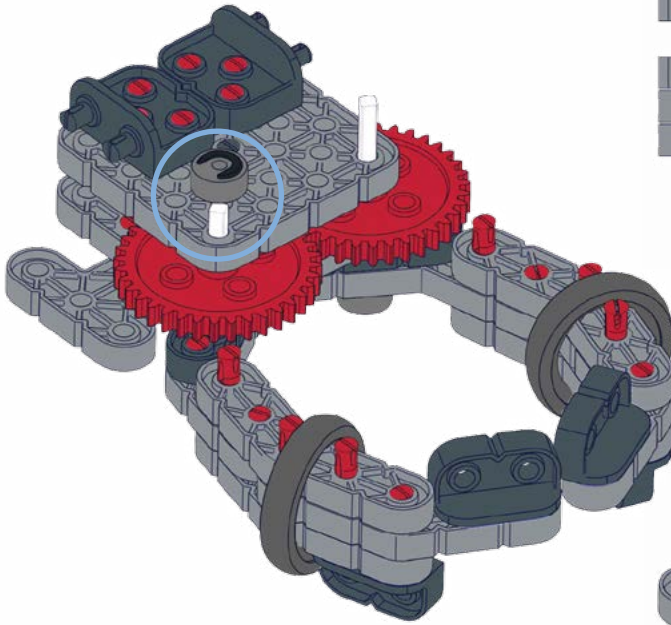
From Step 41



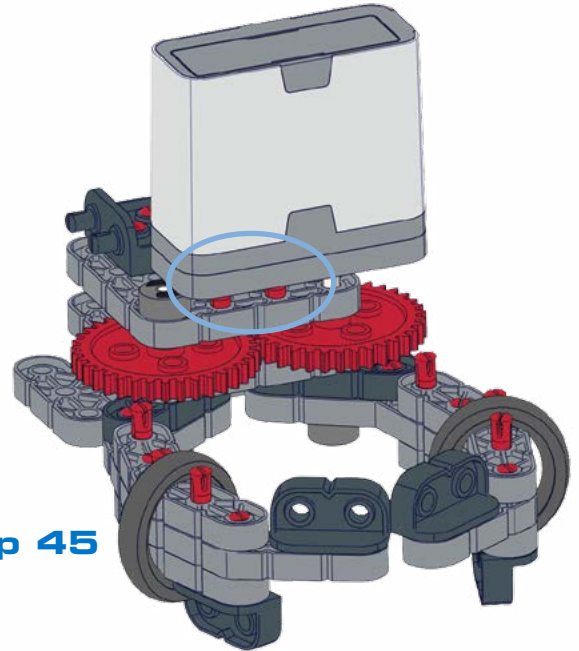
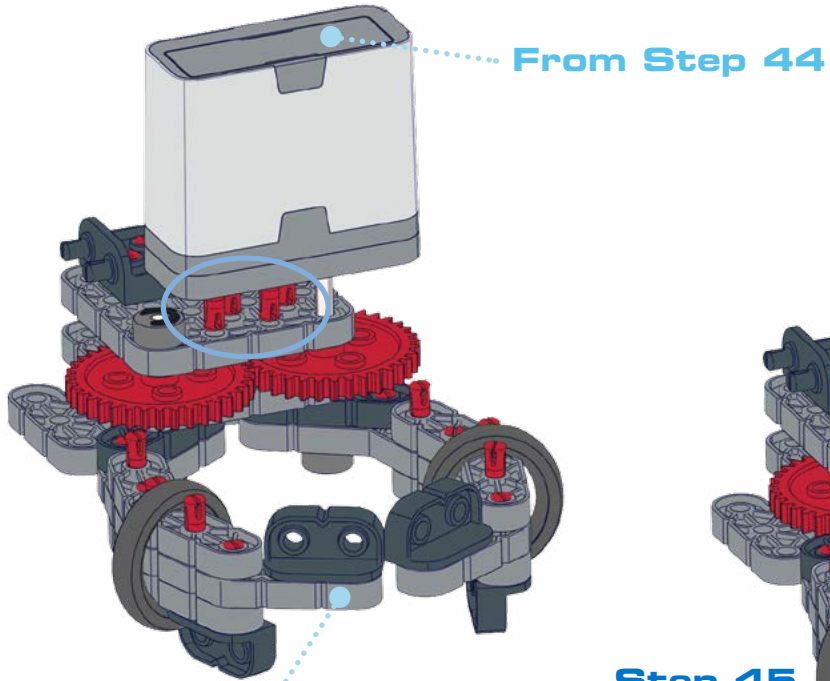
Step 42



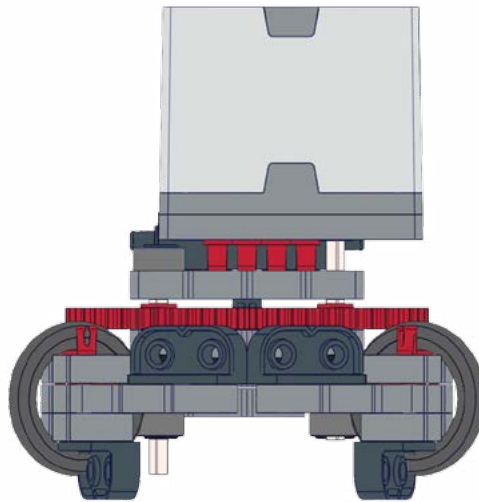
Step 43

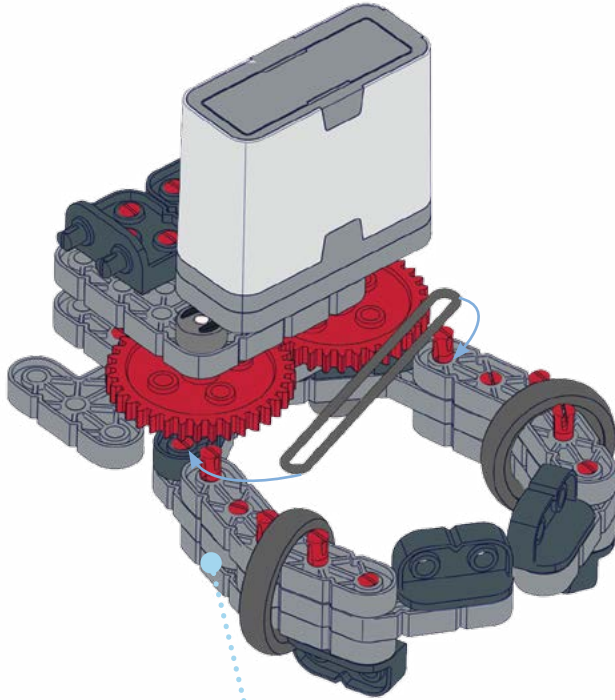


Step 44

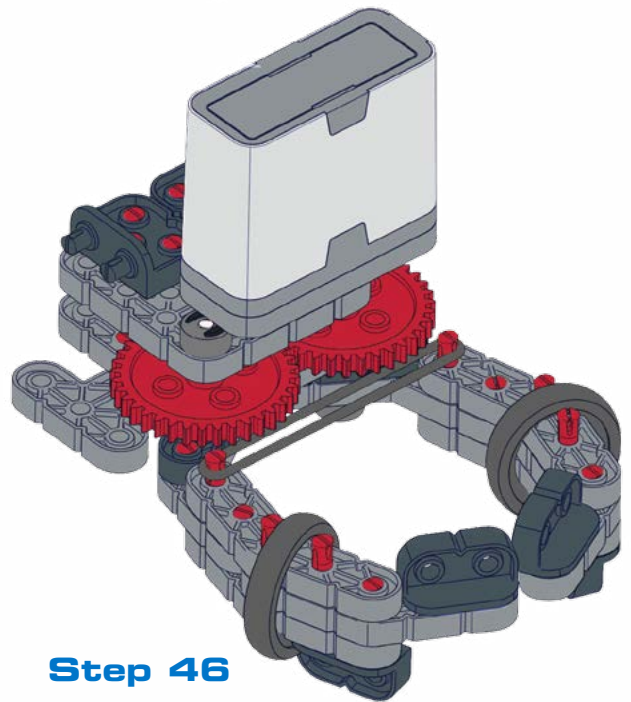


Step 45



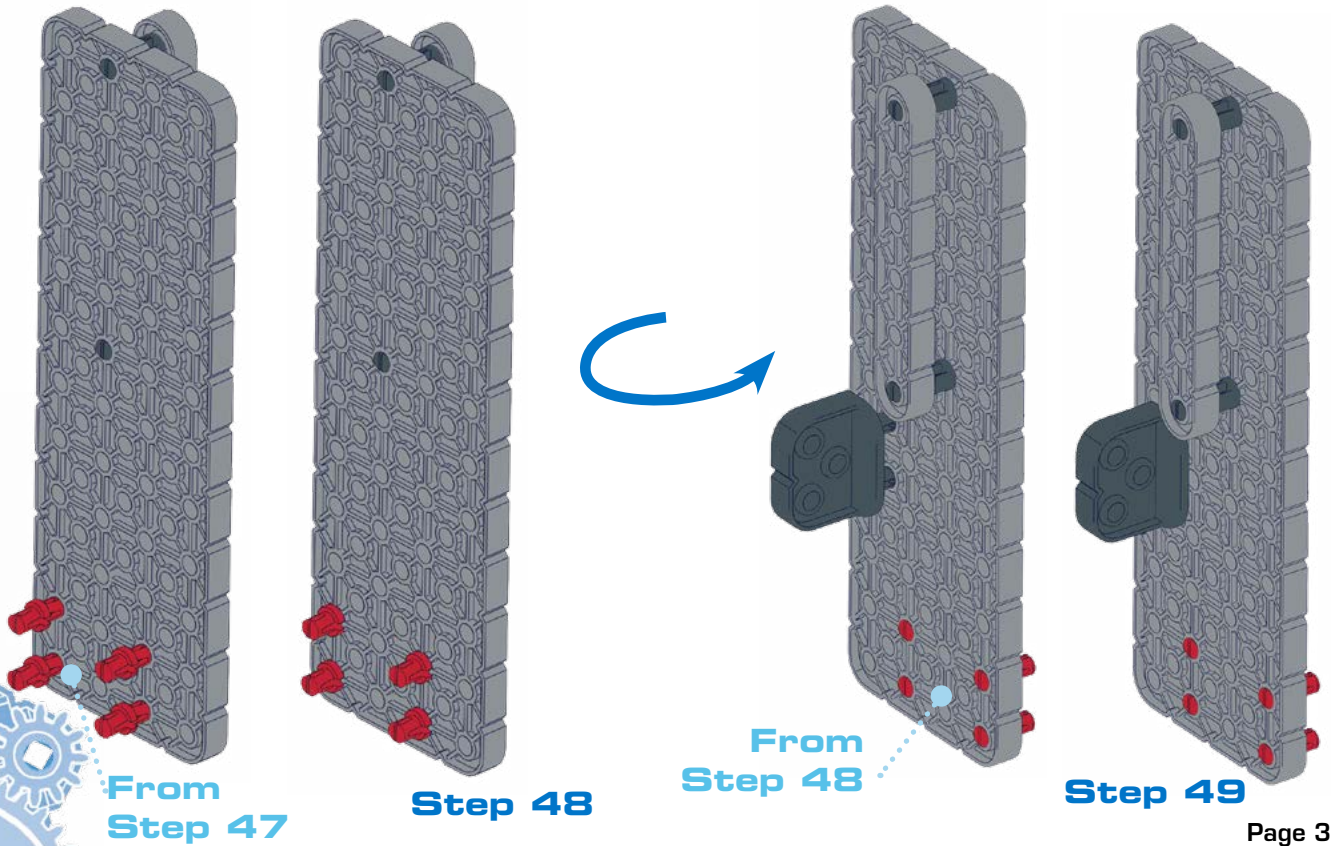
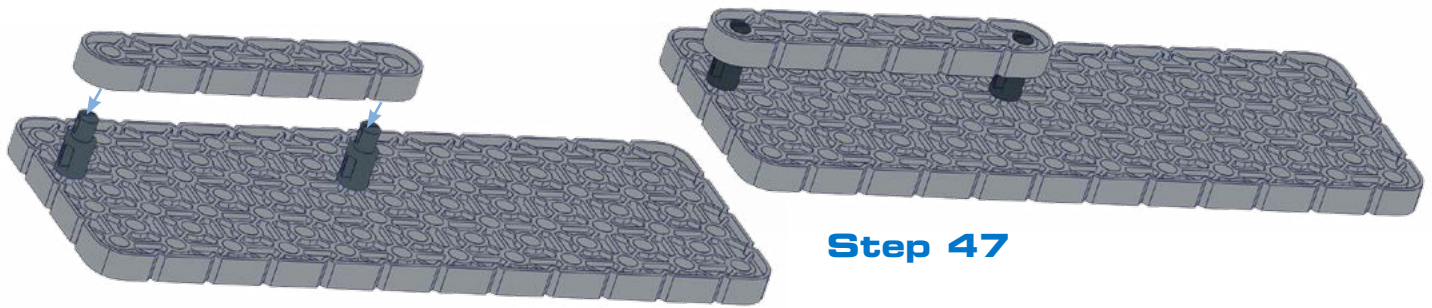
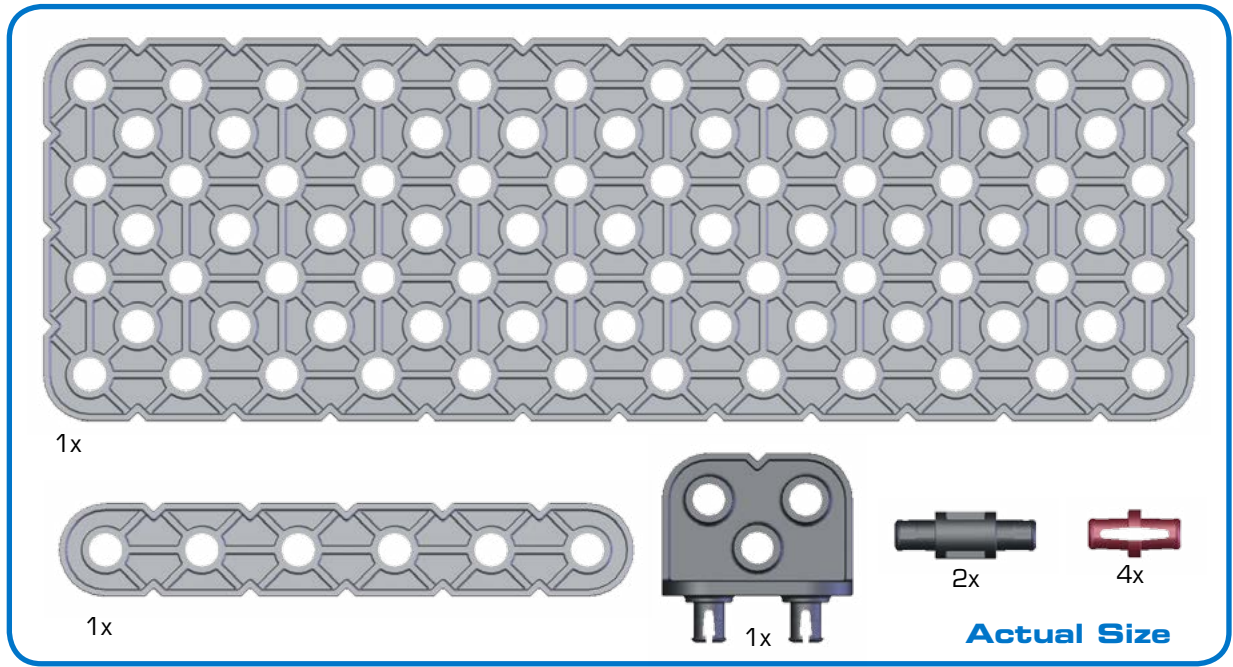


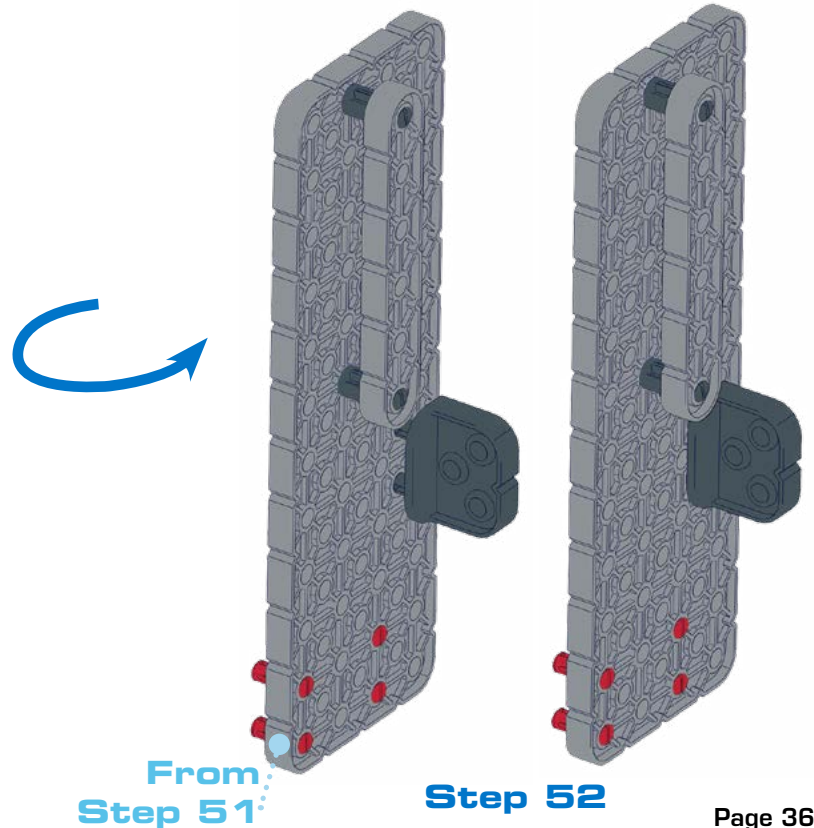
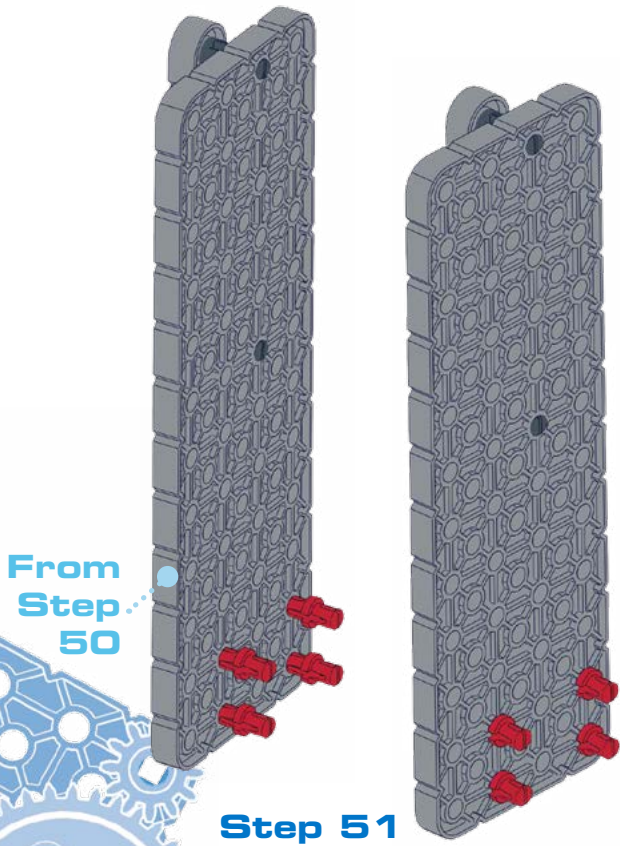
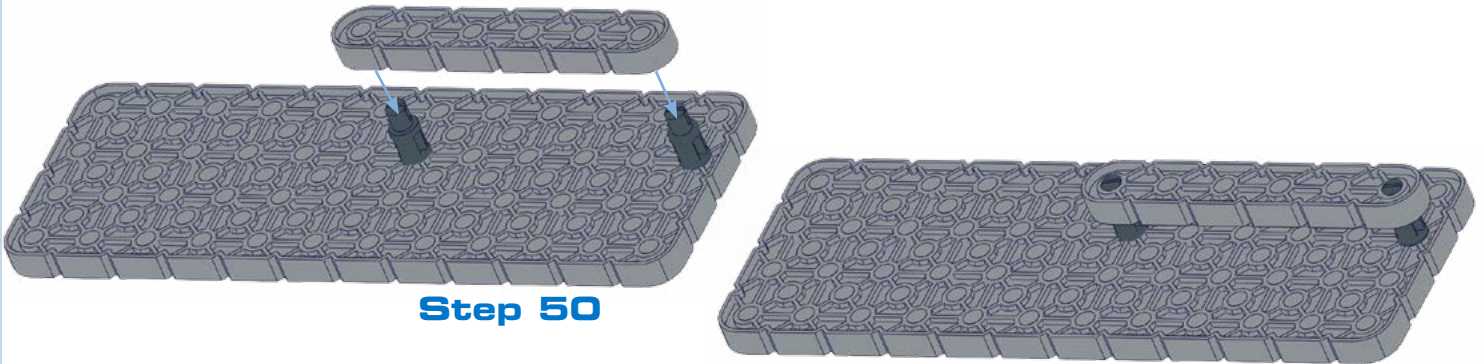
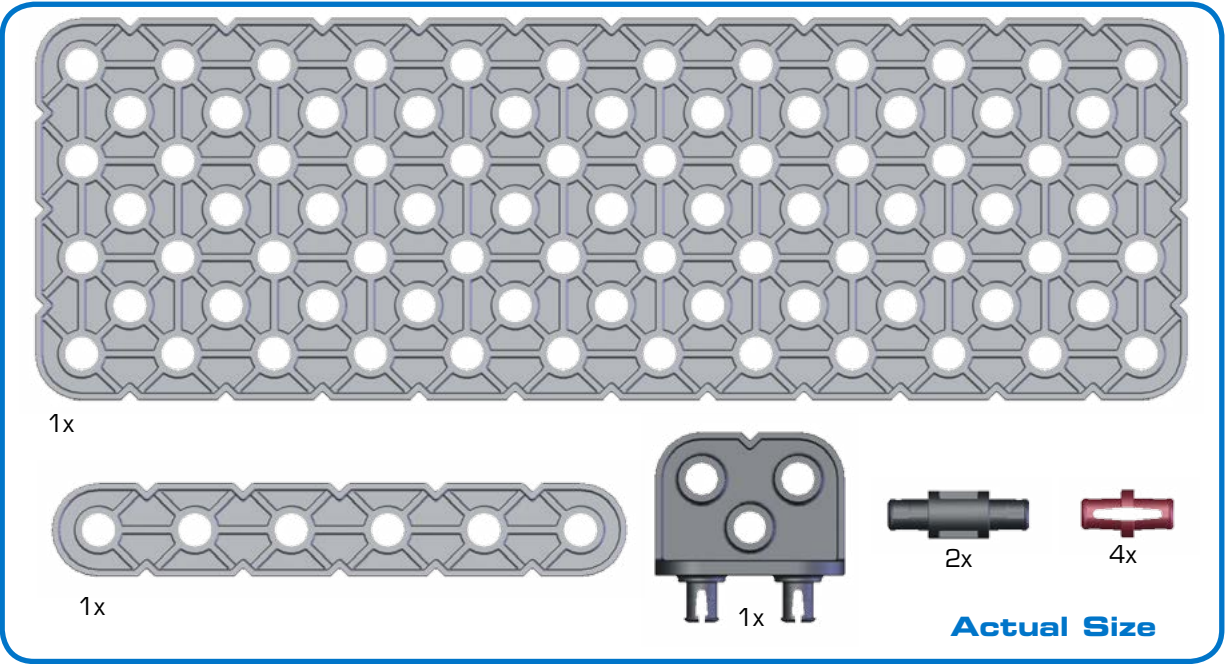
From Step 45

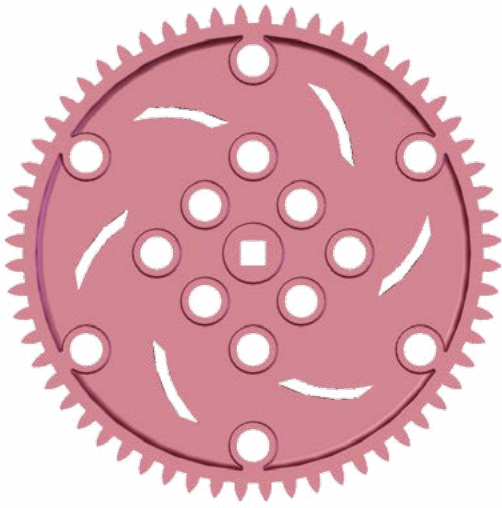


Step 46

Part 3 Tower







1x

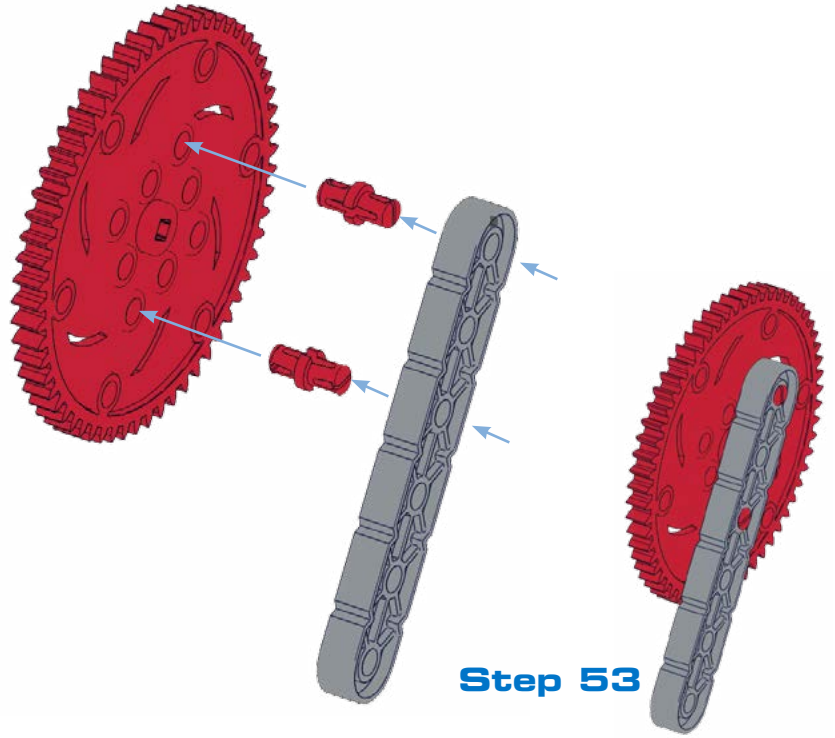


2x



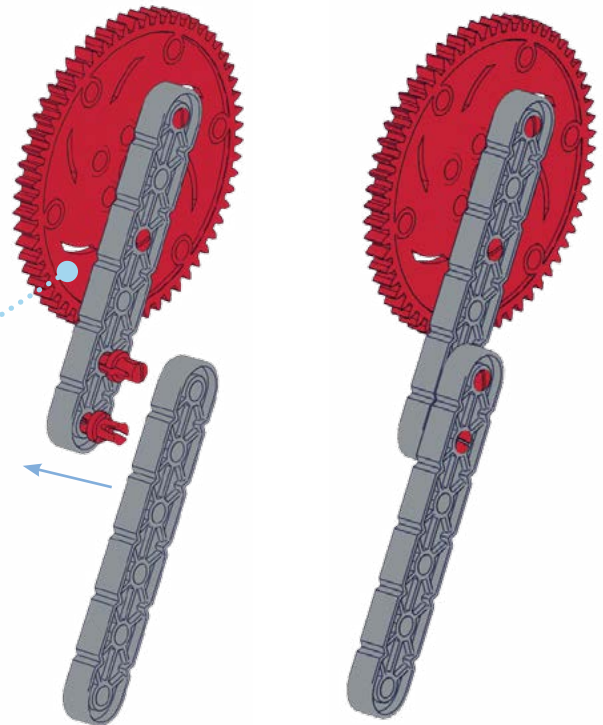
4x

Actual Size

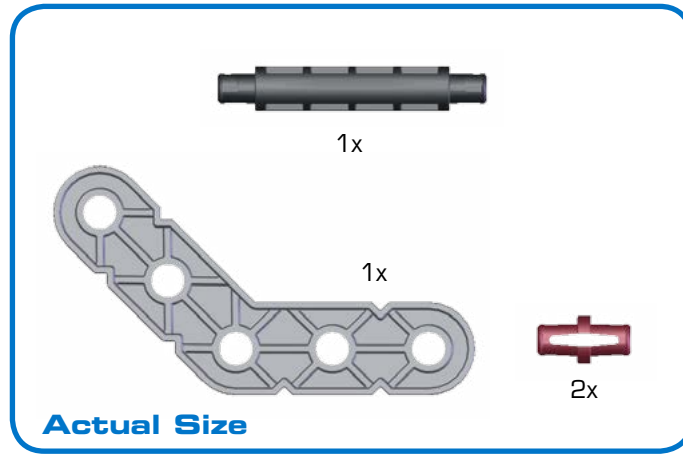


Step 53

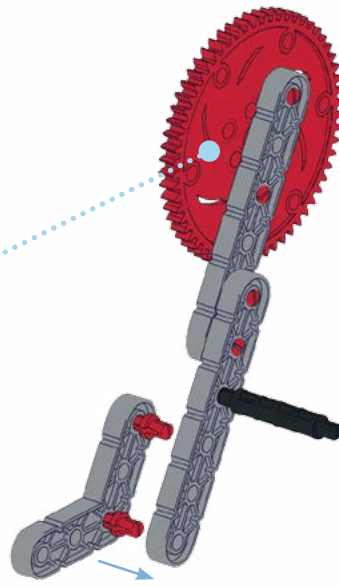
From Step 53



Step 54

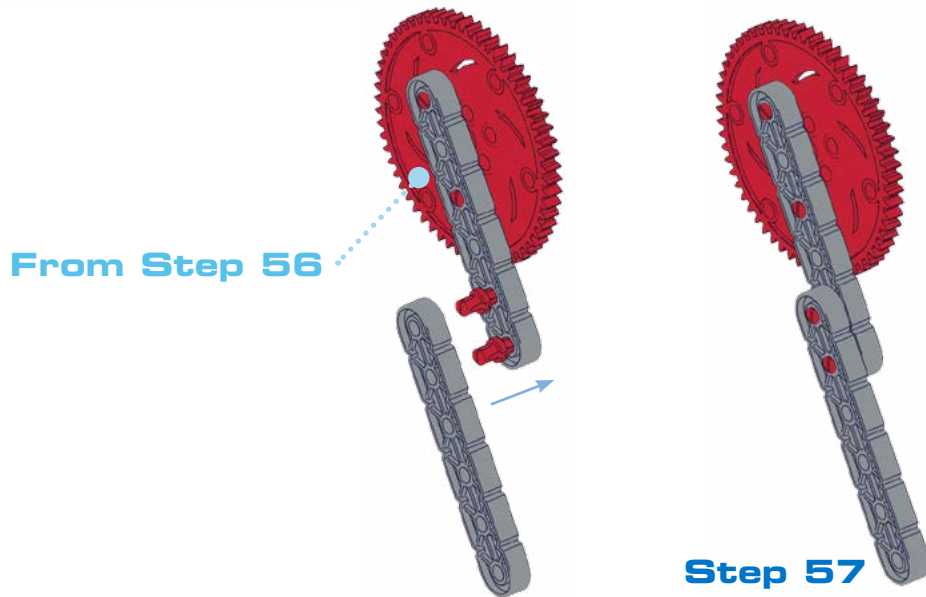
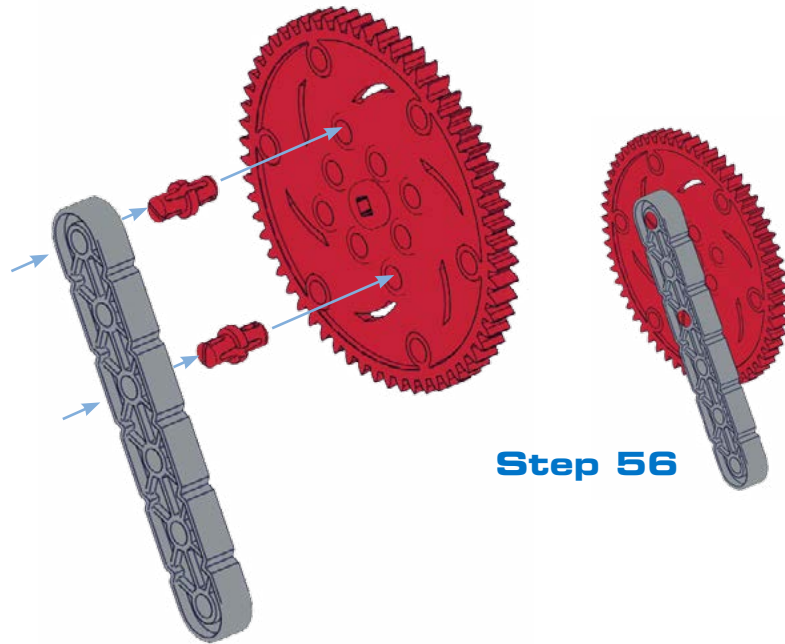
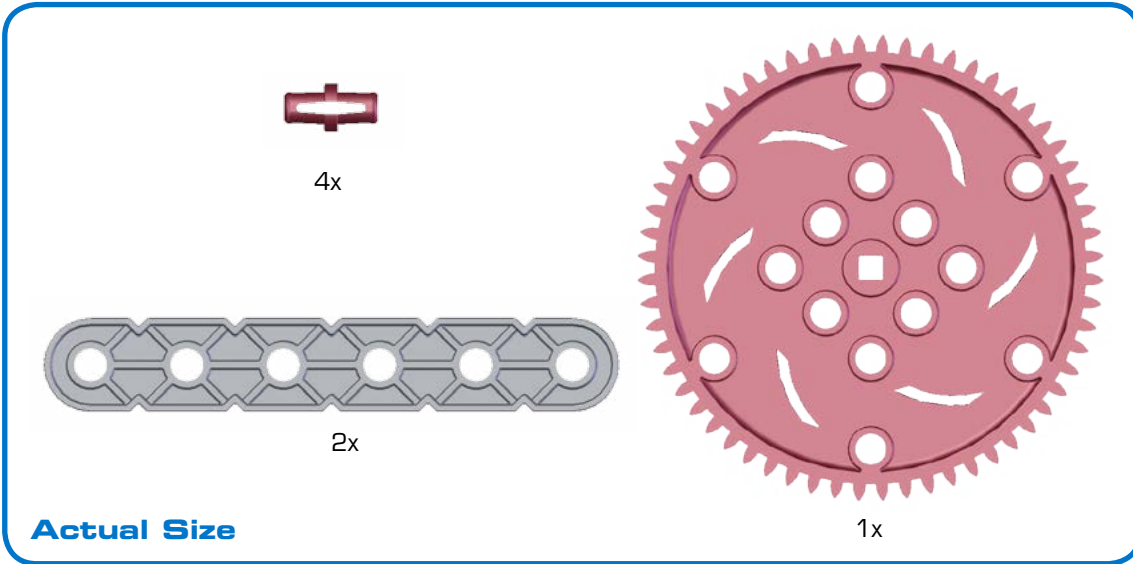


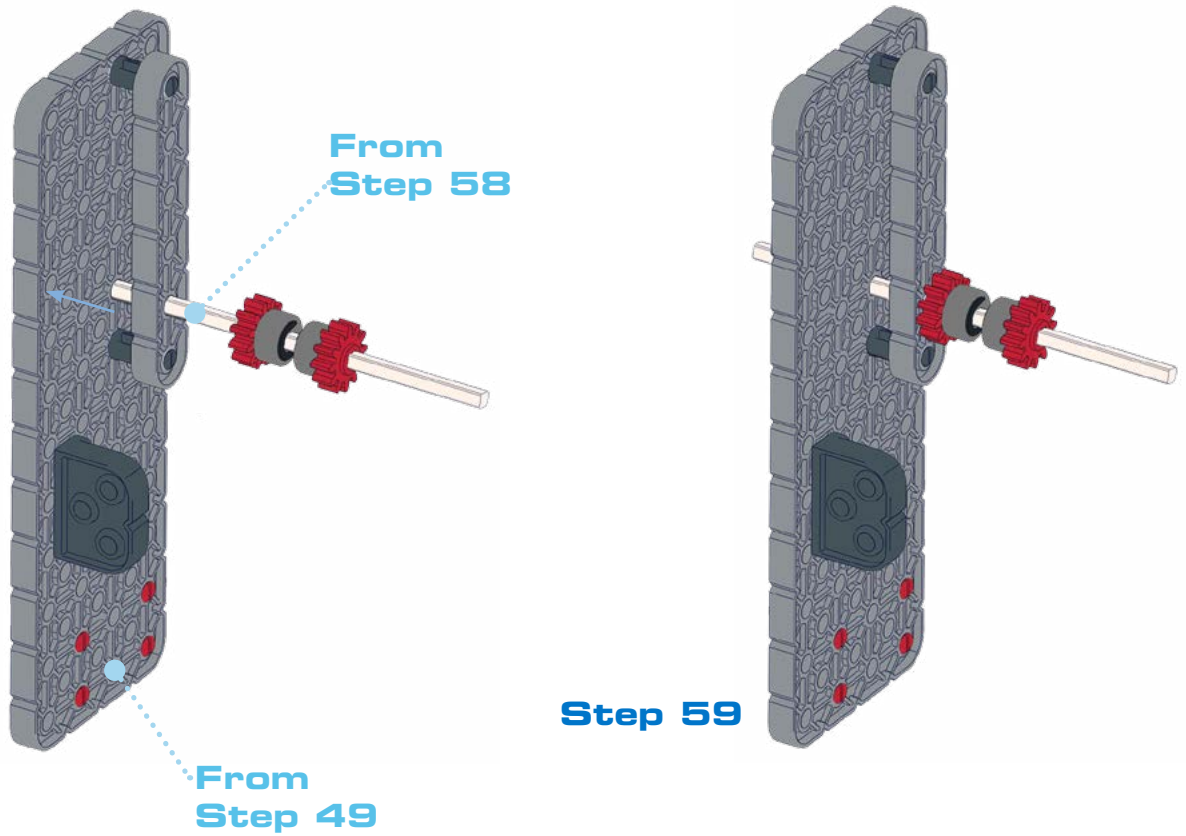
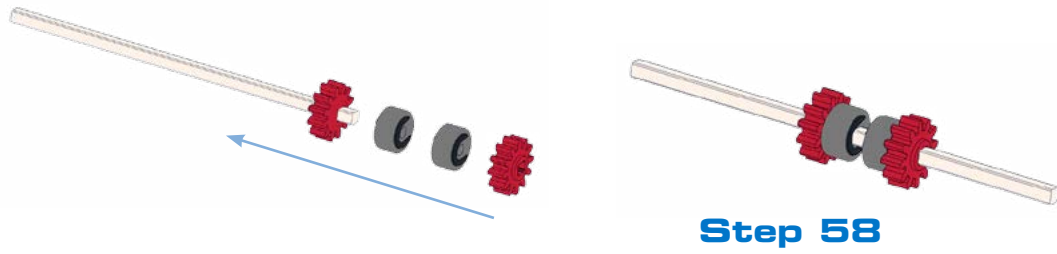
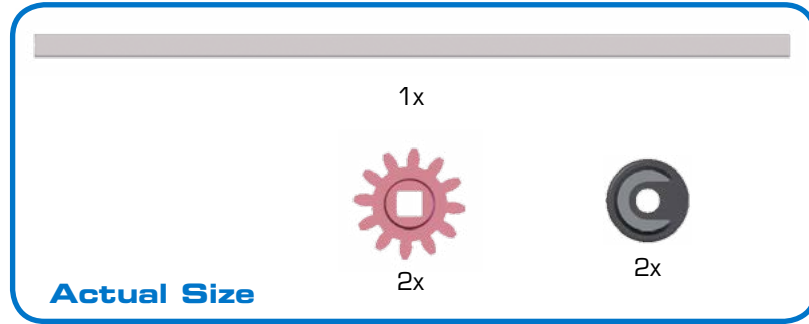
From Step 54



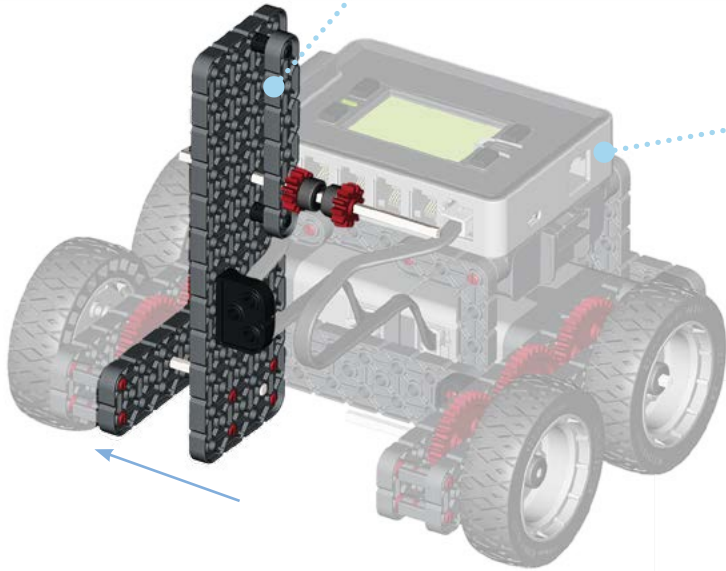
Step 55



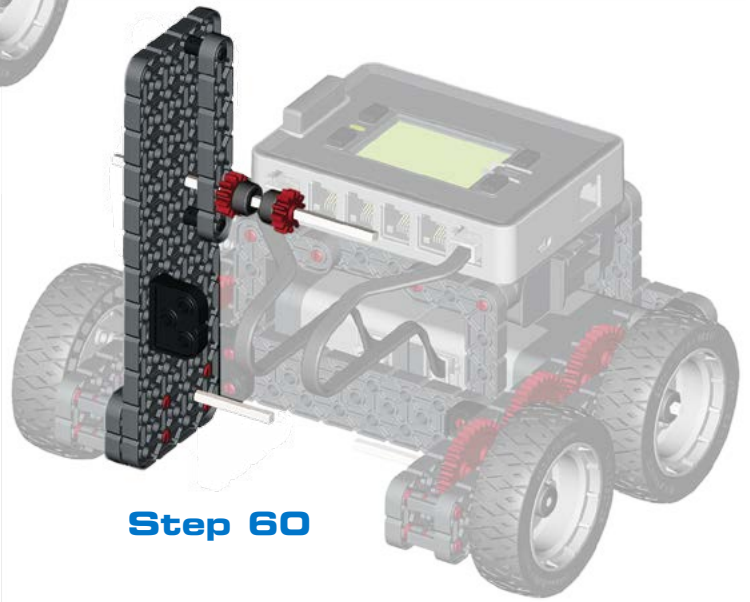




From Step 59

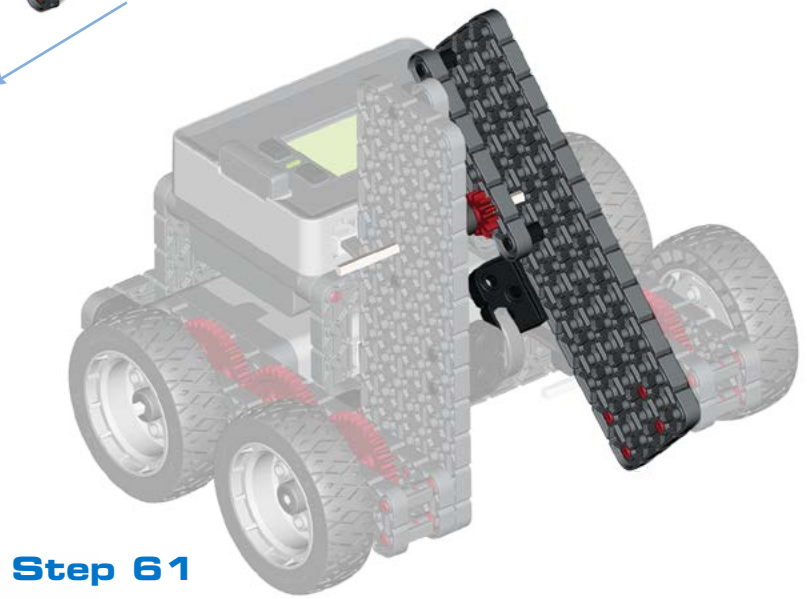
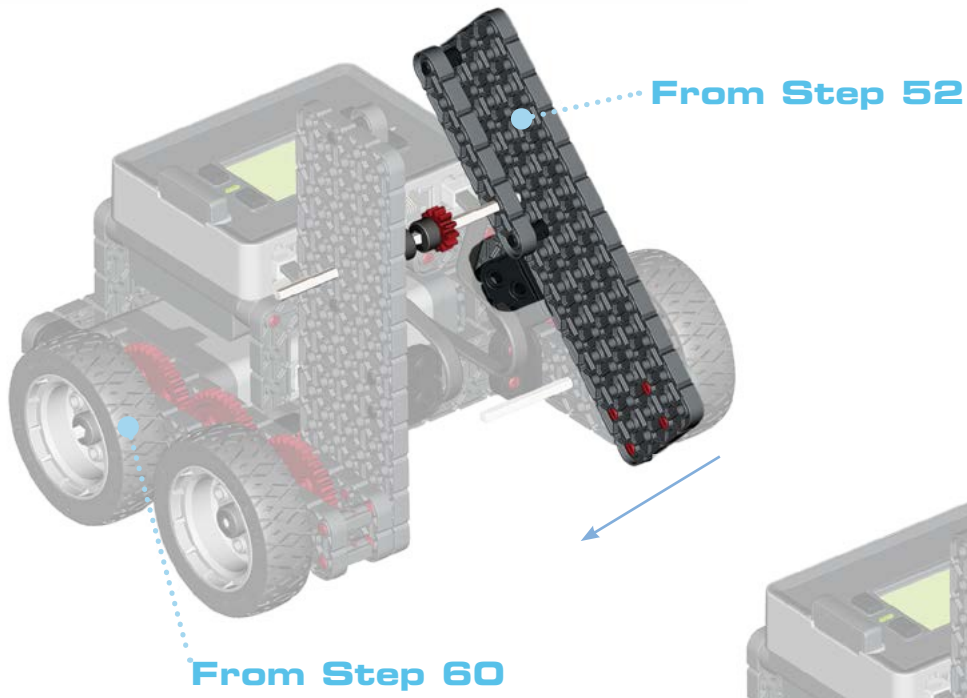


From Step 20

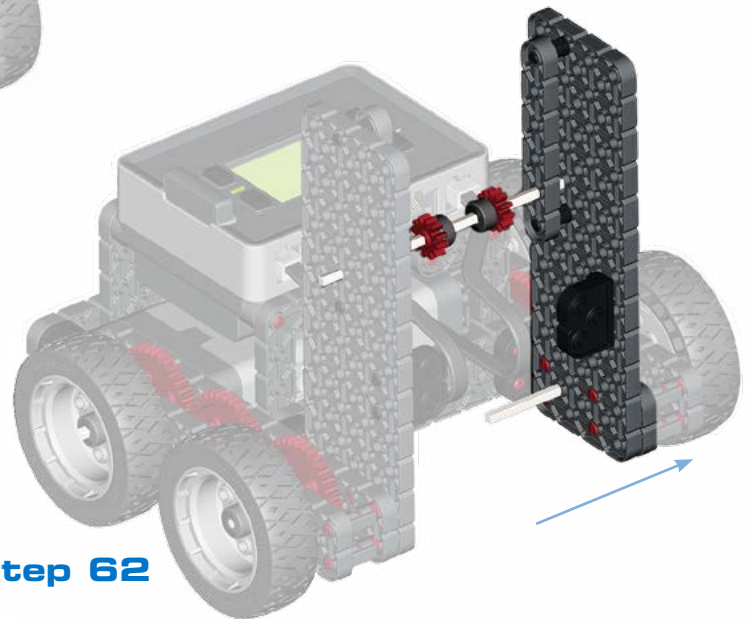
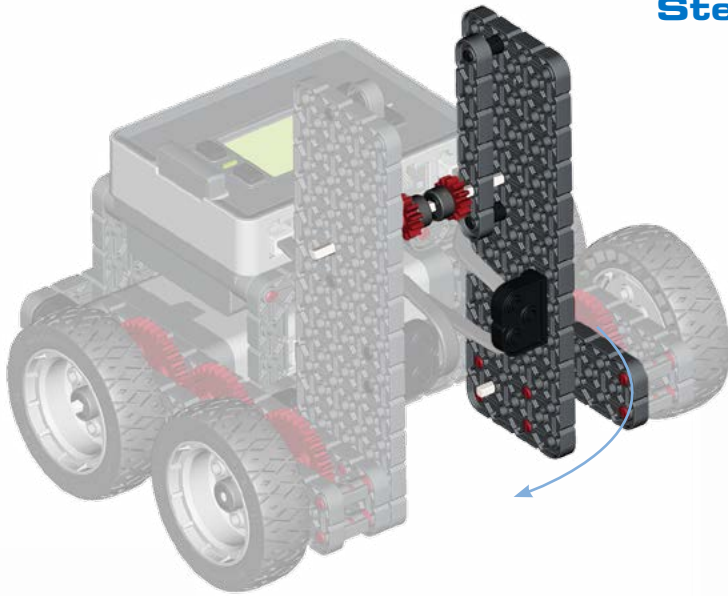


Step 60



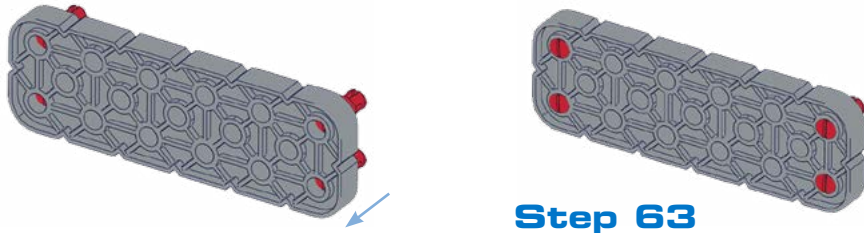
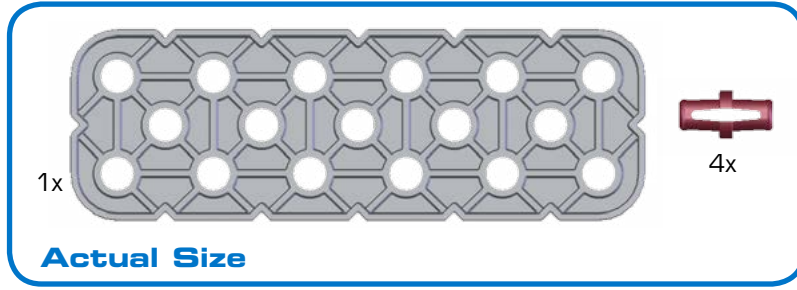


Step 61

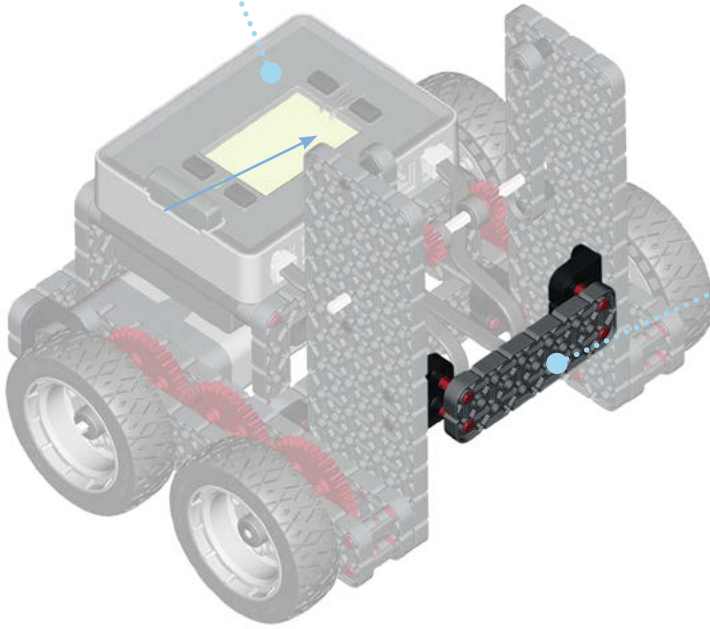


Step 62

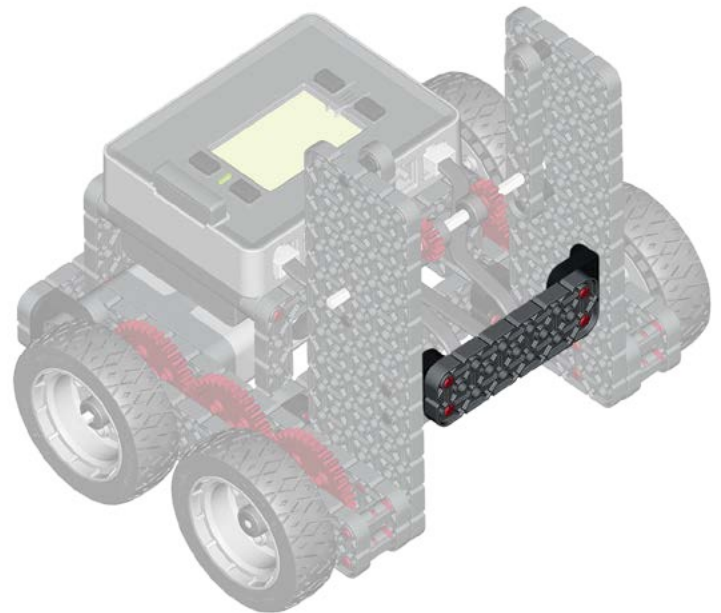




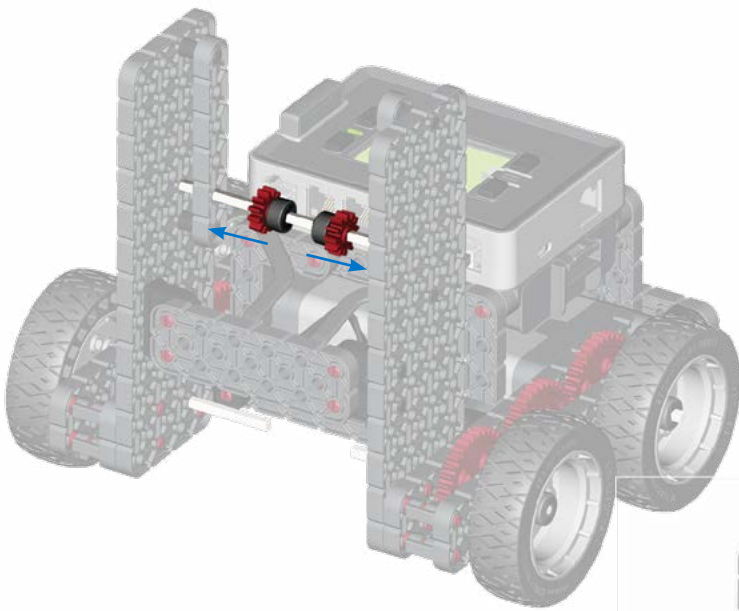
From Step 62



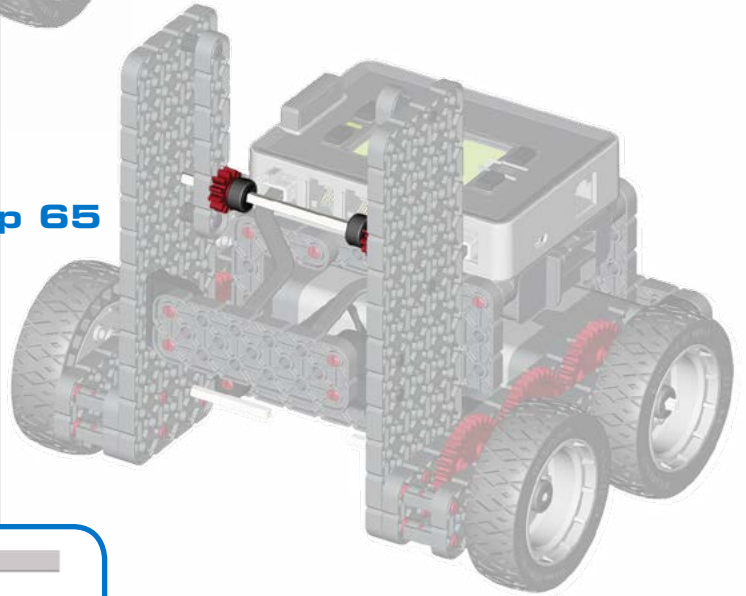
From Step 63



Step 64



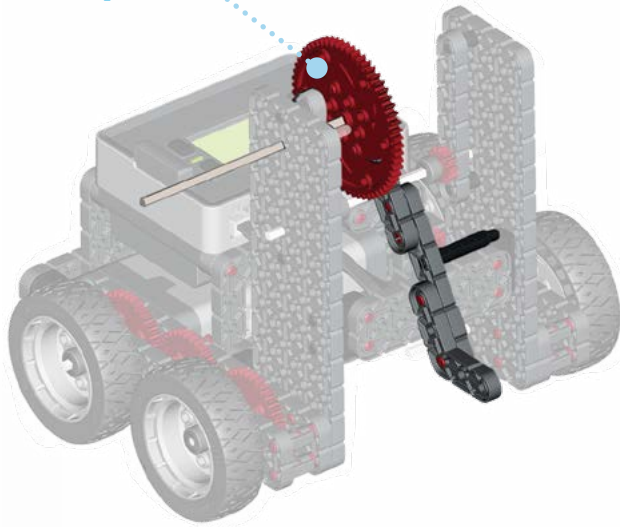
Step 65



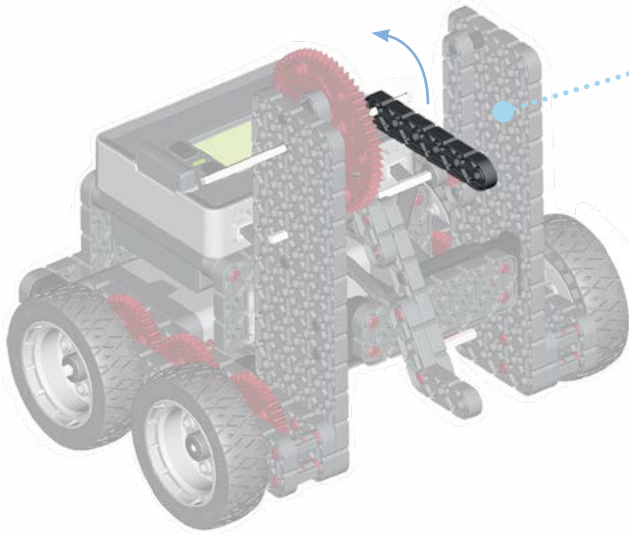
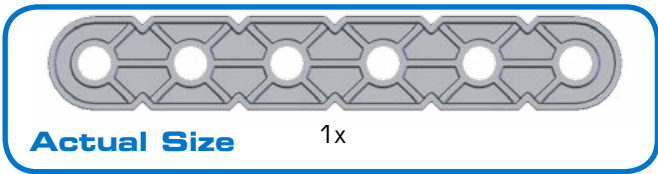
Actual Size

1x

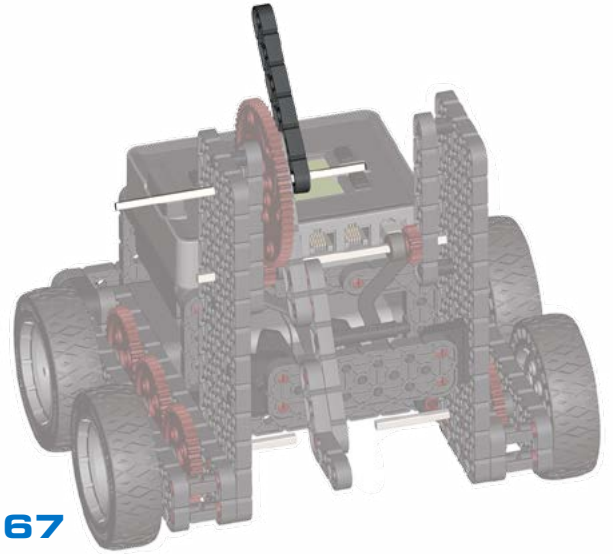
From Step 55



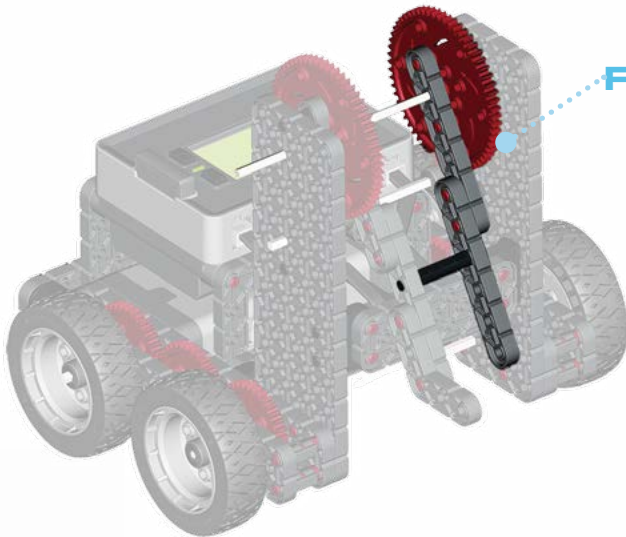
Step 66



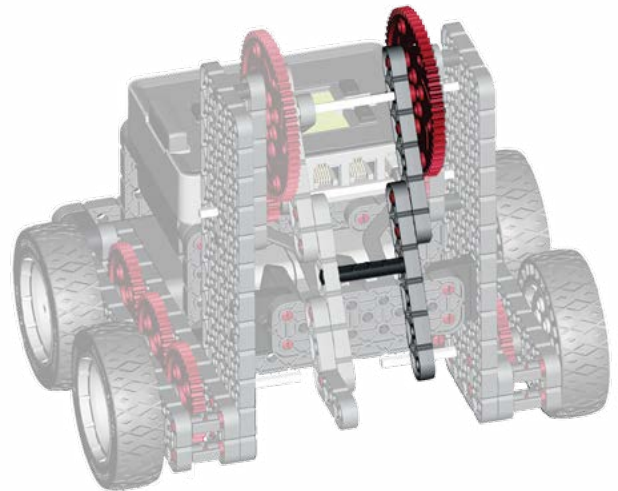
From Step 66



Step 67

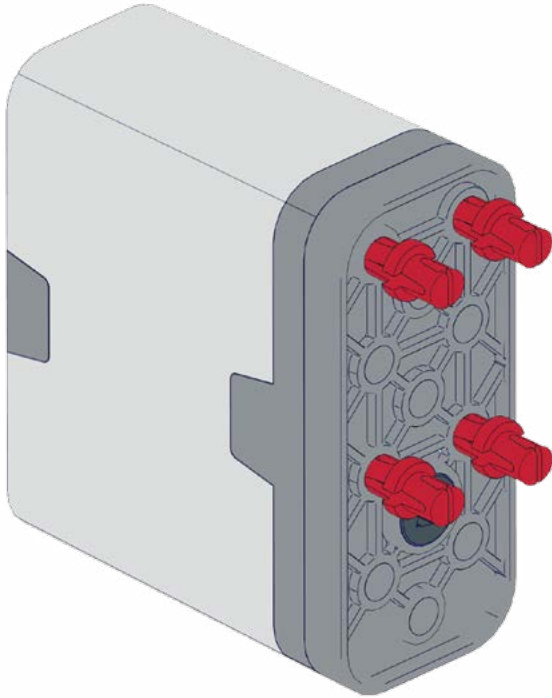
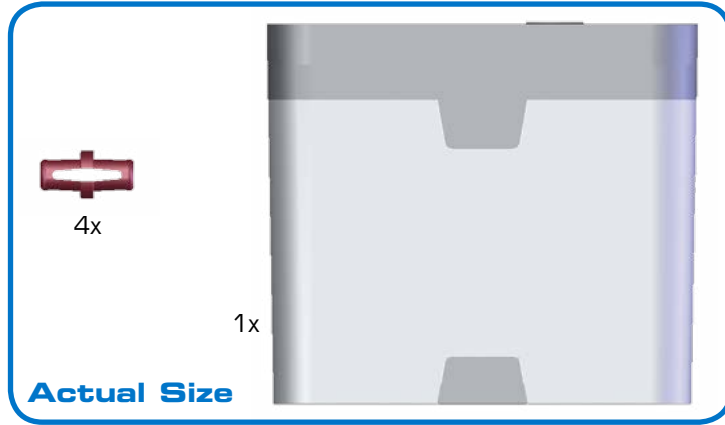


From Step 67

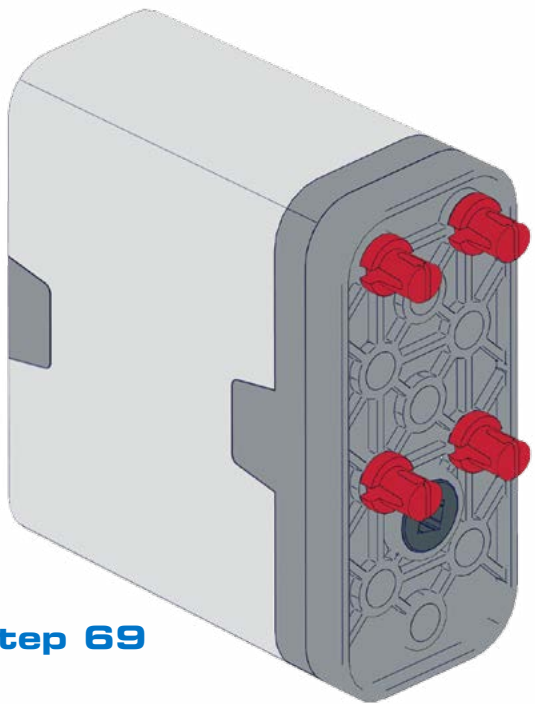


Step 68

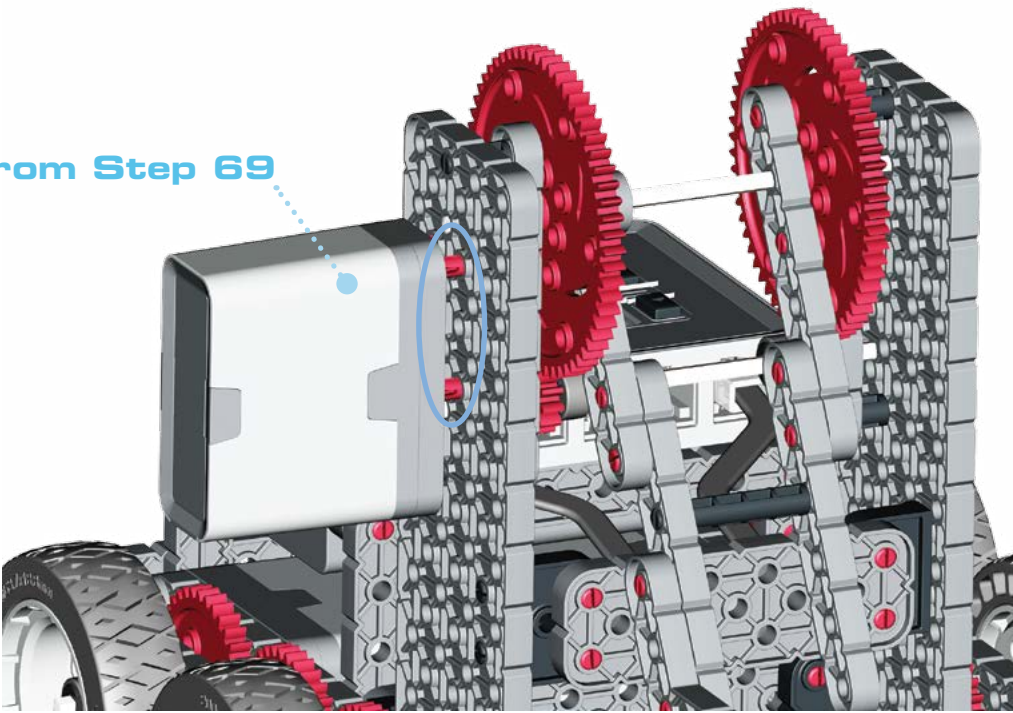




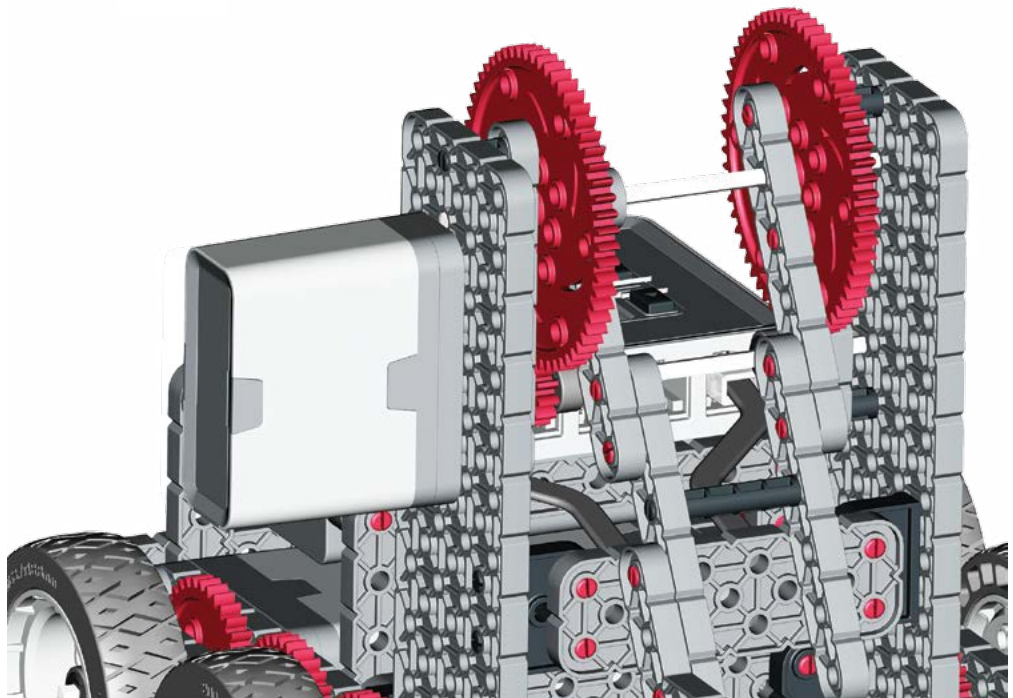
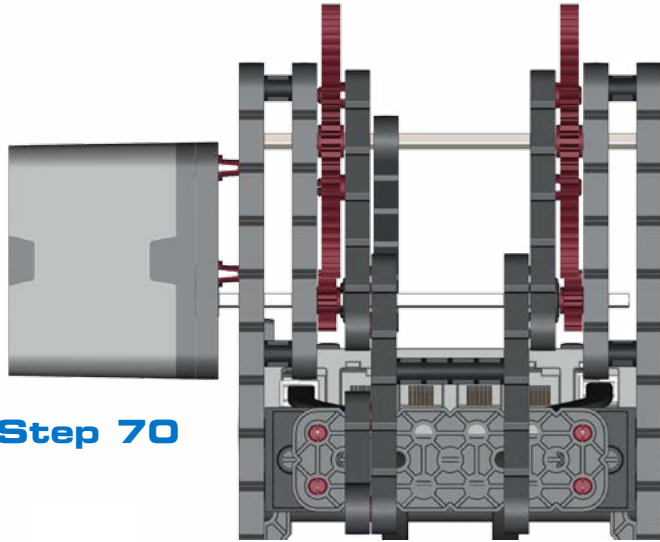
Step 69

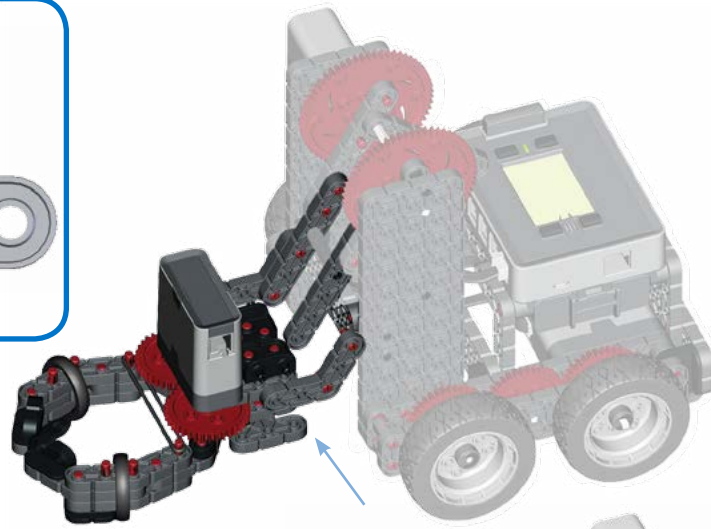
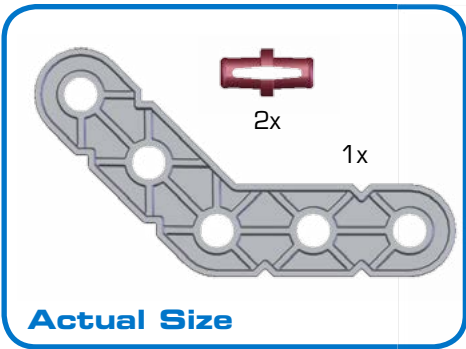


From Step 69

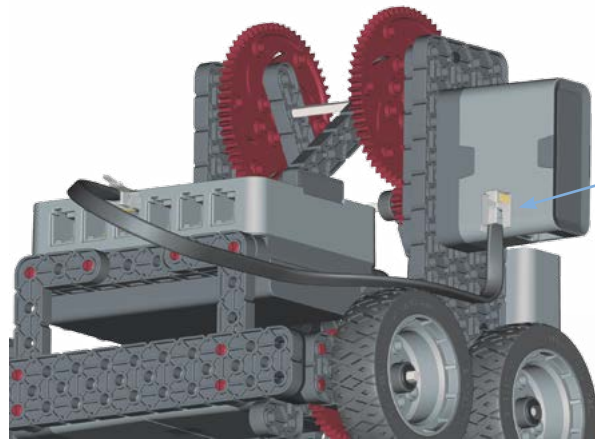
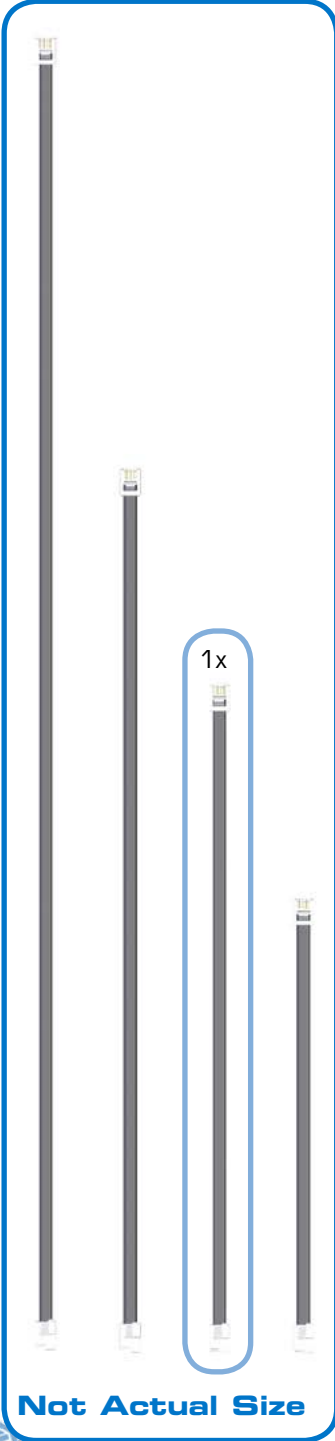


Step 70



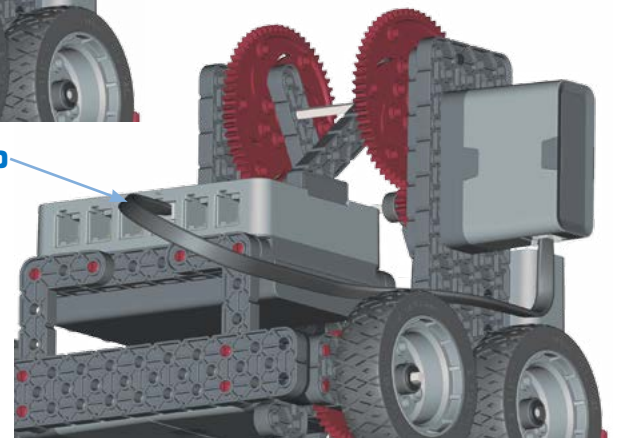
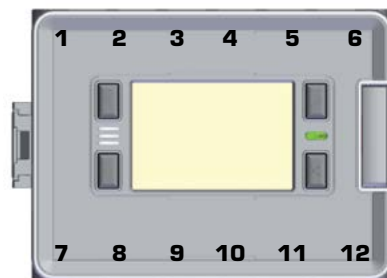


Step 71

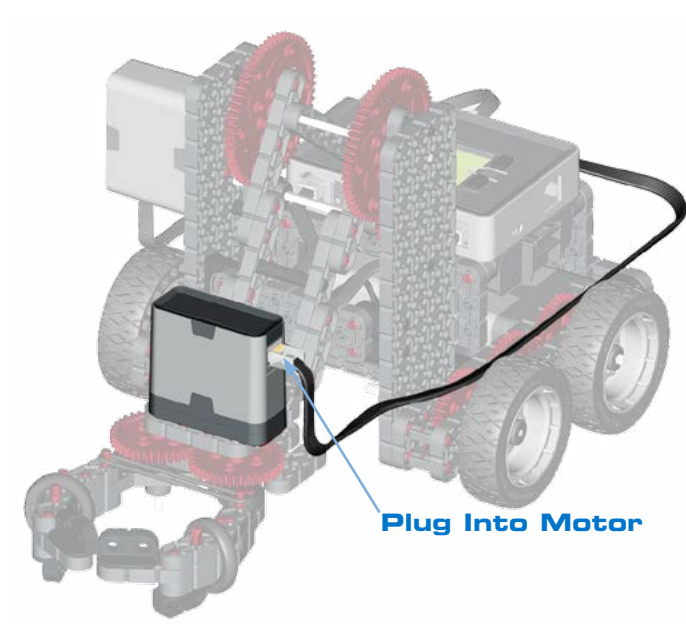
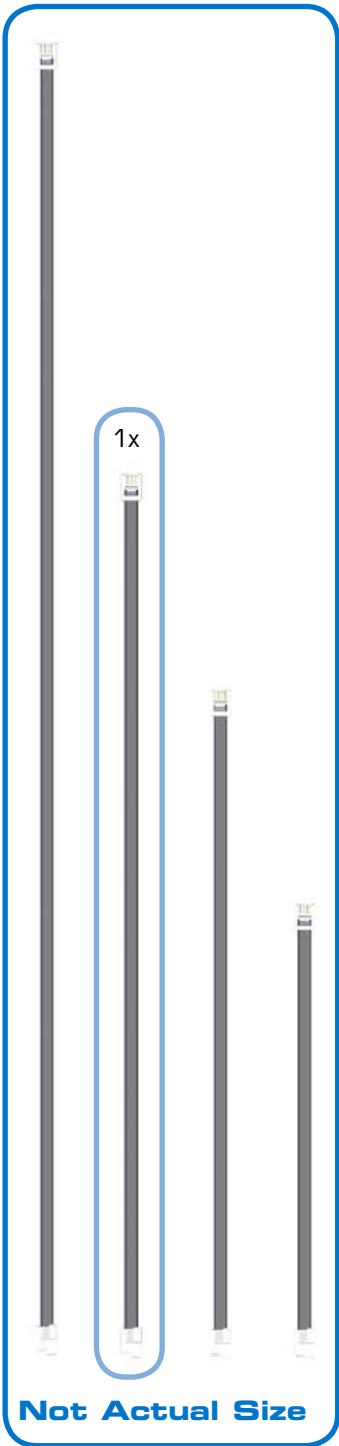


Plug into Motor

Plug Into Port 10

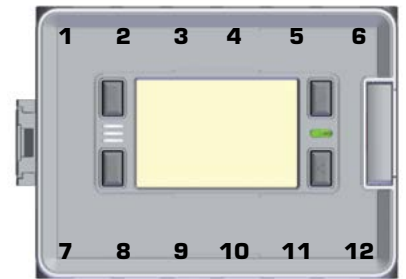
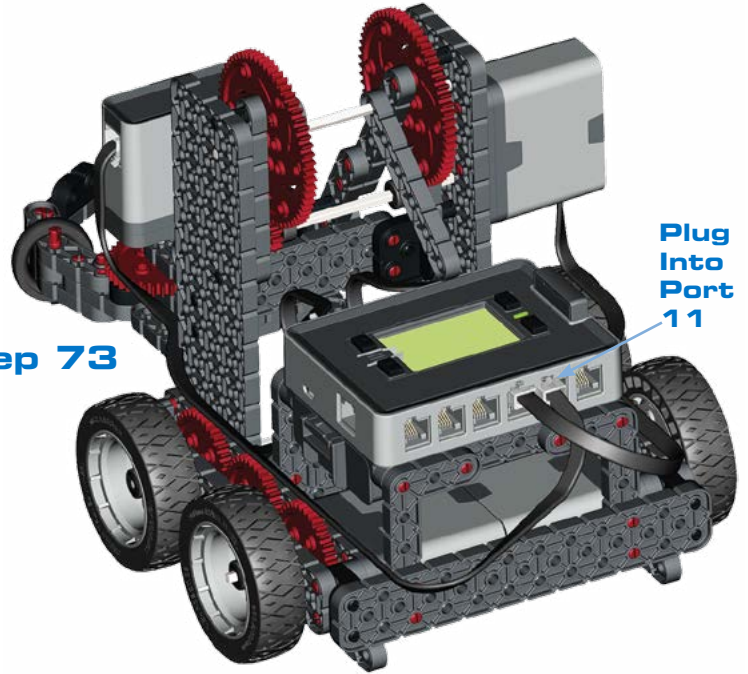
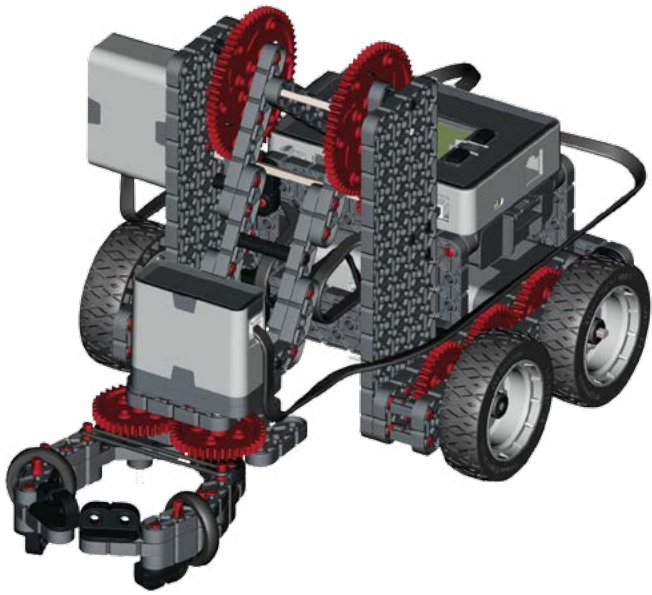


Step 72



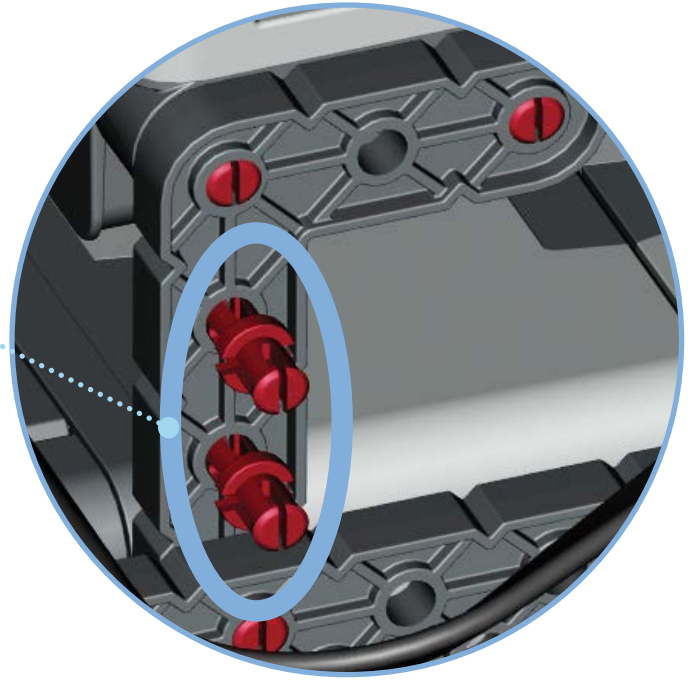
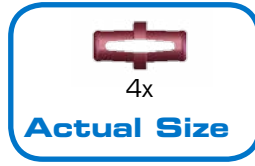
Step 73

Plug Into Port 11



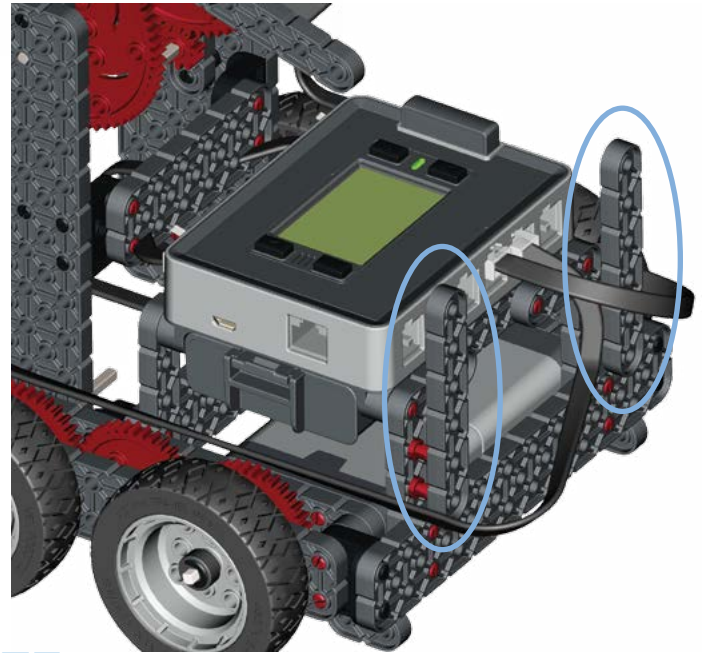
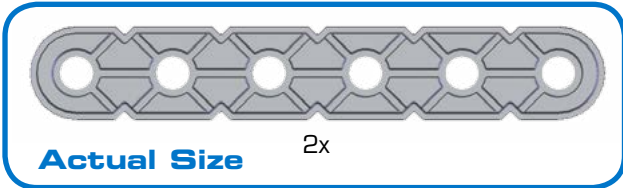
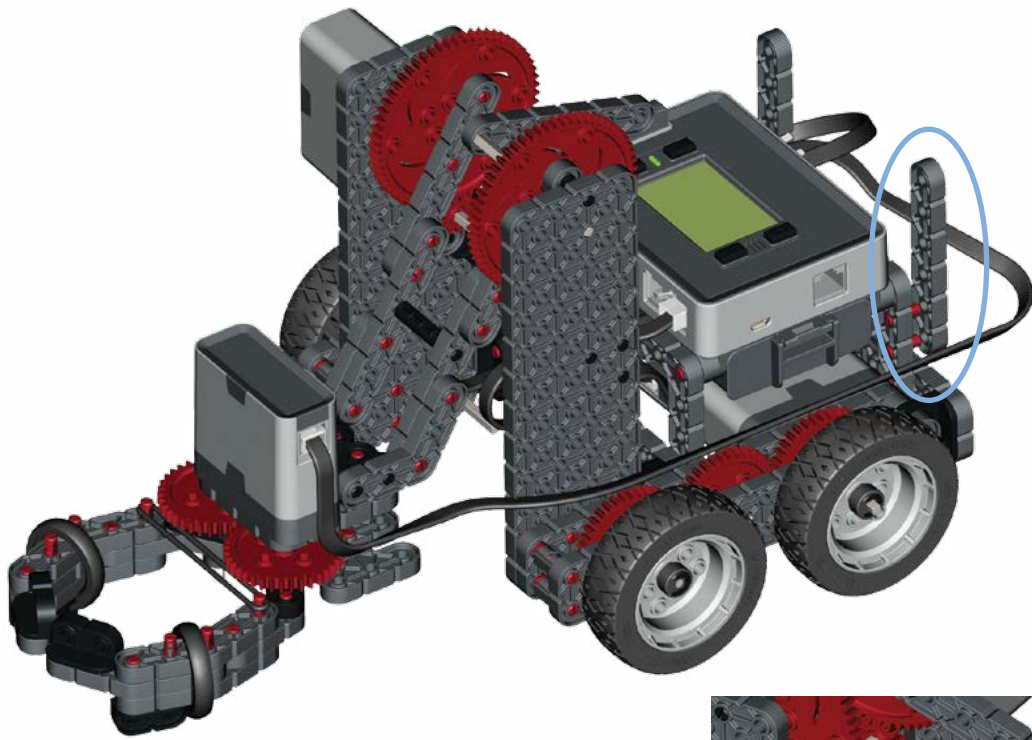
Robot Claw is now Ready to Run!

Part 4 Ball Holder



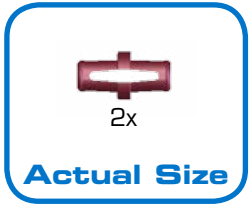
Step 74



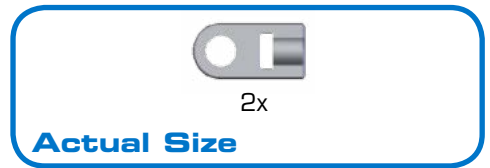
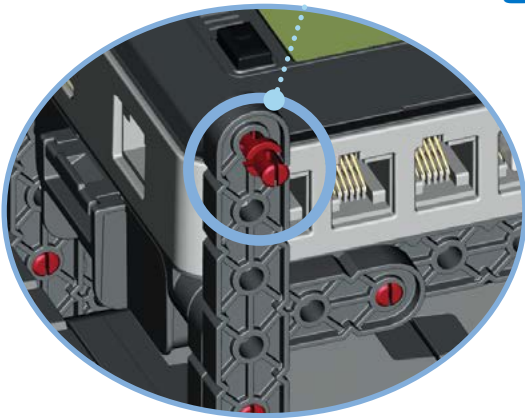


Step 75

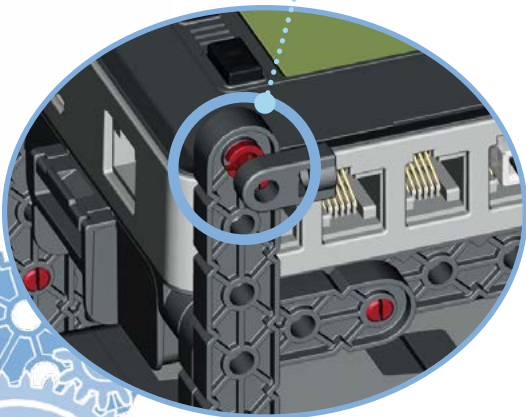


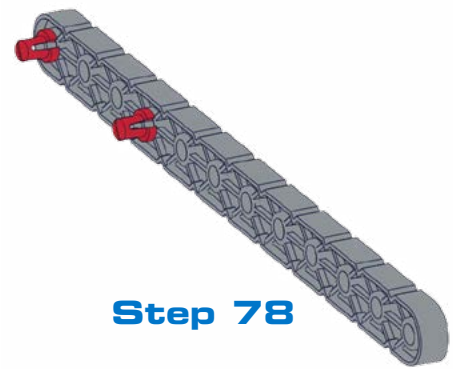
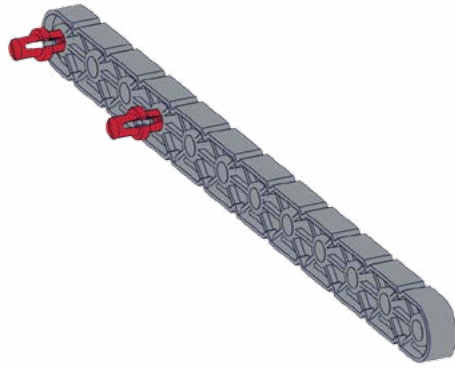
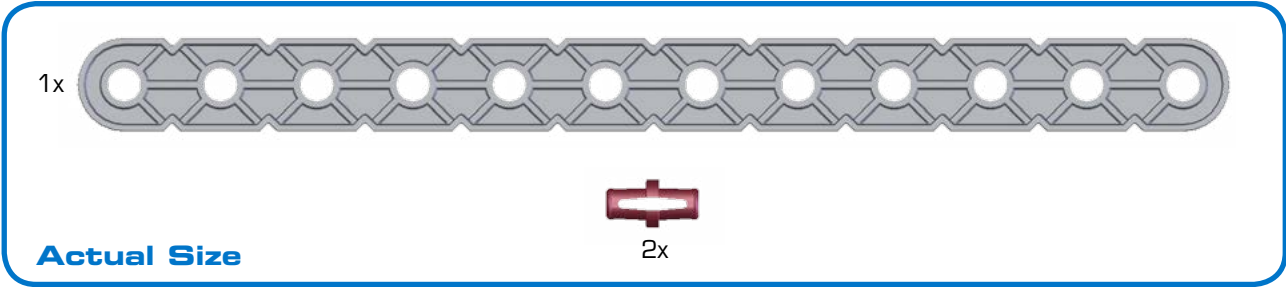


Step 76

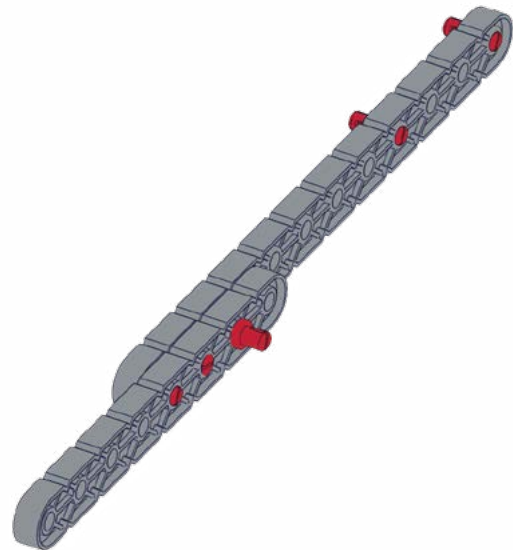
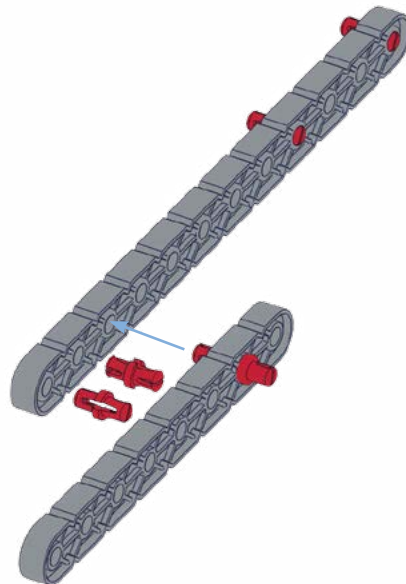
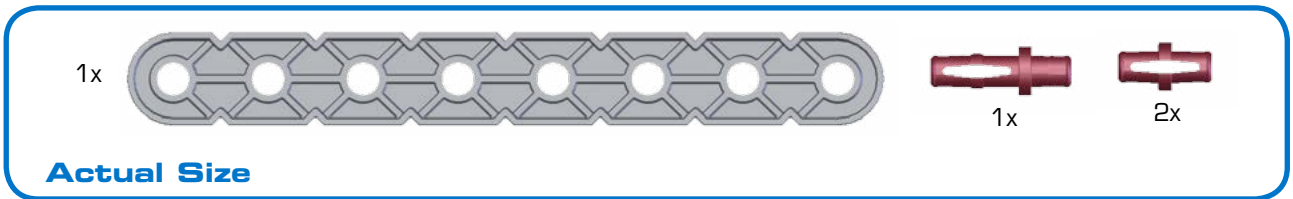


Step 77

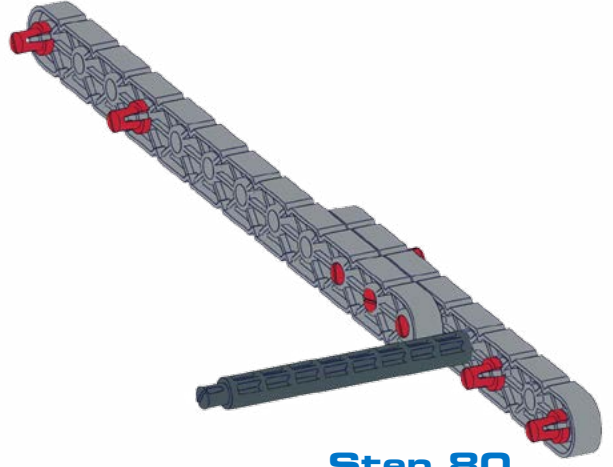
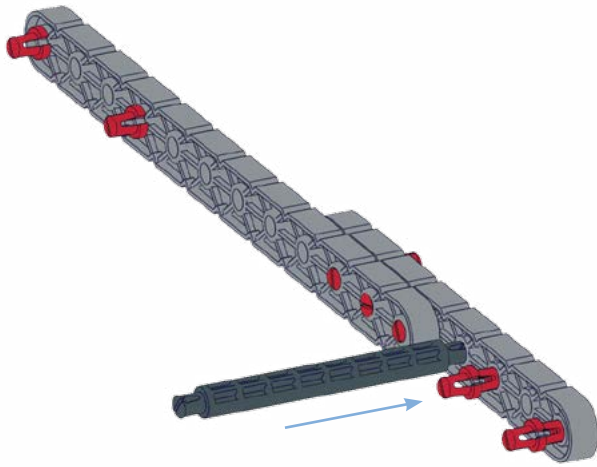




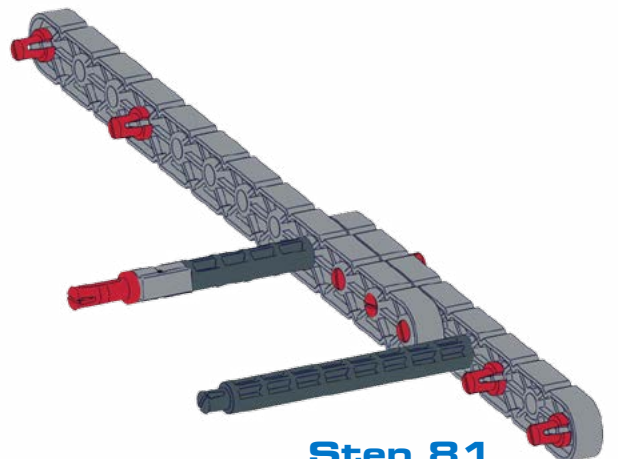
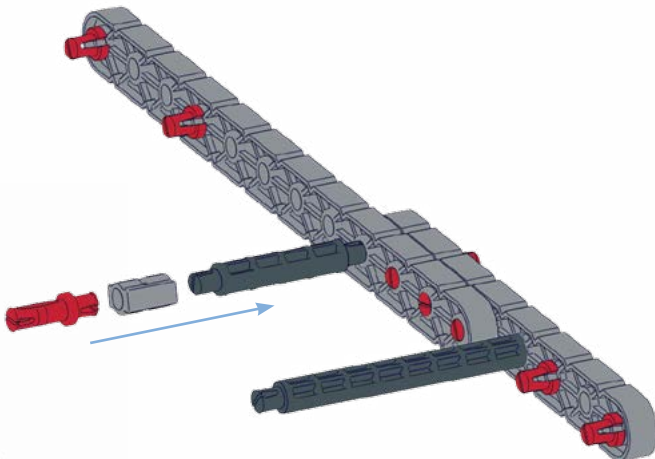
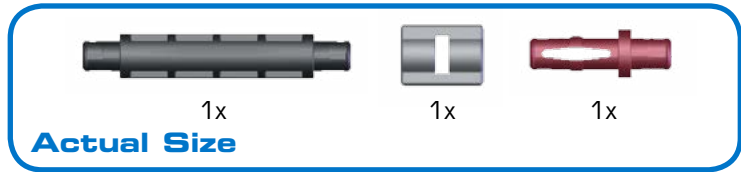
Step 78



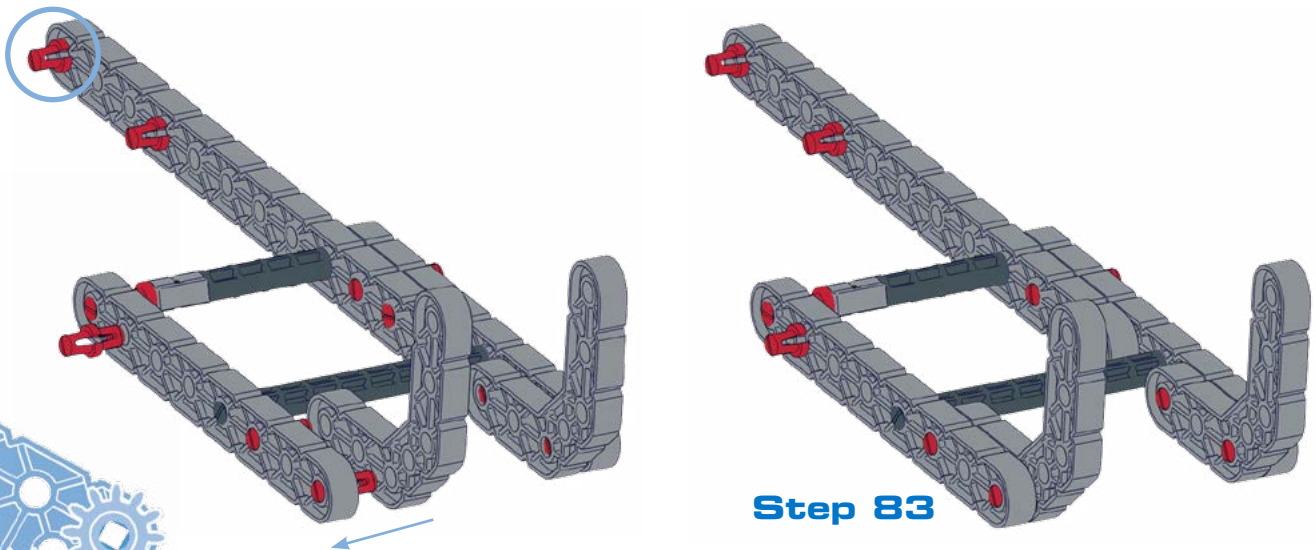
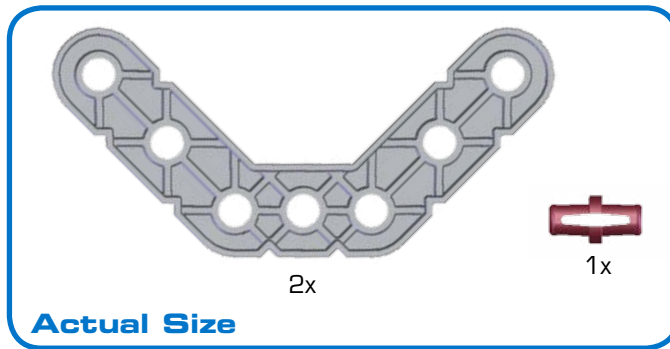
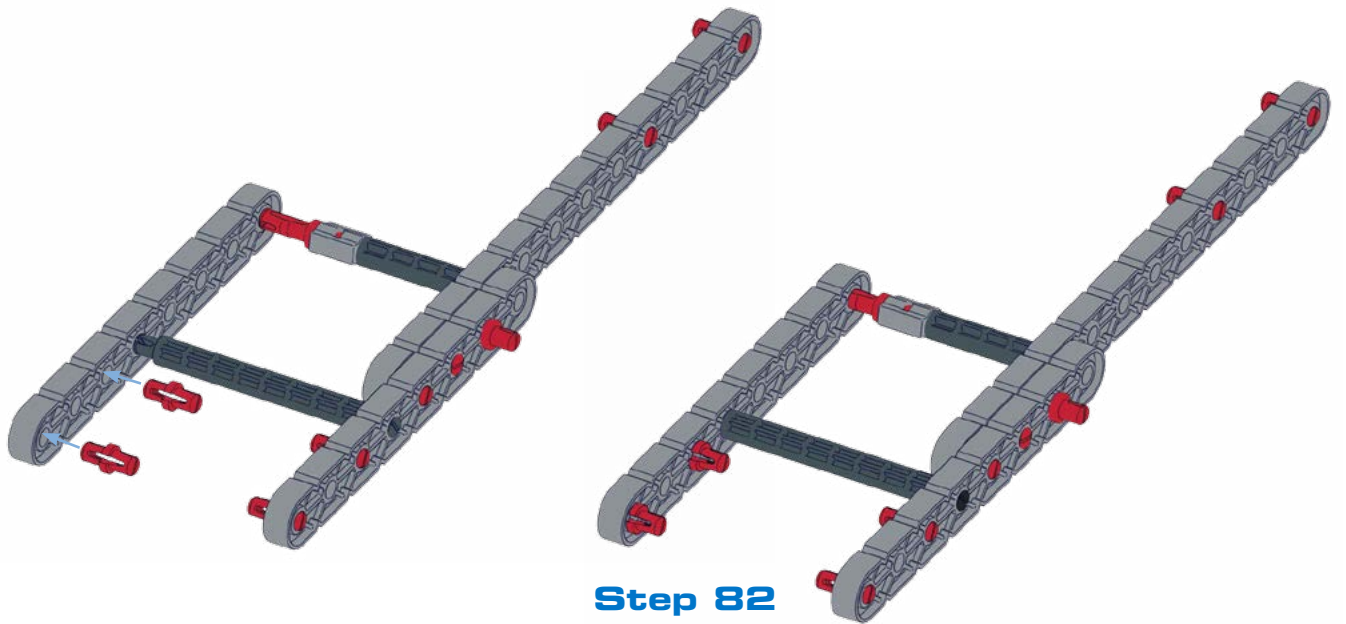
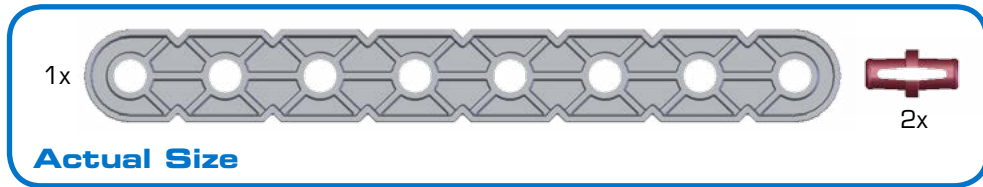
Step 79

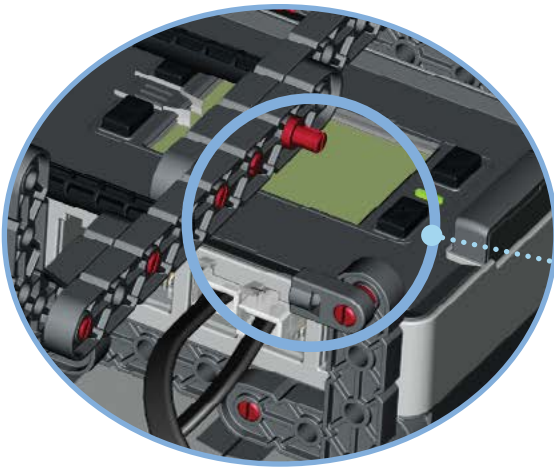
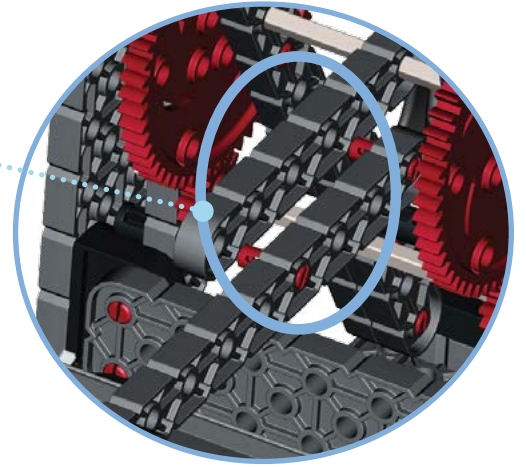
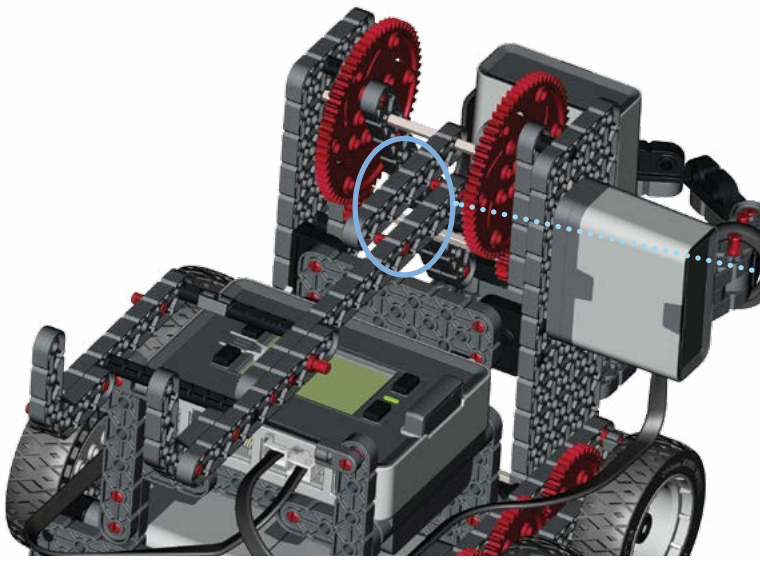


Step 80

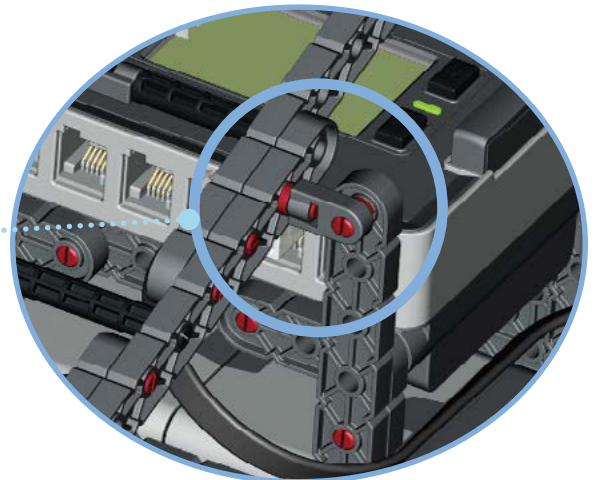


Step 81

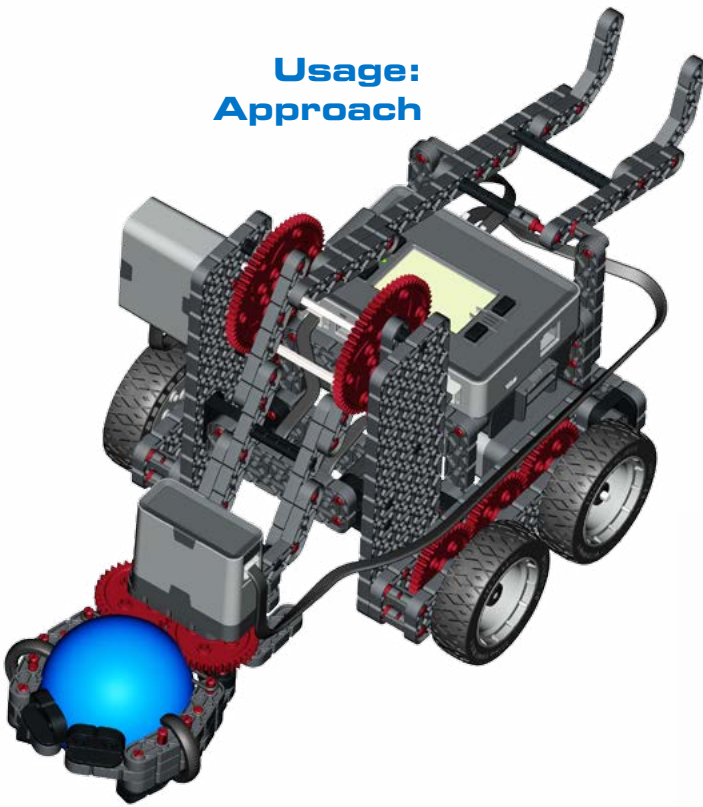




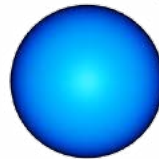
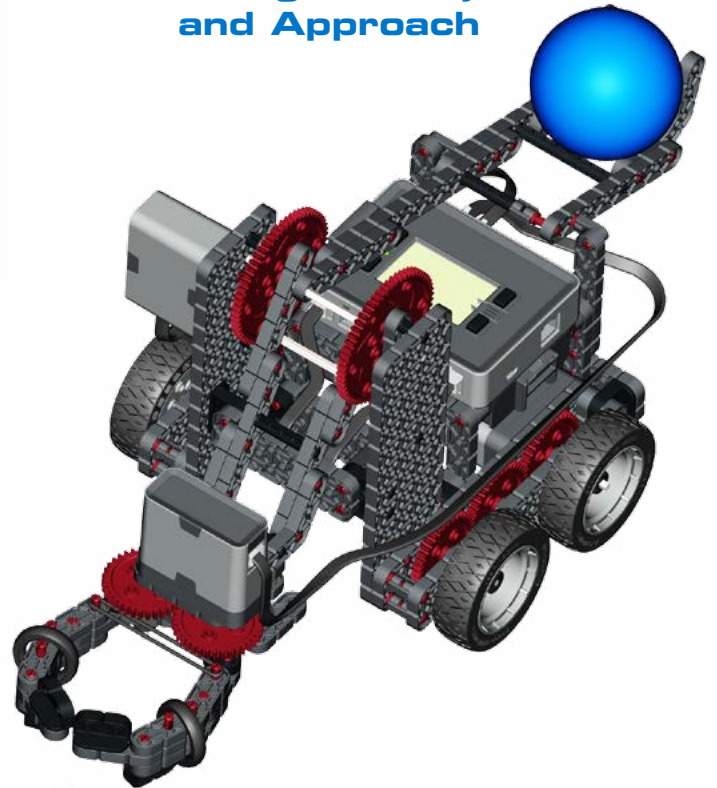
Step 84



Usage: Approach



Usage: Carry and Approach



Usage: Storage

